



RELIANCE PAPI, Precision Approach Path Indicator
L-880(L)/PAPI and L-881(L)/APAPI

User Manual

DM00012-000-01, Rev. J, 2024/07/25



A.0 Disclaimer / Standard Warranty

CE certification

The equipment listed as CE certified means that the product complies with the essential requirements concerning safety and hygiene. The European directives that have been taken into consideration in the design are available on written request to ADB SAFEGATE.

ETL certification

The equipment listed as ETL certified means that the product complies with the essential requirements concerning safety and C22.2 No.180:13 (R2018) regulations. The CSA directives that have been taken into consideration in the design are available on written request to ADB SAFEGATE.

All Products Guarantee

ADB SAFEGATE will correct by repair or replacement per the applicable guarantee below, at its option, equipment or parts which fail because of mechanical, electrical or physical defects, provided that the goods have been properly handled and stored prior to installation, properly installed and properly operated after installation, and provided further that Buyer gives ADB SAFEGATE written notice of such defects after delivery of the goods to Buyer. Refer to the Safety section for more information on Material Handling Precautions and Storage precautions that must be followed.

ADB SAFEGATE reserves the right to examine goods upon which a claim is made. Said goods must be presented in the same condition as when the defect therein was discovered. ADB SAFEGATE further reserves the right to require the return of such goods to establish any claim.

ADB SAFEGATE's obligation under this guarantee is limited to making repair or replacement within a reasonable time after receipt of such written notice and does not include any other costs such as the cost of removal of defective part, installation of repaired product, labor or consequential damages of any kind, the exclusive remedy being to require such new parts to be furnished.

ADB SAFEGATE's liability under no circumstances will exceed the contract price of goods claimed to be defective. Any returns under this guarantee are to be on a transportation charges prepaid basis. For products not manufactured by, but sold by ADB SAFEGATE, warranty is limited to that extended by the original manufacturer. This is ADB SAFEGATE's sole guarantee and warranty with respect to the goods; there are no express warranties or warranties of fitness for any particular purpose or any implied warranties of fitness for any particular purpose or any implied warranties other than those made expressly herein. All such warranties being expressly disclaimed.

Standard Products Guarantee

Products manufactured by ADB SAFEGATE are guaranteed against mechanical, electrical, and physical defects (excluding lamps) which may occur during proper and normal use for a period of two years from the date of ex-works delivery, and are guaranteed to be merchantable and fit for the ordinary purposes for which such products are made.

Note

See your applicable sales agreement for a complete warranty description.

Replaced or repaired equipment under warranty falls into the warranty of the original delivery. No new warranty period is started for these replaced or repaired products.

FAA Certified products manufactured by ADB SAFEGATE

ADB SAFEGATE L858 Airfield Guidance Signs are warranted against mechanical and physical defects in design or manufacture for a period of 2 years from date of installation, per FAA AC 150/5345-44 (applicable edition).

ADB SAFEGATE LED products (with the exception of obstruction lighting) are warranted against electrical defects in design or manufacture of the LED or LED specific circuitry for a period of 4 years from date of installation, per FAA EB67 (applicable edition). These FAA certified constant current (series) powered LED products must be installed, interfaced and powered with and through products certified under the FAA Airfield Lighting Equipment Program (ALECP) to be included in this 4 (four) year warranty. This includes, but is not limited to, interface with products such as Base Cans, Isolation Transformers, Connectors, Wiring, and Constant Current Regulators.

i Note

See your sales order contract for a complete warranty description.

Replaced or repaired equipment under warranty falls into the warranty of the original delivery. No new warranty period is started for these replaced or repaired products.

Liability



WARNING

Use of the equipment in ways other than described in the catalog leaflet and the manual may result in personal injury, death, or property and equipment damage. Use this equipment only as described in the manual.

ADB SAFEGATE cannot be held responsible for injuries or damages resulting from non-standard, unintended uses of its equipment. The equipment is designed and intended only for the purpose described in the manual. Uses not described in the manual are considered unintended uses and may result in serious personal injury, death or property damage.

Unintended uses, includes the following actions:

- Making changes to equipment that have not been recommended or described in this manual or using parts that are not genuine ADB SAFEGATE replacement parts or accessories.
- Failing to make sure that auxiliary equipment complies with approval agency requirements, local codes, and all applicable safety standards if not in contradiction with the general rules.
- Using materials or auxiliary equipment that are inappropriate or incompatible with your ADB SAFEGATE equipment.
- Allowing unskilled personnel to perform any task on or with the equipment.

Copyright Statement

This manual or parts thereof may not be reproduced, stored in a retrieval system, or transmitted, in any form or by any means, electronic, mechanical, photocopying, recording, nor otherwise, without the author's prior written consent.

This manual could contain technical inaccuracies or typographical errors. The author reserves the right to revise this manual from time to time in the contents thereof without obligation of the author to notify any person of such revision or change. Details and values given in this manual are average values and have been compiled with care. They are not binding, however, and the author disclaims any liability for damages or detriments suffered as a result of reliance on the information given herein or the use of products, processes or equipment to which this manual refers. No warranty is made that the use of the information or of the products, processes or equipment to which this manual refers will not infringe any third party's patents or rights. The information given does not release the buyer from making their own experiments and tests.

TABLE OF CONTENTS

1.0 Safety	1
1.1 Safety Messages	1
1.1.1 Introduction to Safety	2
1.1.2 Intended Use	2
1.1.3 Material Handling Precautions: Storage	3
1.1.4 Operation Safety	3
1.1.5 Maintenance Safety	3
1.1.6 Material Handling Precautions, ESD	4
2.0 About this manual	5
2.1 How to work with the manual	5
3.0 RELIANCE PAPI Overview	7
3.1 LED PAPI	7
3.2 Signal Display	9
3.2.1 Type L-880(L) PAPI (4 Light Unit) System	9
3.2.2 Type L-881(L) APAPI (2 Light Unit) System	10
3.3 RELIANCE PAPI Light Unit	11
3.4 Operation Overview - Voltage Powered Systems	12
3.4.1 Primary Enclosure	12
3.4.2 Local/Remote Operation	12
3.4.3 Daytime Operation	12
3.4.4 Nighttime Operation	12
3.4.5 Output to LED Light Assembly	12
3.4.6 Optional Interlock Relay	12
3.5 Operation Overview - Current Powered Systems	13
3.5.1 Style B Series Circuit Current Powered	13
3.6 Operation Overview - RELIANCE PAPI Light Unit	13
3.6.1 RELIANCE PAPI Control Board Overview	14
3.6.2 RELIANCE PAPI Display Board Overview	18
3.6.3 Inclinometer Overview	18
4.0 Siting the RELIANCE PAPI System	19
4.1 Siting Considerations	19
4.1.1 Distance of the PAPI from the Runway Edge	19
4.1.2 Lateral Spacing of the PAPI Light Units	19
4.2 Siting a PAPI with an FAA ILS Glideslope	19
4.3 Siting a PAPI Without an FAA ILS Glideslope	20
4.3.1 Threshold Crossing Height (TCH)	21
4.3.2 Glideslope Angle	21
4.3.3 Obstacle Clearance Surface	21
4.3.4 Reduction of Beam Coverage for Obstacle Avoidance	22
4.4 Siting Tolerances	22
4.4.1 Azimuth Aiming (Horizontal Alignment with Runway Centerline)	22
4.4.2 Mounting Height Tolerance	23
4.4.3 PAPI Tolerance Along Line Perpendicular to Runway	23
4.4.4 Correction for Runway Longitudinal Gradient	24
4.5 Additional Siting Considerations	25
4.6 Baffle for Obstruction	25
4.6.1 For an Angle of 3 Degrees Baffle	26
5.0 Installation	29
5.1 Safety Considerations	29
5.2 Inspect the Equipment	29
5.2.1 What's Included	29
5.2.2 Required Materials Supplied by Others	31
5.3 PAPI Foundations	32

5.3.1 Adjustable Mounting Legs	34
5.3.2 Assembling Adjustable Legs	36
5.3.3 Mounting Unit	36
5.4 System Wiring Connections	37
5.4.1 External Wiring Connections	37
5.4.2 Input Power Connections	51
5.5 Aligning and Aiming the LED PAPI	52
5.5.1 Adjusting Azimuth Aim (Horizontal Alignment with Runway Centerline)	53
5.5.2 Adjusting the Horizontal Level and Setting Rough Elevation Glide Slope Angle	54
5.5.3 Adjusting Fine Elevation Glide Slope Angle	55
5.5.4 Saving the Glide Angle to Memory	56
6.0 RELIANCE PAPI Ground Check Procedure	57
6.1 Equipment Needed to Perform a Ground Check	57
6.2 Prior to Performing A Ground Check	58
6.3 Setup and Ground Check Procedure	59
7.0 Operation	63
7.1 Operation Safety Considerations	63
7.1.1 Normal Operation	63
7.1.2 Preparation for Heavy Snowfall	63
7.2 Understanding the LED Readout	64
7.2.1 Four-Segment LED	64
7.2.2 Push Button Functions	64
7.3 Initial Startup Using Local Control - Voltage Powered	65
7.4 Set Up and Test Remote Control Operation	65
7.5 Set Up and Test Optional Interlock Relay	66
7.6 Understanding the Fail-Open Monitoring Feature	66
7.7 Set Up the Alarm Contact on the Control Board (for Systems without Fail-Open Monitoring)	67
7.8 Initial Startup of the Current Powered System	68
7.8.1 Check Light Unit Alignment	68
7.8.2 Verify Correct Input Current in Each Light Unit	68
7.9 Commissioning the PAPI System	68
8.0 Maintenance	69
8.1 Maintenance and Repair Safety Considerations	69
8.2 Maintenance Schedule	69
8.3 Standards and Tolerances	71
9.0 Troubleshooting	73
9.1 Troubleshooting Tips	73
9.2 Troubleshooting the Field Circuit First	73
9.3 Detailed Troubleshooting and Repair Procedures	74
9.3.1 Troubleshoot and repair the RELIANCE PAPI	75
9.3.2 Troubleshooting COMM LOST error	76
9.3.3 Troubleshooting HEAT FAIL error	77
9.3.4 Troubleshooting RED LED FAIL error	77
9.3.5 Troubleshooting WHT LED FAIL error	77
9.3.6 Troubleshooting PHOT FAIL error	77
9.3.7 Troubleshooting the Inclinometer Board	78
9.3.8 Troubleshooting the Control Board	78
10.0 Repair	81
10.1 Inclinometer Assembly Replacement	81
10.2 LED Light Engine Replacement	82
10.3 Control Board Replacement	83
10.3.1 Replacing the Control Board/Display Side Panel Assembly	84
10.4 Front Glass Replacement	92
10.4.1 Replace the LED PAPI Front Glass	92
10.5 Replace the Two Desiccant Packs	93
10.6 Optional Touchpad Cover	95
11.0 Wiring Diagrams	97
11.1 Internal Wiring Diagrams	97

11.2 Field Cabling Diagrams	104
12.0 RELIANCE PAPI Parts	113
12.1 Spare Parts	116
12.1.1 Spare Part Drawings	118
A.0 SUPPORT	121
A.1 ADB SAFEGATE Website	122
A.2 Recycling	122
A.2.1 Local Authority Recycling	122
A.2.2 ADB SAFEGATE Recycling	122

List of Figures

Figure 1: PAPI System	7
Figure 2: Signal Display - L-880(L) PAPI (4 Light Unit) and L-881(L) APAPI (2 Light Unit) Systems	9
Figure 3: RELIANCE PAPI light unit	11
Figure 4: RELIANCE PAPI Control Board	14
Figure 5: LED PAPI Control Board Dip Switches	14
Figure 6: Control Board - J7 jumper setting	16
Figure 7: FAA PAPI Obstacle Clearance Surface	20
Figure 8: Obstacle Clearance Surface	21
Figure 9: Light Unit Mounting Height	23
Figure 10: Correction for Runway Longitudinal Gradient	24
Figure 11: Baffle Adjustment Rod	25
Figure 12: Installation on Concrete Pad	32
Figure 13: Positioning Plate	33
Figure 14: Frangible Coupling	34
Figure 15: Adjustable Mounting Legs	35
Figure 16: Mounting the PAPI-L Assembly to the Leg Assembly	36
Figure 17: External Grounding Diagram	37
Figure 18: One Hub Installation	38
Figure 19: Two Hub Installation	39
Figure 20: Three Hub Installation	40
Figure 21: Conduit Installation	41
Figure 22: PAPI A Primary Light Unit Installation (Box 1)	42
Figure 23: PAPI A Secondary Light Unit Installation (Box 2 and 3 of 4)	43
Figure 24: PAPI A Secondary Light Unit Installation (Box 2 of 2 and 4 of 4)	44
Figure 25: PAPI B Primary Light Unit Installation (Box 1)	45
Figure 26: PAPI B Secondary Light Unit Installation (Box 2 and 3 of 4)	46
Figure 27: PAPI B Secondary Light Unit Installation (Box 2 of 2 and 4 of 4)	47
Figure 28: PAPI B Redundant Primary Light Unit Installation (Box 1)	48
Figure 29: PAPI B Redundant Secondary Light Unit Installation (Box 2 and 3 of 4)	49
Figure 30: PAPI B Redundant Secondary Light Unit Installation (Box 2 of 2 and 4 of 4)	50
Figure 31: Elevation Setting Sequence	55
Figure 32: Adjustable Mounting Legs	55
Figure 33: Projection Screen	57
Figure 34: Ground Check Setup	59
Figure 35: LED PAPI Light Beam Centerline Mark	59
Figure 36: Laser Level	60

Figure 37: Transition Boundary	61
Figure 38: Transition Boundary Explanation	61
Figure 39: Calculate adjustment in the PAPI inclinometer elevation setting	62
Figure 40: LED Display	64
Figure 41: Fail-Open Monitoring System Layout (Primary Light Unit Only)	66
Figure 42: Fail-Open Relay	67
Figure 43: Alarm Contact on the Control Board	67
Figure 44: Control Board Indication LEDs	76
Figure 45: LED PAPI Control Board DC Power Supply Test Point	78
Figure 46: Top Inside View	81
Figure 47: Replace the LED Assembly	82
Figure 48: Desiccant Packs and Rear Seal	83
Figure 49: Identify the Side Panel Configuration	84
Figure 50: Remove the baffle closeout (configuration 1)	85
Figure 51: Remove the baffle closeout (configuration 2)	86
Figure 52: Side Panel Removal/Replacement	87
Figure 53: Control Board DIP Switch Location	88
Figure 54: Control Board - J7 jumper setting	88
Figure 55: Reassembly of the Baffle Actuator Fitting (configuration 1)	89
Figure 56: Reassembly of the Baffle Seal Washer and Seal Plate (configuration 1)	90
Figure 57: Reassembly of the Baffle (configuration 2)	91
Figure 58: Front Glass Replacement	92
Figure 59: Copper Tab and Spring Loaded Power Connector	93
Figure 60: LED Assembly	93
Figure 61: Desiccant Packs and Rear Seal	94
Figure 62: Desiccant Packs	94
Figure 63: Touchpad Cover Assembly 44A7564	95
Figure 64: Touchpad Cover Assembly Installed	95
Figure 65: Input Power Wiring Diagram - Voltage Powered (Primary Light Unit)	97
Figure 66: Input Power Wiring Diagram - Voltage Powered (Secondary Light Unit)	98
Figure 67: Input Power Wiring Diagram - Current Powered (Primary and Secondary Light Unit)	99
Figure 68: Input Power Wiring Diagram - Current Powered with Redundant Circuit (Primary and Secondary Light Unit)	100
Figure 69: Input Power Wiring Diagram - Current Powered with Fail-Open Relay (Primary Only)	101
Figure 70: Control Board Wiring Diagram	102
Figure 71: LED Assembly and Front Lens Heater Wiring Diagram	103
Figure 72: Field Cabling Diagram - Voltage Powered (2 Box)	104
Figure 73: Field Cabling Diagram - Voltage Powered (4 Box)	105
Figure 74: Field Cabling Diagram - Current Powered (2 Box)	106
Figure 75: Field Cabling Diagram - Current Powered (4 Box)	107
Figure 76: Field Cabling Diagram - Current Powered with Redundant Circuit (2 Box)	108

Figure 77: Field Cabling Diagram - Current Powered with Redundant Circuit (4 Box)	109
Figure 78: Field Cabling Diagram - Current Powered with Fail-Open Monitoring (2 Box)	110
Figure 79: Field Cabling Diagram - Current Powered with Fail-Open Monitoring (4 Box)	111
Figure 80: RELIANCE PAPI Exploded View - Parts	118
Figure 81: RELIANCE PAPI Exploded View - Hardware	119
Figure 82: RELIANCE PAPI Side View Assembly	120
Figure 83: RELIANCE PAPI Assembly Top View	120

List of Tables

Table 1: Light Unit Position - Switch SW1	15
Table 2: Function of the DIP Switches	15
Table 3: FAA Threshold Crossing Height	20
Table 4: Components Supplied by ADB Safegate	29
Table 5: Contractor Kit Items	31
Table 6: Aiming Angles for L-880(L) PAPI Light Units	52
Table 7: Aiming Angles for L-881(L) APAPI Light Units	52
Table 8: Conversion Table for Decimal Degrees to Minutes	52
Table 9: Blank Table: Record of PAPI Changes to Elevation from "H1" to "H"	58
Table 10: Sample Table: Record of PAPI Changes to Elevation from "H1" to "H"	58
Table 11: LED PAPI Periodic Maintenance Schedule	69
Table 12: FAA Standards and Tolerances for Precision Approach Path Indicator (PAPI)	71
Table 13: FAA Standards and Tolerances for a Vertical Angle Aiming Tool	71
Table 14: General PAPI System Troubleshooting Guide	74
Table 15: Indication LEDs on the Control Board	75
Table 16: COMM LOST Troubleshooting Wiring Between Boxes	77
Table 17: Spare Parts	116
Table 18: Voltage Powered Style A Only	117
Table 19: Current Powered Style B Only	117
Table 20: LED Light Engine Replacement Kit AK00030-XXX-01 Parts	117

1.0 Safety

Introduction to Safety

This section contains general safety instructions for installing and using ADB SAFEGATE equipment. Some safety instructions may not apply to the equipment in this manual. Task- and equipment-specific warnings are included in other sections of this manual where appropriate.

1.1 Safety Messages

HAZARD Icons used in the manual

For all HAZARD symbols in use, see the Safety section. All symbols must comply with ISO and ANSI standards.

Carefully read and observe all safety instructions in this manual, which alert you to safety hazards and conditions that may result in personal injury, death or property and equipment damage and are accompanied by the symbol shown below.



WARNING
Failure to observe a warning may result in personal injury, death or equipment damage.



DANGER - Risk of electrical shock or ARC FLASH
Disconnect equipment from line voltage. Failure to observe this warning may result in personal injury, death, or equipment damage. ARC Flash may cause blindness, severe burns or death.



WARNING - Wear personal protective equipment
Failure to observe may result in serious injury.



WARNING - Do not touch
Failure to observe this warning may result in personal injury, death, or equipment damage.



CAUTION
Failure to observe a caution may result in equipment damage.



ELECTROSTATIC SENSITIVE DEVICES
This equipment may contain electrostatic devices.

Qualified Personnel



Important Information

The term **qualified personnel** is defined here as individuals who thoroughly understand the equipment and its safe operation, maintenance and repair. Qualified personnel are physically capable of performing the required tasks, familiar with all relevant safety rules and regulations and have been trained to safely install, operate, maintain and repair the equipment. It is the responsibility of the company operating this equipment to ensure that its personnel meet these requirements.

Always use required personal protective equipment (PPE) and follow safe electrical work practice.

1.1.1 Introduction to Safety



CAUTION

Unsafe Equipment Use

This equipment may contain electrostatic devices, hazardous voltages and sharp edges on components

- Read installation instructions in their entirety before starting installation.
- Become familiar with the general safety instructions in this section of the manual before installing, operating, maintaining or repairing this equipment.
- Read and carefully follow the instructions throughout this manual for performing specific tasks and working with specific equipment.
- Make this manual available to personnel installing, operating, maintaining or repairing this equipment.
- Follow all applicable safety procedures required by your company, industry standards and government or other regulatory agencies.
- Install all electrical connections to local code.
- Use only electrical wire of sufficient gauge and insulation to handle the rated current demand. All wiring must meet local codes.
- Route electrical wiring along a protected path. Make sure they will not be damaged by moving equipment.
- Protect components from damage, wear, and harsh environment conditions.
- Allow ample room for maintenance, panel accessibility, and cover removal.
- Protect equipment with safety devices as specified by applicable safety regulations
- If safety devices must be removed for installation, install them immediately after the work is completed and check them for proper functioning prior to returning power to the circuit.

Failure to follow this instruction can result in serious injury or equipment damage

Additional Reference Materials



Important Information

- IEC - International Standards and Conformity Assessment for all electrical, electronic and related technologies.
- IEC 60364 - Electrical Installations in Buildings.
- CSA - C22.2 No.180:13 (R2018) Series isolating transformers for airport lighting
- FAA Advisory: AC 150/5340-26 (current edition), Maintenance of Airport Visual Aid Facilities.
- Maintenance personnel must refer to the maintenance procedure described in the ICAO Airport Services Manual, Part 9.
- ANSI/NFPA 79, Electrical Standards for Metalworking Machine Tools.
- National and local electrical codes and standards.

1.1.2 Intended Use



CAUTION

Use this equipment as intended by the manufacturer

This equipment is designed to perform a specific function, do not use this equipment for other purposes

- Using this equipment in ways other than described in this manual may result in personal injury, death or property and equipment damage. Use this equipment only as described in this manual.

Failure to follow this instruction can result in serious injury or equipment damage

1.1.3 Material Handling Precautions: Storage



CAUTION

Improper Storage

Store this equipment properly

- If equipment is to be stored prior to installation, it must be protected from the weather and kept free of condensation and dust.

Failure to follow this instruction can result in equipment damage

1.1.4 Operation Safety



CAUTION

Improper Operation

Do Not Operate this equipment other than as specified by the manufacturer

- Only qualified personnel, physically capable of operating the equipment and with no impairments in their judgment or reaction times, should operate this equipment.
- Read all system component manuals before operating this equipment. A thorough understanding of system components and their operation will help you operate the system safely and efficiently.
- Before starting this equipment, check all safety interlocks, fire-detection systems, and protective devices such as panels and covers. Make sure all devices are fully functional. Do not operate the system if these devices are not working properly. Do not deactivate or bypass automatic safety interlocks or locked-out electrical disconnects or pneumatic valves.
- Protect equipment with safety devices as specified by applicable safety regulations.
- If safety devices must be removed for installation, install them immediately after the work is completed and check them for proper functioning.
- Route electrical wiring along a protected path. Make sure they will not be damaged by moving equipment.
- Never operate equipment with a known malfunction.
- Do not attempt to operate or service electrical equipment if standing water is present.
- Use this equipment only in the environments for which it is rated. Do not operate this equipment in humid, flammable, or explosive environments unless it has been rated for safe operation in these environments.
- Never touch exposed electrical connections on equipment while the power is ON.

Failure to follow these instructions can result in equipment damage

1.1.5 Maintenance Safety



DANGER

Electric Shock Hazard

This equipment may contain electrostatic devices

- Do not operate a system that contains malfunctioning components. If a component malfunctions, turn the system OFF immediately.
- Disconnect and lock out electrical power.
- Allow only qualified personnel to make repairs. Repair or replace the malfunctioning component according to instructions provided in its manual.

Failure to follow these instructions can result in death or equipment damage

1.1.6 Material Handling Precautions, ESD



CAUTION

Electrostatic Sensitive Devices

This equipment may contain electrostatic devices

- Protect from electrostatic discharge.
- Electronic modules and components should be touched only when this is unavoidable e.g. soldering, replacement.
- Before touching any component of the cabinet you shall bring your body to the same potential as the cabinet by touching a conductive earthed part of the cabinet.
- Electronic modules or components must not be brought in contact with highly insulating materials such as plastic sheets, synthetic fiber clothing. They must be laid down on conductive surfaces.
- The tip of the soldering iron must be grounded.
- Electronic modules and components must be stored and transported in conductive packing.

Failure to follow this instruction can result in equipment damage

2.0 About this manual

This document includes system information for the ADB Safegate RELIANCE™ Precision Approach Path Indicator type L-880(L) PAPI and type L-881(L) APAPI, style A (voltage-powered) and style B (current-powered) systems with a focus on safety, installation, and maintenance procedures.

For more information, see www.adbsafegate.com.



Note

It is very important to read this document before any work is started.

2.1 How to work with the manual

1. Become familiar with the structure and content.
2. Carry out the actions completely and in the given sequence.

3.0 RELIANCE PAPI Overview

This manual provides instructions for installation, operation and maintenance of the RELIANCE™ Precision Approach Path Indicator (PAPI) LED system.

The RELIANCE PAPI systems provide visual approach path guidance to pilots of landing aircraft.

Figure 1: PAPI System



3.1 LED PAPI

Compliance with Standards

FAA	L-880(L) / L-881(L) AC 150/5345-28 (Current Edition). ETL Certified.
ICAO	PAPI Annex 14, Volume 1 (Current Edition)
T/C	PAPI / APAPI Transport Canada TP 312 par. 5.3.16.12 and Appendix 5B, Figure B-19
EASA	CS ADR-DSN.M.645
MOS	Part 139, para. 9.9.4.6
CE	DIRECTIVE 2014/35/EU: LVD annex IV & with DIRECTIVE 2014/30/EU: EMC annex IV
Rosaviation/IAC	AP-170 (Aviation rules. Part 170)

Uses

The RELIANCE™ LED PAPI (Precision Approach Path Indicator) system uses a multi-LED array to form a single light channel on each light unit to provide the pilot precise visual information, enabling the approach procedure to be performed with the utmost accuracy and safety.

Type L-880(L) PAPI system consists of four light units located at the side of the runway adjacent to the origin of the glide path. The nominal glide slope angle is midway between the angular settings of the central pair of the four units. If an aircraft is on the correct approach path, the pilot will see two red and two white light indicators. If the aircraft approach is too high, an increased number of white light indicators will be seen. If the approach is too low, the pilot will note an increased number of red light indicators.

Type L-881(L) APAPI system is an abbreviated PAPI system. It is identical to the L-880(L) PAPI system, except it consists of only two light units (instead of four). The nominal glide slope is midway between the angular settings of the two units, and when the pilot is on or close to the correct approach path, the unit nearest the runway will be seen as red and the other unit as white.

Style A (voltage powered) system is for use with 120 VAC or 240 VAC, 50/60 Hz voltage input. Style B (current powered) system is for use with 6.6 A or 20 A, 50/60 Hz series current input from a CCR.

Each ADB Safegate LED PAPI light unit is equipped with a built-in mercury-free digital inclinometer aiming tool as part of the light unit. The digital inclinometer displays the glide slope angle and horizontal level of the light unit. FAA certified PAPIs are designed to de-energize all light units if the optical pattern of any light unit is raised more than 0.5° or lowered more than 0.25° with respect to the set aiming angle of the light unit (refer to AC 150/5345-28H). For ICAO and TP312 compliant units, this feature is factory disabled, but can easily be enabled if desired.

Power Supply

For Style A (Voltage Powered) systems, power is supplied to the primary light unit. For Style B (Current Powered) systems, power is supplied individually to each light unit via a 6.6A 200 W isolation transformer. When used on a 20 A series lighting circuit, a 20A/6.6A isolation transformer must be used to step the current down to 6.6 A.

Style A (Voltage Powered)	
Input Voltage	240 VAC ±10%, 50/60 Hz or 120 VAC ±10%, 50/60 Hz ¹
L-880(L) PAPI (4 box)	528 VA max
L-881(L) APAPI (2-box)	264 VA max
Style B (Current Powered)	
Input Current	6.6 A or 20 A Series Circuit
L-880(L) PAPI (4-box) Total CCR Load	630 VA max ²
L-881(L) APAPI (2-box) Total CCR Load	330 VA max ²

Notes

¹ Source power maximum 305 m (1000 ft) away using 6 mm² (AWG 10) wire.

² Includes PAPI light units and isolation transformers.

Power Cord

The power cord is available in 8 ft (2.4 m) or 18 ft (5.5 m) length. The 8 ft (2.4 m) length is adequate for most installations. For installations that require a longer power cord, the 18 ft (5.5 m) length can be supplied and cut-to-length on-site during installation.

When the longer power cord and Contractor Kit Items are specified together, a longer length conduit is provided to accommodate the longer length power cord.

Monitored Fail-Open

The Monitored Fail-Open ordering option is for ILCMS installations and required an external remote for fail-open monitoring. Requires use of a remote monitor and a separate 65 W auxiliary isolation transformer for the primary light unit only or for each light unit as determined by the monitoring system used. Compatible with ADB Safegate and other remote monitoring systems. This ordering option does not provide CCR monitoring functionality.

Baffles

Baffles modify the horizontal light beam from the PAPI light unit for obstacle avoidance in the approach area. ADB Safegate LED PAPI baffles provide an adjustment capability to reduce the light beam from a full-width beam down to ±4.0 degree of visible light. Note: FAA Engineering Brief No.95 cautions that a light beam of less than ±3.0 degrees of visible light may not satisfy flight inspection criteria.

PAPI systems specified with baffles will include factory installed left and right side baffles on all light units. Each side can be adjusted independently. The baffles cannot be installed in the field, they are factory installed only.

Touchpad Cover

The optional touchpad cover provides added protection for the LED display.

Contractor Kit Materials

Items specified as "Contractor Supplied" are not included with the light unit. These items are typically provided by the contractor. However, as a convenience these items are available from ADB Safegate as an option within the ordering code or they can be provided as an optional "Contractor Kit". See the user manual for more information on contractor kit items.

The following items are considered contractor supplied:

- EMT for legs
- Flexible conduit
- Conduit fittings
- Reducer bushings

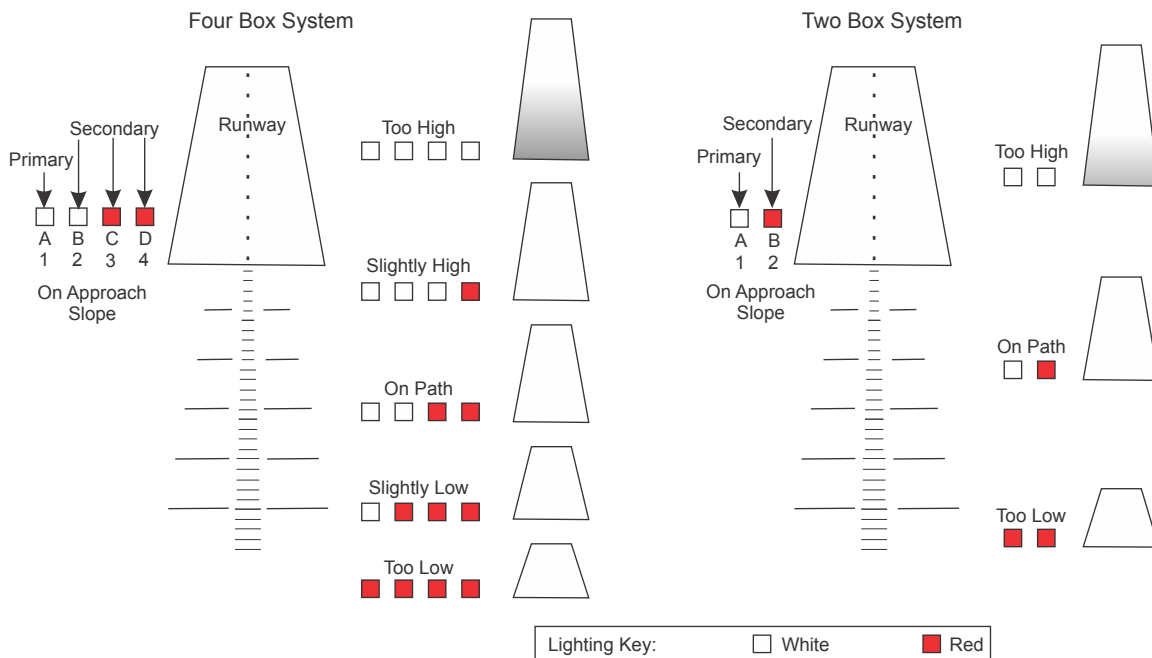
Packaging

Weight per 2 Box System	199-209 lb (90-95 kg)
Weight per 4 Box System	356-375 lb (161-170 kg)
Pallet Dimensions 2 Box System (LxWxH)	65 x 42 x 27 in (1651 x 1067 x 686 mm)
Pallet Dimensions 4 Box System (LxWxH)	65 x 42 x 48 in (1651 x 1067 x 1219 mm)

If contractor kit items are supplied with the PAPI system, the contractor kit items will be included within each PAPI light units packaging. Contractor kit items add approximately 25 lb (11.3 kg) per light unit.

3.2 Signal Display

Figure 2: Signal Display - L-880(L) PAPI (4 Light Unit) and L-881(L) APAPI (2 Light Unit) Systems



3.2.1 Type L-880(L) PAPI (4 Light Unit) System

The L-880(L) PAPI system consists of four identical light units installed in a line perpendicular to the runway centerline. The units are usually installed on the left side of the runway viewed from the approach end.

The units should be aimed so that pilots during a landing approach will see the signal format shown in [Figure 2](#):

- If the aircraft is **too high above** the approach slope, **all four units are white**.
- If the aircraft is **slightly above** the approach slope, **three units are white** (farthest from the runway); the other is red.
- If the aircraft is **close to or on** the approach slope, **two units are red and two are white**.
- If the aircraft is **slightly below** the approach slope, **three units are red** (closest to the runway); the other is white.
- If the aircraft is **too far below** the approach slope, **all four units are red**.

3.2.2 Type L-881(L) APAPI (2 Light Unit) System

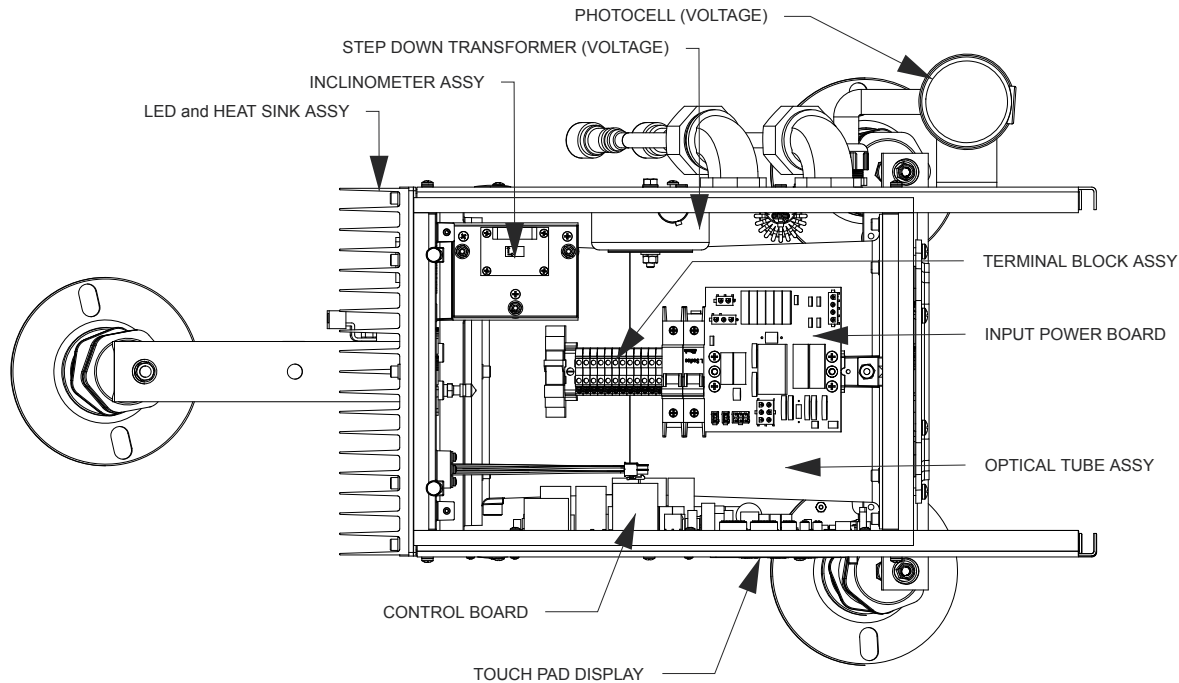
The L-881(L) APAPI system consists of two identical light units installed in a line perpendicular to the runway centerline. The units are usually installed on the left side of the runway viewed from the approach end. The units should be aimed so that pilots during a landing approach will see the signal format shown below right in [Figure 2](#):

- If the aircraft is **too high above** the approach slope, **both units are white**.
- If the aircraft is **close to or on** the approach slope, **one unit is red and one is white**.
- If the aircraft is **too far below** the approach slope, **both units are red**.

3.3 RELIANCE PAPI Light Unit

A RELIANCE PAPI light unit contains one LED light assembly, optical unit, front glass, input power board, control board, and inclinometer board. Each PAPI light unit is mounted on three adjustable legs. See Figure 9. Each component is discussed below. See Figure 3.

Figure 3: RELIANCE PAPI light unit



LED Light Assembly

An LED light assembly is located in the rear of the unit, aligns to pin located on the heat sink.

Optical Unit

A sealed optical unit that contains the optics and is designed to prevent dew, frost and dust from interfering with the light output and transition.

Front Glass

The heated front glass is designed to protect the optical unit and ensure that the front glass is kept free of dew and frost.

Digital Display

A unique digital display indicating the vertical angle can be read from outside the light unit. This eliminates the need to manually use an aiming device during initial installation and for routine verification of vertical angle setting, minimizing maintenance time.

Tilt Detection Electronics

The tilt measurement/control electronics, built into the Control Board and Inclinometer Board, are designed to de-energize the LEDs if the optical pattern is raised more than $\frac{1}{2}$ degree or lowered more than $\frac{1}{4}$ degree from the proper setting angle or if the optical pattern is tilted horizontally in either direction more than 1.75 degrees. If any Light Unit is moved from proper vertical or horizontal alignment, all PAPI light units will de-energize after about 25 seconds.



Note

For ICAO/TP312 PAPIs, the tilt/de-energizing LEDs function is optional.

3.4 Operation Overview - Voltage Powered Systems

This section provides an overview of operation for the Style A voltage powered RELIANCE PAPI system.

3.4.1 Primary Enclosure

Input voltage ([Wiring Diagrams](#)) is supplied to the Primary Enclosure at circuit breaker, Terminals 1 and 2 on the DIN rail. The Earth Ground connection attaches to the input power board on the DIN rail at J10 from the internal panel ground lug. The circuit breaker provides overcurrent protection. When the circuit breaker is turned on the voltage is fed to the input power board, which is used for lightning protection, then to the switch located on the front bulkhead, giving the user the ability to turn the system on and off externally. The switch feeds the input voltage back to the input power board which passes the voltage on to the secondary units and also fuses the voltage prior to feeding the power transformer. The power transformer steps the incoming voltage (120/240VAC) down to various internal operating voltages (0V, 24V, 48V). These voltages are fed to the control board via the input power board along with signals used for photocell control and remote operation control. The primary enclosure will turn the system on and off if any errors are detected on secondary units. This error detection is done through the use of CAN bus communications.

3.4.2 Local/Remote Operation

DIP switch (SW3-1 on PCU-1) on the control board in the primary unit enables remote or local mode operation. When set to LOCAL the system can be operated locally. When the switch is set to remote (REM) and the remote wires are connected to terminals 3 & 4 on the DIN rail, the PAPI system can be turned on or off from a remote location using a dry-switch contact closure across Terminals 3 & 4 of the DIN rail.

If the switch is in LOCAL, the PAPI system then turns ON to either the 100% level (if Daytime) or to the 5% or 20% level (if Nighttime) as controlled by the photocell.

If the switch is in REMOTE and there is a Remote ON command via a contact closure across Terminals 3 & 4 on the DIN rail. The PAPI system then turns ON to either the 100% level (if Daytime) or to the 5% or 20% level (if Nighttime) as controlled by the photocell.

3.4.3 Daytime Operation

The photocell is powered with 24VAC via the input power board feeding the control board from the power transformer after it has been stepped down from 120VAC or 240VAC. The photocell connects to the input power board via connector J2. When illumination on the photocell rises to 50-60 foot-candles, the photocell is de-energized. A delay of 45-75 seconds is incorporated in the photocell circuit to prevent switching because of stray light or temporary shadows. Zero volts is then present on J2-2 on the input power board, which the control board interprets as a Daytime signal and will control the secondary units using CAN bus communication to all turn on to the 100% level.

3.4.4 Nighttime Operation

When the illumination drops to 25 to 35 foot-candles (270-377 lux), the photocell energizes. 24VAC is then present on J2-2 on the input power board. The control board interprets this signal as a Nighttime signal. A delay of 45-75 seconds is incorporated in the photocell circuit to prevent switching because of stray light or temporary shadows. If the photocell control circuitry fails, the system reverts to high intensity. Two night-intensity settings, 5% and 20% of full intensity, can be set by using DIP switch (SW3-2 PCU-2). This allows the user to select either of the two settings to accommodate local site conditions. The primary unit will control the secondary units using CAN bus communication to all turn on to the selected intensity level.

3.4.5 Output to LED Light Assembly

Each individual unit has a control board with LED drivers which control the light engine of each individual unit.

3.4.6 Optional Interlock Relay

This option provides ON/OFF control through current sensing of the runway series circuit during nighttime operations when operated by remote control.



Note

A 6.6 A secondary, 30/45W isolation transformer is typically used. However, a 10/15W or 20/25W isolation transformer may be used.

If DIP switch (SW3-1 PCU-1), is in LOCAL, the PAPI system then turns ON to either the 100% level (if Daytime) or to the 5% or 20% level (if Nighttime) as controlled by the photocell. Therefore, in this situation, the current sensing input has no effect on operation.

If DIP switch (SW3-1 PCU-1), is in REMOTE and there is a Remote ON command via a contact closure across Terminals 3 & 4 on the DIN rail and it is Daytime, the PAPI system then turns ON to 100% level as controlled by the photocell. Therefore, in this situation, the current sensing input has no effect on operation.

If DIP switch (SW3-1 PCU-1), is in REMOTE and it is Nighttime, and the current in the series circuit is greater than 2.8A (as provided by an external isolation transformer connected to Terminals 3 & 4 on the DIN rail, with a wire passing through CT1 on the control board that is attached to Terminals 3 & 4 on the DIN rail), the PAPI system then turns ON to either the 5% or 20% level. If current in the series circuit is less than 2.8A, the PAPI system turns off.

3.5 Operation Overview - Current Powered Systems

This section provides an overview of operation for the Style B current powered RELIANCE PAPI system.

3.5.1 Style B Series Circuit Current Powered

The PAPI Style B is designed to operate from an L-828 Constant Current Regulator (CCR) with a maximum output current of 6.6 A. A single 200 W isolation transformer is connected to each Light Unit. Current from the secondary of the isolation transformer supplies power to the LED Light Assembly. When used on a 20 A series lighting circuit, a 20A/6.6A isolation transformer must be used to step the current down to 6.6 A. The CCR controls the brightness of the PAPI system. The CCR may have three or five brightness steps.

An ordering option is available for a current-powered style B LED PAPI with redundant series circuit input power capability. With this system there will be two independently fed circuits both simultaneously connected to the LED PAPI input power PCB [see wiring diagram Dual-Power Source]. Under normal operation the primary input power source will be the preferred source. If the primary input power source fails, the PAPI will automatically switch to the redundant input power source. If the primary input power source is re-energized then the PAPI will automatically switch back to the primary input power source.

Refer to one of the following wiring diagrams in [Wiring Diagrams](#).

3.6 Operation Overview - RELIANCE PAPI Light Unit

Style A - Voltage Powered

The light units used in Style A systems contain the following components; Control Board, Inclinator Board, Power Transformer, DIN rail with terminals and Input Power Board, Light Engine, Front Glass Defroster and Display Board. In Style A systems the Primary unit also contains a Photocell, Circuit Breaker and External ON/OFF switch.

Style B - Current Powered

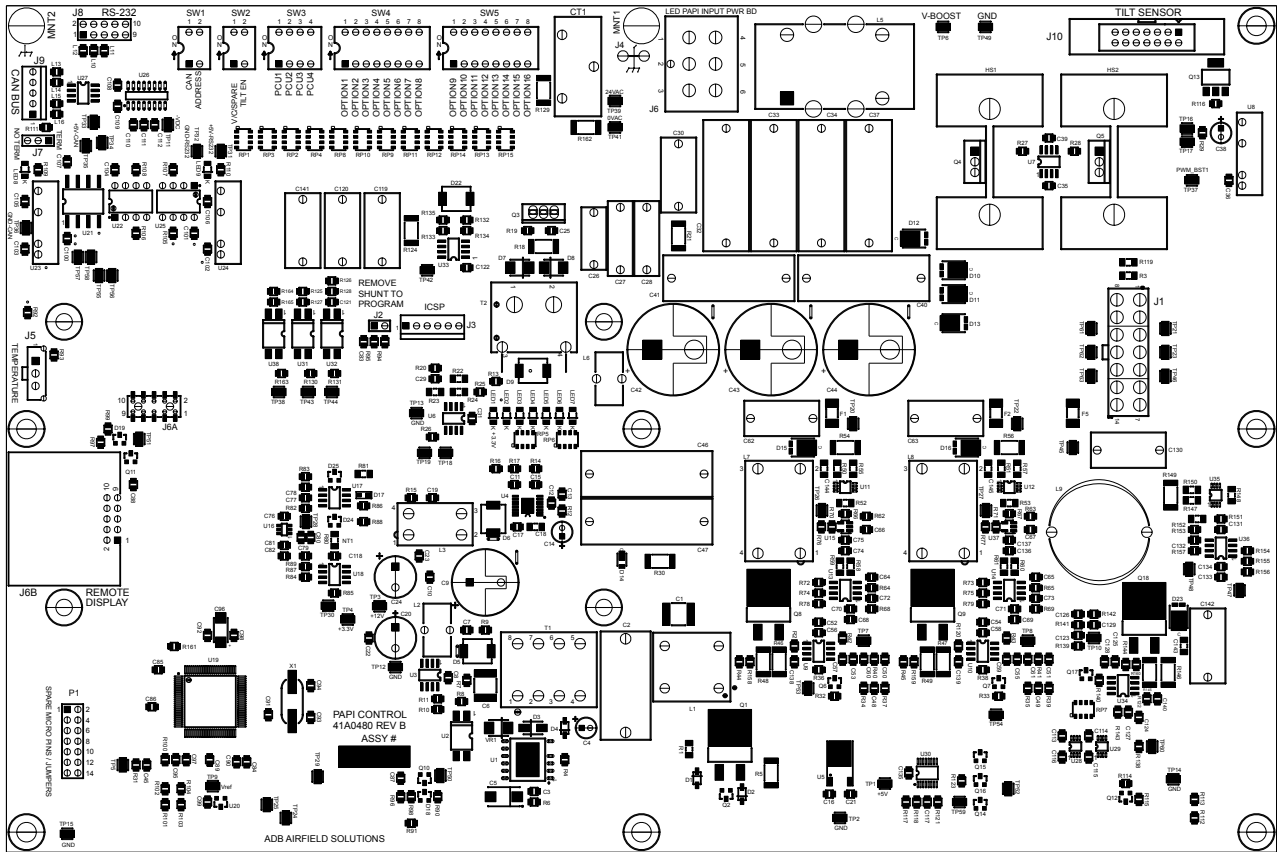
The light units used in Style B systems contain the following components; Control Board, Inclinator Board, DIN rail with terminals and Input Power Board, Light Engine, Front Glass Defroster and Display Board.

If your PAPI system is configured with TILT enabled, if any PAPI light unit is tilted for more than 25 seconds, the tilt electronics are activated and the LEDs are de-energized for all light units to indicate a system failure. The PAPI system LEDs cannot be re-energized until all the light units are in proper alignment.

3.6.1 RELIANCE PAPI Control Board Overview

The Control Board has a micro controller that controls all operations of the PAPI Light Unit as follows:

Figure 4: RELIANCE PAPI Control Board



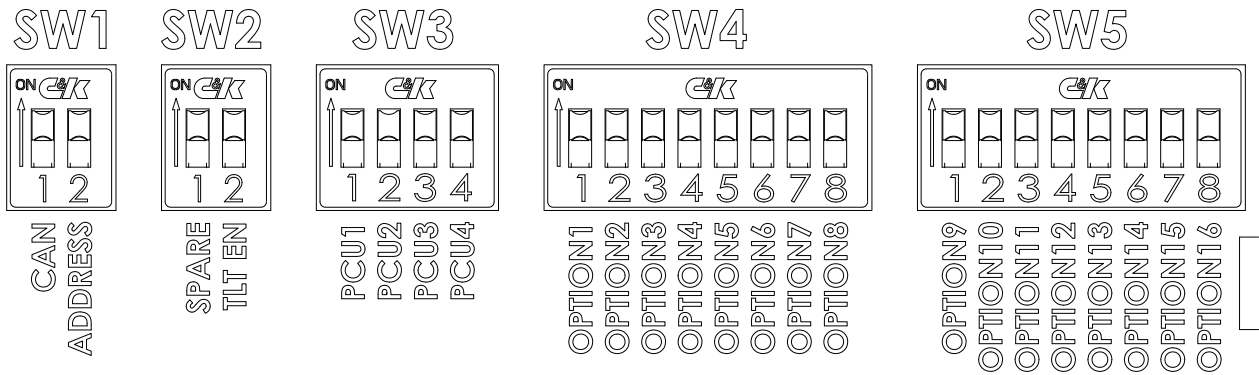
Dip Switches

The Control Board contains many DIP switches which are used for configuring each PAPI light unit.

Note

DIP switches must only be changed while the PAPI is powered OFF. To avoid damage to the electronics and ensure correct operation, DIP switch changes will only take effect after the PAPI is powered back ON.

Figure 5: LED PAPI Control Board Dip Switches



The tables below outline the function of each DIP switch.

Table 1: Light Unit Position - Switch SW1

Dash Number	Light Unit	CAN / ADDRESS	
		SW1-1 (CAN)	SW1-2 (ADDRESS)
/XXXXXX1	Position 1	ON	ON
/XXXXXX2	Position 2	OFF	ON
/XXXXXX3	Position 3	ON	OFF
/XXXXXX4	Position 4	OFF	OFF

Table 2: Function of the DIP Switches

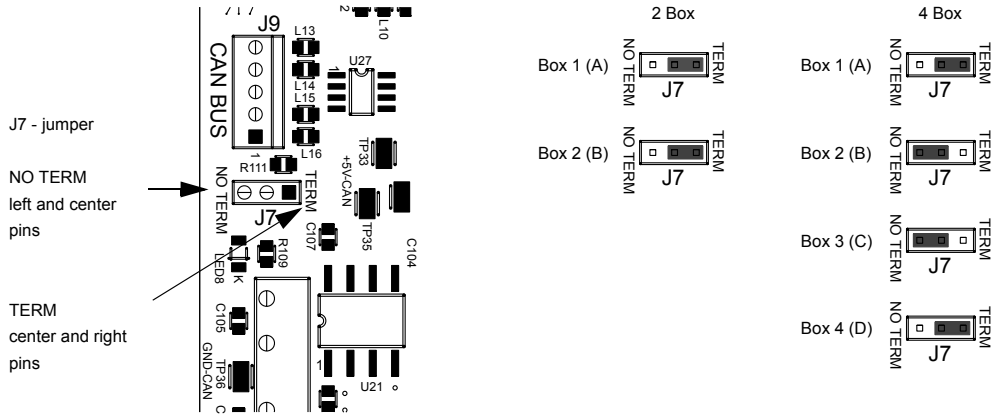
SW	PCB LABEL	ON Position	OFF Position	DEFAULT
2-1	SPARE	N/A	N/A	OFF
2-2	TLT EN	Tilt disabled	Tilt enabled	Pre-Configured
3-1	PCU1	Local	Remote	Pre-Configured
3-2	PCU2	5% Night intensity	20% Night intensity	Pre-Configured
3-3	PCU3	Current sensing for night only	Current sensing for day and night	Pre-Configured
3-4	PCU4	2 box system	4 box system	Pre-Configured
4-1	OPTION1	LEDs are OFF for B1 and B2	LEDs are ON for all steps B1-B5	OFF
4-2	OPTION2	LEDs stay ON when HEAT FAIL is detected	LEDs turn OFF when HEAT FAIL is detected	OFF
4-3	OPTION3	LEDs turn OFF on all PAPI light units when a HEAT FAIL is detected on any light unit. (SW4-2 and 5-7 must be OFF)	LEDs turn OFF on only the light unit with a HEAT FAIL. All other PAPI light units remain ON.	OFF
4-4	OPTION4	LEDs turn OFF on all PAPI light units when a LED FAIL is detected on any light unit. (SW5-7 must be OFF) (has no effect in ICAO mode)	LEDs turn OFF on only the light unit with a LED FAIL. All other PAPI light units remain ON.	OFF
4-5	OPTION5	N/A	N/A	OFF
4-6	OPTION6	Control Board Calibration Mode	Normal Operation Mode	OFF
4-7	OPTION7	FAA Mode	ICAO Mode	Pre-Configured
4-8	OPTION8	N/A	N/A	OFF
5-1	OPTION9	N/A	N/A	Pre-Configured
5-2	OPTION10	N/A	N/A	Pre-Configured
5-3	OPTION11	N/A	N/A	Pre-Configured
5-4	OPTION12	N/A	N/A	Pre-Configured
5-5	OPTION13	N/A	N/A	Pre-Configured

Table 2: Function of the DIP Switches (Continued)

SW	PCB LABEL	ON Position	OFF Position	DEFAULT
5-6	OPTION14	N/A	N/A	Pre-Configured
5-7	OPTION15	Communication disabled between boxes	Communication enabled between boxes	OFF
5-8	OPTION16	Defrost Timer disabled (instant ON)	Defrost timer enabled (180 seconds)	ON

2-box and 4-box Termination Setup at J7

Figure 6: Control Board - J7 jumper setting



2 Box setup: The jumper position on J7 for Box 1 and Box 2 will be on the Left and Center pins (TERM).

4 Box setup: The jumper position on J7 for Box 1 and Box 4 will be on the Left and Center pins (TERM); Box 2 and Box 3 will be on the Center and Right pins (NO TERM).

Light Engine Control

LED driver circuitry is used in combination with the micro controller to control the brightness levels of the light engines in the RELIANCE PAPI. This circuitry will alter the brightness levels of the LEDs when attached to a CCR according to the FAA Engineering Brief 67 (current rev).

Lamps Out

A micro controller monitors the voltage and current across each LED string (white and red). An LED string consists of all LEDs of the same color.

If one of the LEDs in either of the strings goes out or fails as an open circuit, the micro controller recognizes the abnormal voltage and will shut down the LED string. As a result both red and white LEDs are de-energized.

If one of the LEDs in either of the strings goes out or fails as a closed circuit, it is possible for the remaining LEDs to continue operating. The micro controller recognizes the abnormal voltage and will de-energize the LEDs if a maximum 25% of the LEDs in a string goes out or fails as a closed circuit. As a result both red and white LEDs are de-energized.

In the event of the LEDs de-energizing due to an LED failure, the display on the light unit will show a corresponding error, RED -> LED -> FAIL or WHT -> LED -> FAIL, on the unit that has the error. In order to fix this issue the light engine may have to be replaced.

Defroster Control

LED driver circuitry is used in combination with the micro controller to control the operation of the front glass defroster. The circuitry will change the amount of current passing through the front glass defroster. When initially turned on, the RELIANCE PAPI has a delay where the front glass is powered in order to properly clear the front glass before turning the light engines on. During normal operation, when the light engines are operating, the front glass defroster will be operating in the range between 10 and 50W, depending upon ambient temperature. The micro-controller monitors the power to the front glass defroster. If the micro-controller detects that the front glass defroster is opened or shorted the unit will shut down and display the following error on the display: **HEAT -> FAIL**.

Note

FAA systems will be shipped to activate lighting at the requested intensity within 5 seconds after the activation of power or current, per FAA AC 150/5345-28 (latest revision). This has been mandated by the testing authority for certification. Note that dew/frost on the lenses may obscure the well defined transition of the PAPI, as noted in FAA CertAlert 02-08 in the front of this manual. It is recommended at this time that PAPI light units on active runways be kept in at least a minimal light output to apply heat to the outer lens to keep it clear of dew/frost at all times, per the FAA CertAlert.

The preset configuration for the heater function can be overridden through switch SW 5-8 (OPTION16) on the Control Board to prevent light output until the outer lens is clear, typically three-five minutes after power/current has been applied. Note that this is not an approved option for FAA installations, and applying this option will place the PAPI installation to be non-compliant with the FAA Advisory Circular.

Tilt Measurement

The micro controller reads the tilt sensor angle from the Inclinator Board 20 times per second through a digital interface via the ribbon cable that connects the Control Board to the Inclinator Board. The angle is displayed on the four-digit LED display and compared to the set angle from the last time the SET ANGLE button was pushed. A tilt situation can occur in two situations. First, if the measured vertical (Glide) angle either 0.25 degrees less than the desired glide angle or 0.50 degrees greater than the desired vertical (Glide) angle. Second, if the measured horizontal (Level) angle is either less or greater than 1.75 degrees. The micro controller will then turn all the lamps off within the Light Unit and will also display the error, BOXn -> TILT, where n = 1, 2, 3 or 4, whichever unit is tilted. The remaining boxes in the system will all display the same error so the user knows which unit is titled.

CAN Bus Communications

Each RELIANCE PAPI system communicates using CAN bus protocol. The individual light units are set up to know which box position they are, 1 (A), 2 (B), 3 (C) or 4 (D). The primary light unit, box 1 (A), sends a command to all secondary units that will respond to the primary unit. The CAN messaging allows the RELIANCE PAPI system to share information between each of the light units.

- The voltage powered Style A intensity is controlled via CAN bus communication.
- Both Style A and Style B share fault conditions and tilt situations via CAN bus communications.

Photocell (Primary Light Unit Only)

The primary light unit in each voltage powered system has a photocell attached. The photocell input is read by the micro controller and will relay this signal to the secondary units using the CAN bus communication link. During daylight the intensity of the light output will be 100%. During nighttime operation the intensity of the light output will be 5% or 20% as selected on the DIP switches, shown previously.

Circuit breaker & External ON/OFF switch (Voltage Powered Primary Light Unit Only)

The primary light unit in each voltage powered system has a circuit breaker and external ON/OFF switch. The circuit breaker protects the entire system from overload or short circuit. The external ON/OFF switch allows the user to turn the entire system ON or OFF from the primary light unit. The circuit breaker is located next to the Input Power PCB, and the external ON/OFF switch is located on the front panel.

Remote/Local Switch (Voltage Powered Primary Light Unit Only)

The local/remote switch (SW3-1) determines if external control signals will be used to remotely control the PAPI system. In local operation, only the photocell is active.

3.6.2 RELIANCE PAPI Display Board Overview

Startup

At startup, the PAPI display board will show the following message:

ADB -> LED -> PAPI -> VER -> V.VV -> GGGG -> BOXn -> OFn -> COLD -> XXX -> SEC.

- **V.VV** corresponds to the current control board firmware version
 - If **V.VV** = 1.47 or earlier, use heated glass spare kit 94A0674/1.
 - If **V.VV** = 1.50 or later, use heated glass spare kit 94A0674/1 or AK00054-000-01.
- **XXX -> SEC** will be repeated until the light output is activated, if the defrost timer (SW 5-8) is enabled.

Errors

The following errors can be displayed by the four-digit LED display, if error messages are enabled:

- **COMM -> LOST** (Communications Lost)
- **HEAT -> FAIL** (Defroster Error)
- **RED -> LED -> FAIL** (Red LED Error)
- **WHT -> LED -> FAIL** (White LED Error)
- **PHOT -> FAIL** (Photocell Error)
- **BOXn -> TILT** (Unit Tilt Error)

Normal Operation

Under Normal Operating conditions the four-digit LED display will show the following information:

When the GLIDE LED is on, the glide angle will be displayed or MIN if the glide angle is less than 0. If the readout shows 9.99, this indicates that the glide slope is equal to or greater than 9.99 degrees from horizon.

When the LEVEL LED is on, the level angle will be displayed. Level readings between -0.01° and -0.99° will show the angle with a negative sign (sign takes the position of the leftmost zero). If the angle is less than -1.00° (all digits used by the angle reading) it will show the angle alternating with the word NEG. The decimal dot eats up one of the characters in the display. The display is a 4-Character not a 4-Digit.

When the SET LED is on, SAVE will be displayed if the SET button is pushed for more than five seconds to store the GLIDE angle.

3.6.3 Inclinometer Overview

The Inclinometer assembly contains a dual axis inclinometer device that provides instrumentation grade performance for leveling applications and regular maintenance checks of the glide slope. It contains a silicon-based chip that measures the tilt angle and transmits it to the PAPI main control board over a digital interface. A digital display on the side of the PAPI light unit displays the glide slope aiming angle and the horizontal level of the light unit in degrees.

The inclinometer device and digital display is considered to be a built-in aiming tool, capable of measuring the vertical angle of the light beam center from 2 to 8 degrees in graduated increments of 10 minutes of arc with a repeatable accuracy of ± 3 minutes of arc. If it is suspected that the vertical glide slope (aiming angle) on the digital display is incorrect or out of tolerance, please first refer to the [Standards and Tolerances](#) section for operating tolerances. If necessary, refer to the [Troubleshooting](#) section of this user manual, or the [SUPPORT](#) section to contact ADB Safegate Technical Support.

Regular calibration services for the inclinometer aiming tool should be performed to ensure accurate performance of the LED PAPI system. Contact ADB Safegate Technical Support for assistance with a calibration service.

4.0 Siting the RELIANCE PAPI System

This section provides guidance on how to determine the physical location for each light unit for an FAA system. Refer to FAA AC 150/5340-30 (current edition) for additional information.

For guidance on how to determine the physical location for each light unit for an ICAO system, refer to Annex 14 (current edition) paragraphs 5.3.5.24 to 5.3.5.46 and in the Aerodrome Design Manual, Part 4 – Visual aids (current edition), section 8.3.

Only FAA siting guidance is explained here after.

4.1 Siting Considerations

When viewed from the approach end, the PAPI system should normally be located on the left-hand side of the runway as shown in [Figure 7](#). The PAPI may be located on the right side of the runway if siting problems exist, such as conflicts with runways or taxiways. The PAPI must be sited and aimed so that it defines an approach path with adequate clearance over obstacles and a minimum threshold crossing height.

If the runway has an established ILS glideslope, refer to [Siting a PAPI with an FAA ILS Glideslope](#). The PAPI must be installed so that the visual glideslope coincides (as much as possible) with the electronic glideslope. If there is no ILS on the runway, refer to [Siting a PAPI Without an FAA ILS Glideslope](#). The PAPI's glideslope must be chosen to ensure the on-course signal of the PAPI provides adequate clearance over obstacles.

4.1.1 Distance of the PAPI from the Runway Edge

See [Figure 7](#). For 4-Box L-880(L) and 2-Box L-881(L) systems, the light unit nearest the runway must be 50 ft (+10, -0 ft) or 15.2 m (+3, -0 m) from the runway edge. This distance may be reduced to 30 ft or 10 m for small general aviation runways used by non-jet aircraft. Refer to FAA and ICAO document for further information.



Note

For all installations, the distance between runway and light unit is measured runway edge to center of light unit.

4.1.2 Lateral Spacing of the PAPI Light Units

The PAPI light units must have lateral separation of between 20 and 30 ft (± 1 ft) or 6 to 9 m (± 0.3 m). Refer to FAA and ICAO document for further information.



Note

For all installations, the distance between light units is measured center to center.

4.2 Siting a PAPI with an FAA ILS Glideslope

When a runway has an established ILS electronic glideslope, the PAPI on-slope signal should coincide, as much as possible, with that for the ILS. To accomplish this, place the PAPI at the same distance (tolerance of ± 30 feet or ± 9.1 m) from the threshold as the virtual source of the ILS glideslope and aim at the same angle as the ILS glideslope.

Refer to Table 3. This procedure must be modified for runways that serve aircraft in height group 4 because of the eye-to-antenna distance. For these runways, the distance of the PAPI from the threshold must equal the distance to the virtual source of the ILS glideslope plus an additional 300 feet (91 m) (+50 feet, -0 feet) (+15.2 m, -0 m). Calculations should be performed to ensure that the site chosen provides adequate obstacle clearance and threshold crossing height. See also FAA AC 150-5340-30 diagram of the same name.

Figure 7: FAA PAPI Obstacle Clearance Surface

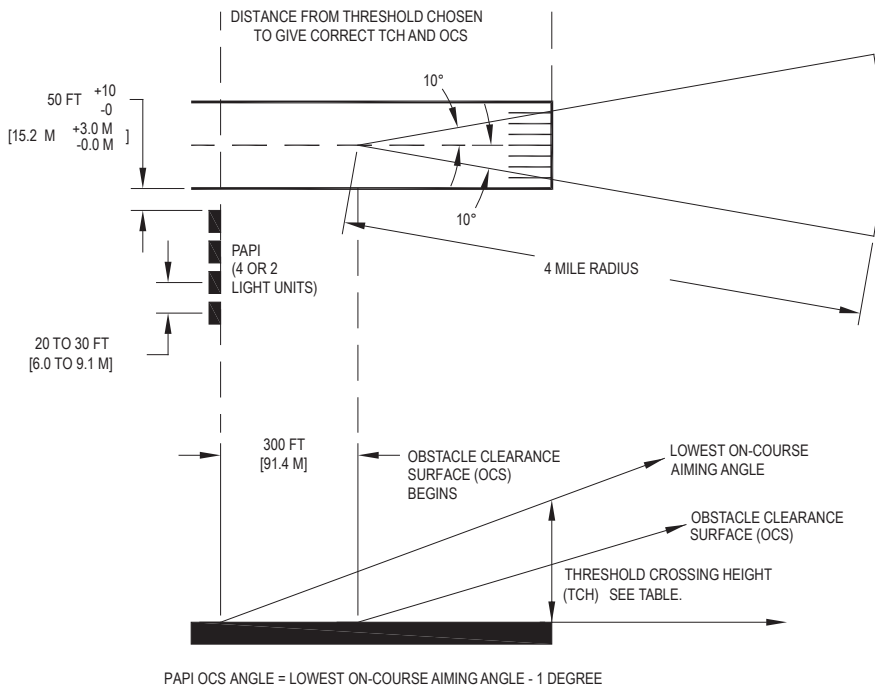


Table 3: FAA Threshold Crossing Height

Type of Aircraft	Cockpit-to-Wheel Height	Visual Threshold Crossing Height	Remarks
Height Group 1 (General aviation, small commuters, corporate turboprops)	10 feet (3.0 m) or less	40 feet (12 m) (+5 ft, -20 ft) (+1.5 m, -6.1 m)	Many runways less than 6,000 ft (1828.8 m) long with reduced widths and/or restricted weight bearing which would normally prohibit landings by larger aircraft
Height Group 2 (F-28, CV 340/440/580, B-737, DC 8/9)	15 feet (4.6 m)	45 feet (13.7 m) (+5 ft, -20 ft) (+1.5 m, -6.1 m)	Regional airport with limited air carrier service
Height Group 3 (B 707/720/727/757)	20 feet (6.1 m)	50 feet (15 m) (+5 ft, -15 ft) (+1.5 m, -4.6 m)	Primary runways not normally used by aircraft with ILS glideslope-to-wheel heights exceeding 20 ft (6.1 m)
Height Group 4 (B-747/767, L-1011, DC-10, A-300)	Over 25 feet (7.6 m)	75 feet (23 m) (+5 ft, -15 ft) (+1.5 m, -4.6 m)	Most primary runways at major airports.

4.3 Siting a PAPI Without an FAA ILS Glideslope

When the runway does not have an ILS glideslope, the PAPI must be sited and aimed so that it defines an approach path which will produce the required threshold crossing height and clearance over any obstacles in the approach area.

4.3.1 Threshold Crossing Height (TCH)

See Figure 7. The TCH is the height of the lowest on-course signal at a point directly above the threshold and the runway centerline. The minimum allowable TCH depends on the height group of the aircraft using the runway, and is shown in Table 3. The glideslope of the PAPI must provide the proper TCH for the most demanding aircraft height group using the runway.

4.3.2 Glideslope Angle

The standard visual glideslope angle for the PAPI is 3 degrees. For non-jet runways, this may be raised to 4 degrees maximum if required to provide obstacle clearance.

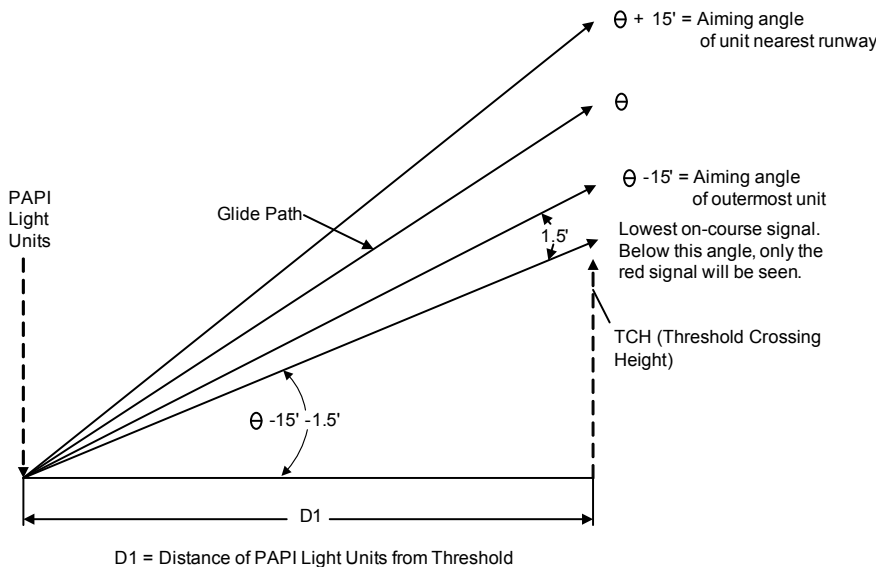
4.3.3 Obstacle Clearance Surface

Position and aim the PAPI so that no risk exists of an obstruction being located in an area where the PAPI signals can be observed. Make a survey of the site to determine if an obstruction is present in the area where you can observe the PAPI signals.

See Figure 7. This obstacle clearance surface begins 300 feet (91 m) in front of the PAPI Light Units (closer to the threshold) and proceeds outward into the approach area at an angle of 1 degree less than the lowest on-course signal. This surface extends 10 degrees on either side of the runway centerline to a distance of 4 miles (6 km) from the point of origin.

If an obstruction penetrates the obstacle clearance surface and cannot be removed, then the re-aim the glideslope angle or move the PAPI system further from the threshold. By moving or re-aiming the PAPI, re-position the obstacle clearance surface so that it will not be penetrated by an obstruction. See Figure 8.

Figure 8: Obstacle Clearance Surface



The 1.5' is one-half the width of the transition sector of the light beam. The transition between the white to red part of the beam is 3 minutes of arc (3'). Hence the additional 1.5' must be taken into account in calculating D1.

- For L-881(L): $D1 = TCH \times \cotangent(\theta - 15' - 1.5')$.



Note

For the L-880(L) PAPI system, the lowest on-course signal will be the aiming angle of the third Light Unit from the runway minus 1.5'. For a standard L-880(L) installation the lowest on-course signal will be $\Theta - 10' - 1.5'$. For Height Group 4 aircraft this angle will be $\Theta - 15' - 1.5'$.

- For L-880(L) (Standard Installation): $D1 = TCH \times \cotangent(\Theta - 10' - 1.5')$.
- For L-880(L) (Ht. Group 4 aircraft): $D1 = TCH \times \cotangent(\Theta - 15' - 1.5')$.

4.3.4 Reduction of Beam Coverage for Obstacle Avoidance

A PAPI system may require a reduction of the horizontal beam coverage because of an obstacle in the approach area. If this is the case, special consideration should be given to the following factors when determining the required system cutoff angle(s):

- Type and location of the obstacle with respect to the area where the PAPI signals can be observed.
- Wingspan of aircraft using the runway.
- Vertical pitch of the glideslope.
- Installation tolerances.
- Position of the PAPI system.
- Additional safety considerations.
- Origin of the cutoff angle should be either the outermost or innermost unit (whichever is closest in azimuth to the obstacle).
- Cutoff angles should be FAA approved.

If a reduction in the horizontal beam coverage is required, contact the ADB Safegate sales department for further details.

4.4 Siting Tolerances

Siting tolerances involve azimuth aiming, mounting height tolerance, PAPI tolerance along a line perpendicular to the runway, and correction for the runway longitudinal gradient.

4.4.1 Azimuth Aiming (Horizontal Alignment with Runway Centerline)

Each Light Unit shall be aimed outward into the approach zone on a line parallel to the runway centerline within a tolerance of $\pm 0.5^\circ$. ADB Safegate recommends azimuth aiming to be within a tolerance of 0° to 0.5° towards centerline, if possible.

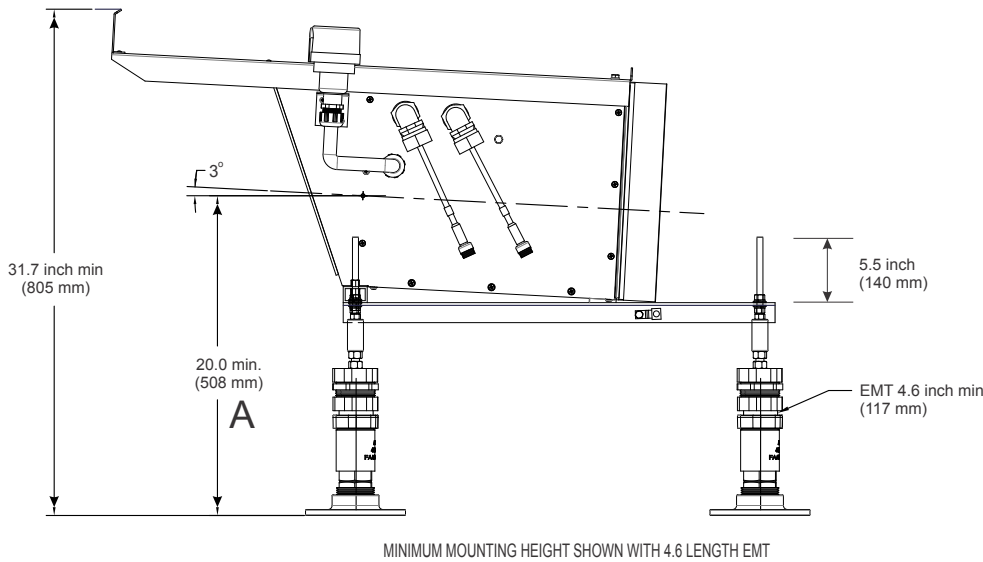
4.4.2 Mounting Height Tolerance

The beam centers of all Light Units shall be within ± 1 inch (25 mm) of a horizontal plane. The beam center is located at the Beam Center Mark (+) as depicted on Figure 9. This plane shall be within ± 1 foot (300 mm) of the elevation of the runway centerline at the intercept point of the visual approach angle with the runway except for additional siting considerations. Refer to [Additional Siting Considerations](#). The Light Unit EMT leg length is chosen by the installer to ensure the proper mounting height is achieved. Refer to FAA AC 150/5340-30 (current edition) for additional information on installation requirements.

Figure 9: Light Unit Mounting Height

EMT Length	A (min)	A (max)	Height (min)	Height (max)
4.6 (117)	20 (508)	25.5 (648)	31.7 (805)	37.2 (945)
10.1 (257)	25.5 (648)	31 (787)	37.2 (945)	42.7 (1085)
13.0 (330)	28.4 (721)	33.9 (861)	40.1 (1019)	45.7 (1161)
14.5 (368)	29.9 (760)	35.4 (900)	41.6 (1057)	47.2 (1200)

Dimensions: inch (millimeter)



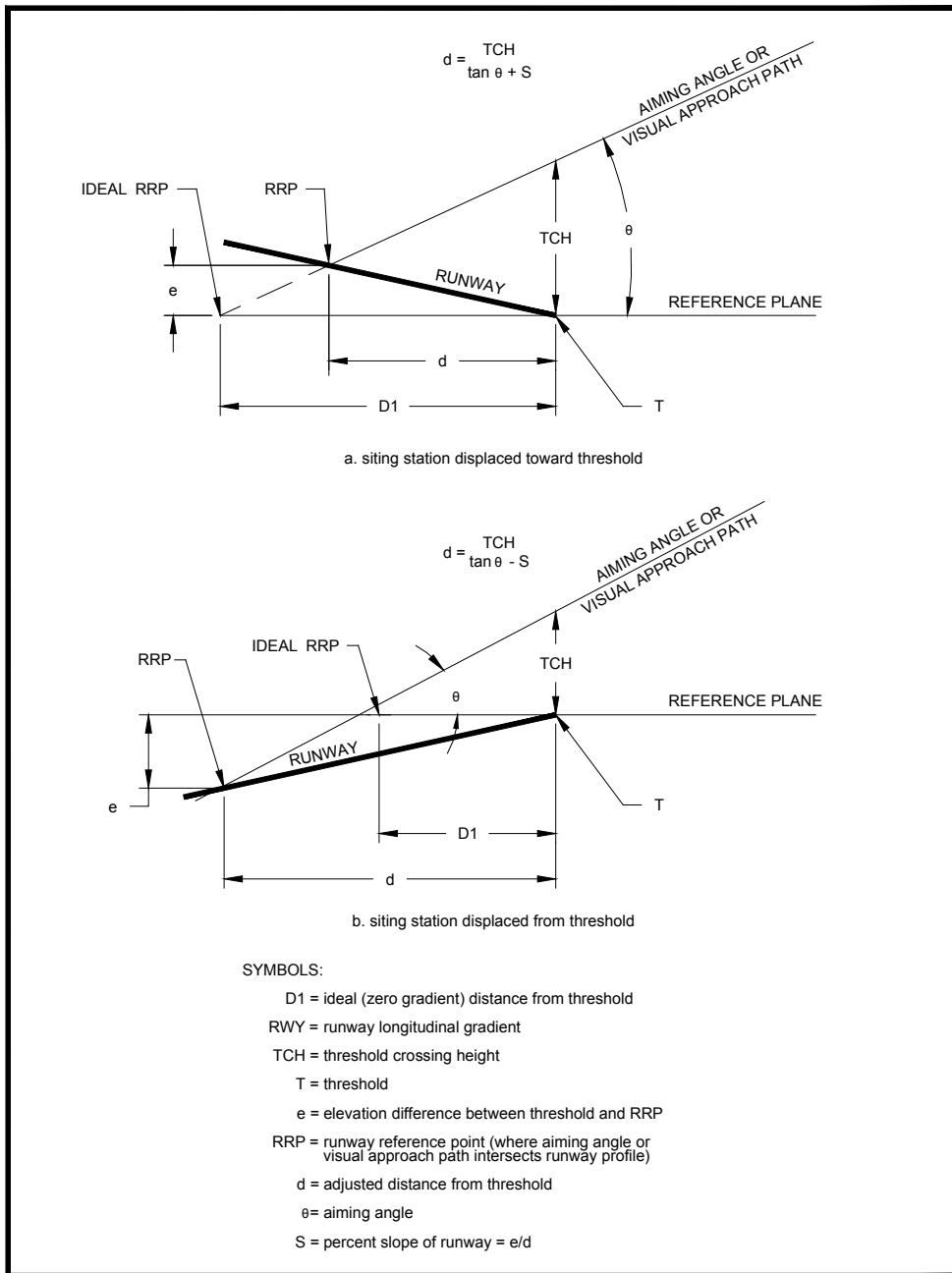
4.4.3 PAPI Tolerance Along Line Perpendicular to Runway

The front face of each Light Unit in a bar shall be located on a line perpendicular to the runway centerline within ± 6 inches (150 mm).

4.4.4 Correction for Runway Longitudinal Gradient

See Figure 10. Refer to AC 150/5430-30 (current edition). On runways where a difference exists in elevation between the runway threshold and the elevation of the runway centerline adjacent to the PAPI, you may need to adjust the location of the Light Units with respect to the threshold to meet the required obstacle clearance and TCH.

Figure 10: Correction for Runway Longitudinal Gradient



If the condition exists, perform the following steps to compute the change in the distance from the threshold required to preserve the proper geometry:

1. Obtain the runway longitudinal gradient. This can be done by survey or obtained from airport obstruction charts or as-built drawings.
2. Determine the ideal (zero gradient) distance from the threshold in accordance with the preceding instructions.
3. Assume a level reference plane at the runway threshold elevation. Plot the location determined in Step 2.
4. Plot the runway longitudinal gradient.

5. Project the visual glideslope angle to its intersection with the runway longitudinal gradient. Then solve for the adjusted distance from the threshold either mathematically or graphically. Refer to [Mounting Height Tolerance](#) .
6. Verify the calculated location gives the desired threshold crossing height.

4.5 Additional Siting Considerations

Below are additional siting considerations.

- Where the terrain drops off rapidly near the approach threshold and severe turbulence is experienced, locate the PAPI farther from the threshold to keep the aircraft at the maximum possible threshold crossing height.
- On short runways, the PAPI should be as near the threshold as possible to provide the maximum amount of runway for braking after landing.
- Contact your ADB sales representative for additional guidance if the PAPI Light Units must be installed at locations where snow is likely to obscure the light beams.
- Since the effectiveness of the PAPI system is dependent on the optical red and/or white signal pattern from the Light Units, make sure that no other lights are close enough to confuse the pilot.

4.6 Baffle for Obstruction

Baffles modify the horizontal light beam from the light unit for obstacle avoidance in the approach area. ADB Safegate LED PAPI baffles provide an adjustment capability to reduce the light beam from a full-width beam down to ± 4.0 degree of visible light. Note: FAA Engineering Brief No.95 cautions that a light beam of less than ± 3.0 degrees of visible light may not satisfy flight inspection criteria.

PAPI systems specified with baffles will include factory installed left and right side baffles on all light units. Each side can be adjusted independently. The baffles cannot be installed in the field, they are factory installed only.

Contact ADB SAFEGATE for more information or if you are not sure about the cut-offs required for your particular application.

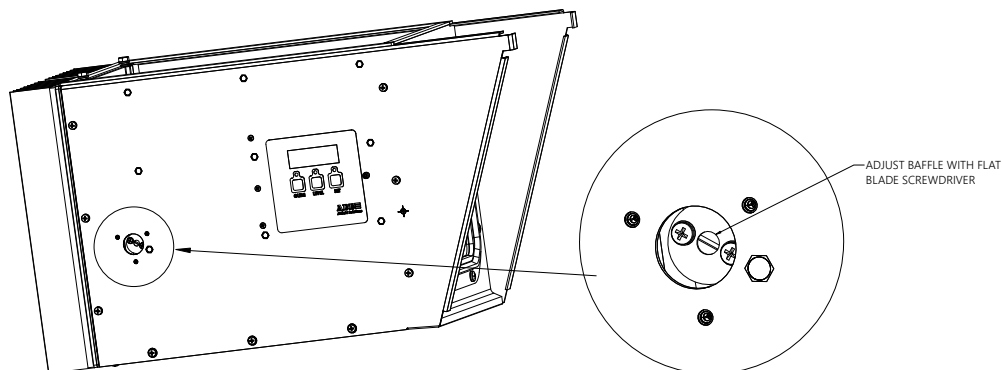
i Note
The estimated time required is 60 minutes per light unit.

To modify the horizontal light beam coverage of the light unit, perform the following procedure:

Depending on the location of the obstruction in the approach area (right or left side), adjust the baffle rod on the opposite side bulkhead. If both sides are obstructed, adjust one side completely first, then do the other side.

i Note
The baffle adjustment rod is mounted on either the left or right side on the bulkhead.

Figure 11: Baffle Adjustment Rod



IF the obstacle is on the LEFT side of the approach area, then adjust the baffle adjustment knob on the RIGHT side. -OR- IF the obstacle is on the RIGHT side of the approach area, then adjust the baffle adjustment knob on the LEFT side. See [Figure 11](#).

Baffling right or baffling left requires adjusting the baffle on the opposite side of the light unit as the PAPI optics invert and flip the beam image. Each full rotation of the adjusting rod will change the amount of baffling by approximately 0.157 degree (9.4 minutes).

i Note

It may be necessary to lower the light unit in elevation for the individual to see the light beam. If this is the case, and the TILT function activates and turns the LEDs off, disable the TILT switch to restore power to the unit.

To disable the TILT switch, place the DIP switch SW2-2 on the control board to the ON (or UP) position. See [RELIANCE PAPI Control Board Overview](#) section for further explanation.

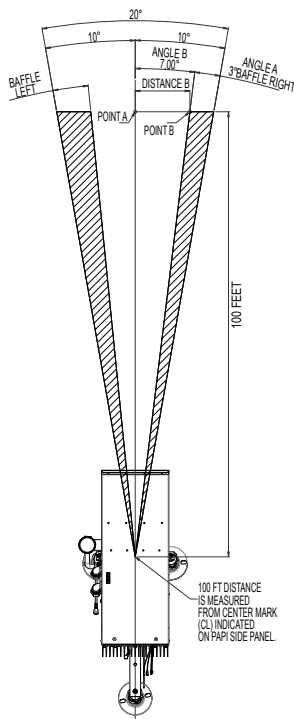
To meet FAA specification requirements, the TILT switch must be enabled.

Position someone equipped with a radio at the edge of the obstacle or as far out from the edge the beam where cutoff is desired. Move the baffle along the aperture of the baffle mounting plate until the light beam cut-off is seen by the individual who is standing in front of the obstacle. See [Figure 11](#).

i Note

To meet FAA specification requirements, the LED PAPI should be shipped with the baffle in the minimum baffle position. This can be verified by rotating the adjusting rod clockwise until resistance is felt. This indicates that the baffle is fully retracted. Movement of the baffle plate can be observed by looking through the front window of the PAPI.

4.6.1 For an Angle of 3 Degrees Baffle



For the amount of baffling desired (in this instance 3 degrees), calculate the distance B required to provide visual indication of the angle. Base the calculation on the 100 foot (30.5 m) distance measured from the PAPI beam CL. Angle B will be the difference between the full PAPI beam angle (10 degrees) and the angular amount that is desired to be cut off.

1. Establish Point A: Measure 100 feet (30.5 m) from the CL mark on the side of the PAPI. Sight along the edges of the PAPI to determine the CL of the horizontal beam.
2. Establish Point B: Starting at point A, measure perpendicular to beam the distance calculated for the desired baffle angle (in this case, 12.3 feet (3.7 m) for 3° baffle).

The adjusting rod can now be rotated counterclockwise to baffle the PAPI. As the rod is rotated counterclockwise, the baffling will slowly increase. This can be observed directly by an observer on a ladder, or by vertically standing a painted pole at point B and watching for the beam edge to pass that point.



Note

If the terrain drops rapidly in front of the PAPI, the observer will require a ladder.



Note

Setting the baffle angle during the day will require the direct observation method (observer on a ladder). For a 3° elevation setting, the beam will rise a little over 5 feet (1.5m) in the 100 foot (30.5 m) distance. Setting the baffle angle at night allows for the use of a white painted pole to determine where the edge of beam is located.

For an Angle of 3 Degrees Baffle, the Angle B will be 7 degrees and for an observation distance of 100 feet (30.5 m).

- Distance B = 100 ft (30.5 m)
- Angle B = 7°
- Distance B = 100 Tan 7° = 12.28 Feet (3.7m)

3. Remove small cover plate from the side of the PAPI to expose the baffle adjustment rod.



CAUTION

Failure to follow these warnings may result in equipment damage.

The adjusting rod should rotate with little torque required. There are hard stops at minimum baffle and maximum baffle. DO NOT attempt to force the adjustment beyond these stops.

- To rotate the baffle adjusting rod, it is not necessary to loosen the adjusting rod fitting.
- Do not loosen the adjusting rod fitting or actuator fitting as this can compromise the seal integrity of the system.

4. Using a flathead screwdriver, rotate the adjusting rod as follows:

- a. Counter-clockwise to increase amount of baffling.
- b. Clockwise to decrease the amount of baffling.

5. Replace the cover plate.

5.0 Installation

This section provides instructions for installing the PAPI Light Units. Refer to airport project plans and specifications for specific installation instructions. The installation must conform to the applicable sections of the National Electric Code and local codes.

5.1 Safety Considerations

Read this installation section thoroughly before installing the equipment. A thorough understanding of system components and their requirements will promote safe and efficient installation. See FAA AC 150/5340-30 (current edition) and site plans and specifications for additional guidance on PAPI installation.



WARNING

INSTALLATION

- Allow only qualified personnel to install ADB Safegate and auxiliary equipment. Use only approved equipment. Using unapproved equipment in an approved system may void agency approvals. Observe the safety instructions in this document and all related documentation.
- Make sure all equipment is rated and approved for the environment where it is being used.
- Follow all instructions for installing components and accessories.
- Install all electrical connections in compliance with local and national codes and regulations.
- Use only electrical wire of sufficient gauge and insulation to handle the rated current demand. All wiring must meet local and national codes.
- Route electrical wiring along a protected path. Make sure it will not be damaged by moving equipment.
- Protect components from damage, wear and harsh environmental conditions.
- Allow ample clearance for maintenance, panel accessibility and cover removal.
- Protect equipment with safety devices as specified by applicable safety regulations.
- If safety devices must be removed for installation, reinstall them immediately after the work is completed and check them for proper functioning.
- The Light Unit cord set must be protected prior to installation.

Failure to follow these safety procedures can result in personal injury or death.

5.2 Inspect the Equipment

Upon receipt of the PAPI system and before unpacking it, verify that the labeled equipment matches the bill of lading. Inspect all items for damage. Report any damage immediately to the carrier and send a copy to ADB SAFEGATE.

5.2.1 What's Included

Table 4: Components Supplied by ADB Safegate

Component	L-880(L)/PAPI (4-box)				L-881(L)/APAPI (2-box)			
	Style A (Voltage)	Style B (Current)	Style B (Redundant)	Style B (Monitored)	Style A (Voltage)	Style B (Current)	Style B (Redundant)	Style B (Monitored)
Light Unit Assembly	4	4	4	4	2	2	2	2
Mounting Flange 62B0107-2	12	12	12	12	6	6	6	6
Frangible Coupling 44B0180	12	12	12	12	6	6	6	6
EMT Compression Coupling 77A0009	12	12	12	12	6	6	6	6

Table 4: Components Supplied by ADB Safegate (Continued)

Component	L-880(L)/PAPI (4-box)				L-881(L)/APAPI (2-box)			
	Style A (Voltage)	Style B (Current)	Style B (Redundant)	Style B (Monitored)	Style A (Voltage)	Style B (Current)	Style B (Redundant)	Style B (Monitored)
Electrical Frangible Coupling 62A0711	7	10	10	10	3	4	4	4
40 ft 6 Pin Inter-Box Cable 73A0178/40	3	3	3	3	1	1	1	1
6 Pin Female Power Cord If 8 ft 73A0176 If 18 ft 73A0176/18	3	3	3	3	1	1	1	1
6 Pin Male Power Cord If 8 ft 73A0180 If 18 ft 73A0180/18	4	3	3	3	2	1	1	3
2.5ft 6 Pin Female Power Cord 73A0175	1	-	-	-	1	-	-	-
16/2 Power Cord If 8 ft 73A0107/98 If 18 ft 73A0107/216	-	4	-	3	-	2	-	1
14/4 Power Cord If 8 ft EW00067-2.5-01 If 18 ft EW00067-5.5-01	-	-	4	1	-	-	2	1
6ft 16/2 L-823 Ext Cord 73A0108/6	-	-	-	1	-	-	-	1
Wye Connector EW00068-000-01	-	-	4	1	-	-	2	1
Cable Clamp 961-X 63A0563	7	6	6	6	3	2	2	2
Cable Clamp L804RGL (Wye) 63A0563/1	-	-	4	1	-	-	2	1

Note: 16-14 AWG butt splices and heat shrink provided for field circuit splicing for voltage powered light units, see [Field Cabling Diagrams](#) for details.

For Installations That Require A Longer Power Cord:

The power cord is available in 8 ft (2.4 m) or 18 ft (5.5 m) length. The 8 ft (2.4 m) length is adequate for most installations. For installations that require a longer power cord, the 18 ft (5.5 m) length can be supplied and cut-to-length on-site during installation.

When the longer power cord and Contractor Kit Items are specified together, a longer length conduit is provided to accommodate the longer length power cord.

 **Note**

Power cord length is specified within the LED PAPI ordering code. See Ordering Code.

5.2.2 Required Materials Supplied by Others

Installing either the L-880(L)/APAPI or the L-881(L)/PAPI requires the following items, which must be supplied by others:

- 3/8-16 anchor bolts, 2 per leg; either expansion bolts and sleeves or J-bolts (M-12 is an expectable substitute)
- Aviation orange paint (used to paint the 2 in EMT legs); 12 oz. spray cans of orange paint are also available from ADB SAFEGATE (P/N 95A0008)
- Contractor supplied materials (See section Contractor Kit Items for details).

Base plates are available as optional sales order line item. Base plates are machined with 2in-11.5 NPS threads to match the threads of the provided 62A0711 Frangible Couplings. See [F Field Cabling Diagrams](#) for details.

Contractor Kit Items

Items specified as "Contractor Supplied" are not included with the light unit. These items are typically provided by the contractor. However, as a convenience these items are available from ADB Safegate as an option within the ordering code or they can be provided as an optional "Contractor Kit":

AK00031-XX1-01 for 8 ft power cord (see [Table 5](#) to choose your configuration).

AK00031-XX2-01 for 18 ft power cord (see [Table 5](#) to choose your configuration).

Table 5: Contractor Kit Items

Component	L-880(L)/PAPI (4-box)			L-881(L)/APAPI (2-box)		
	Style A (Voltage)	Style B (Current)	Style B (Redundant)	Style A (Voltage)	Style B (Current)	Style B (Redundant)
Contractor Kit Part No.	AK00031-A4X-01	AK00031-B4X-01	AK00031-R4X-01	AK00031-A2X-01	AK00031-B2X-01	AK00031-R2X-01
2 in x 13 in EMT Leg 60A4516	12	12	12	6	6	6
1-1/4 in x 8 ft Liquid-Tight Conduit If 8ft 60A4620/8 If 18ft 60A4620/18	7	10	10	3	4	4
1-1/4 in Liquid-Tight Fitting 77A0265	7	10	10	3	4	4
1-1/2 in x 1-1/4 in Bushing 77A0266	7	10	10	3	4	4

2-inch diameter EMT tubing (2-3/16 in OD) to be provided and installed by contractor. Length to be determined at installation to adjust for uneven terrain and to mount optical box at correct elevation above the runway. To ensure stable installation, the EMT tubing shall extend 3-1/4 inches into the frangible coupling and full insertion into compression coupling.

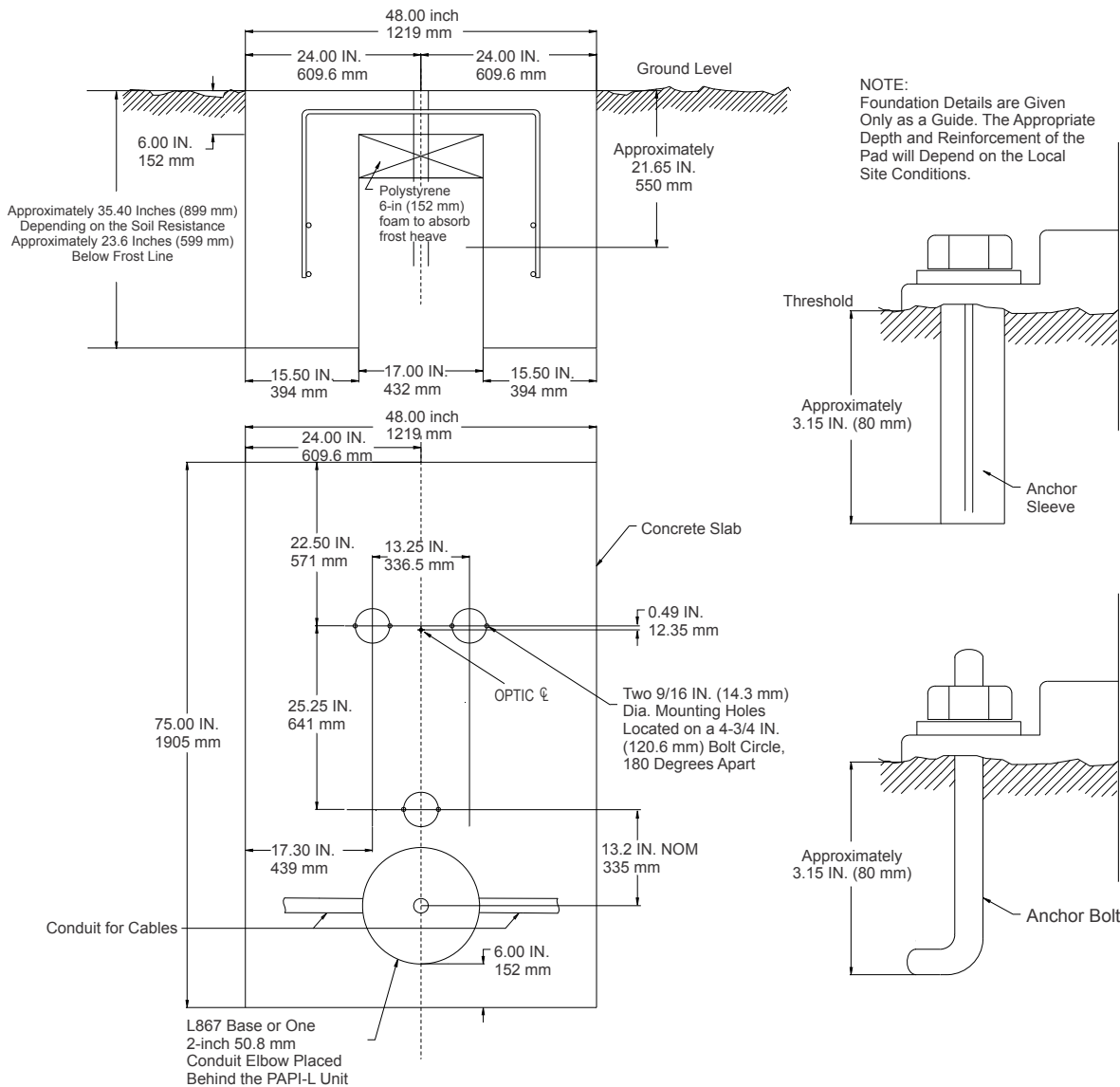
The EMT tubing must be painted international orange per FED-STD-595, color 12197 to provide corrosion protection.

5.3 PAPI Foundations

The PAPI light units shall be installed on concrete pads at ground level with frangible couplings. The foundation should extend at least 12 inches (300 mm) below the frost line and at least 1 foot (300 mm) beyond the light unit to minimize damage from mowers. Figure 12 through Figure 13 show dimensions that are generally acceptable for the concrete pad for the LED PAPI.

For series circuit (Style B) applications, high voltage field cables and low voltage communication cables must have separate conduit runs. See Field Cabling Diagrams.

Figure 12: Installation on Concrete Pad



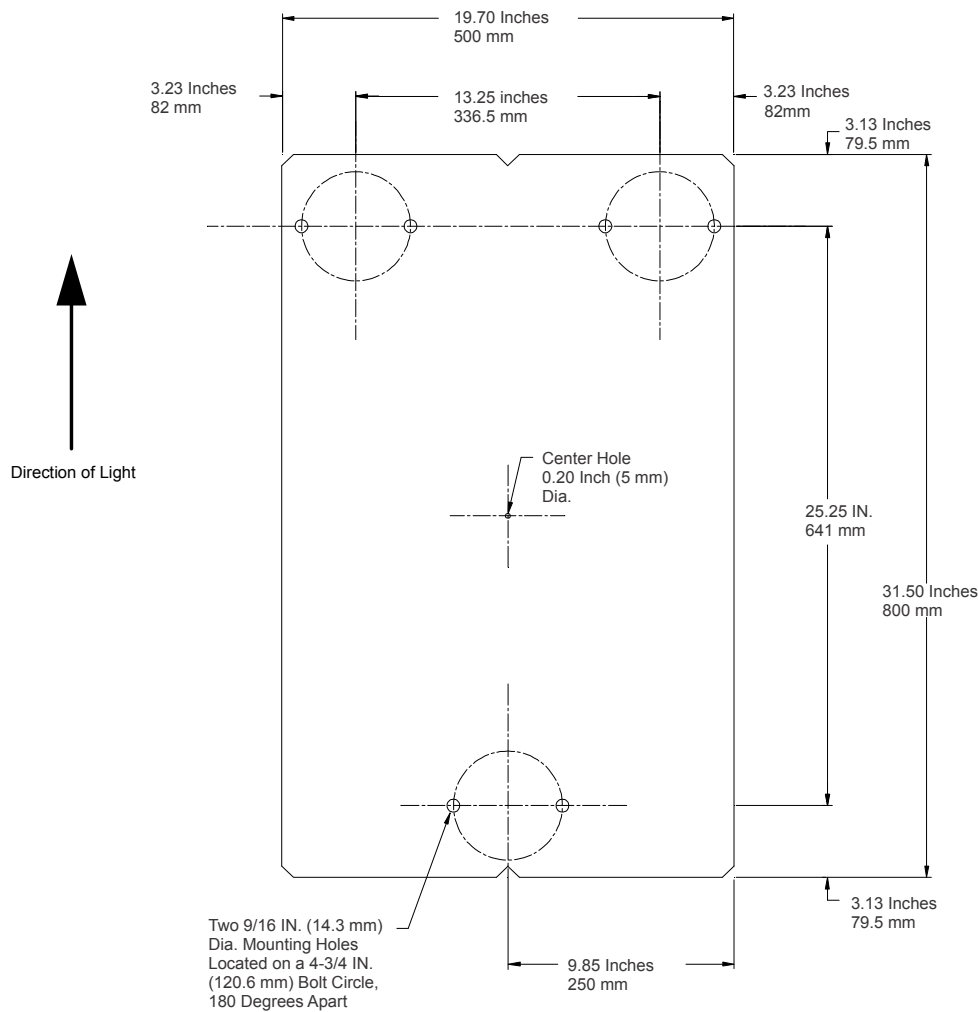
Installation on Concrete Pad (LED, Three-Leg PAPI-L)

To cast the concrete pad and anchor the support fixtures, perform the following procedure:

1. Stake out the longitudinal axis of the light units parallel to the runway centerline.
2. Dig the foundation hole per Figure 12.

3. Place polystyrene foam in pit to absorb frost heave below the central part of the slab. Place L-867 light base/conduit elbows or pipes for cables. Place bars for reinforcement of concrete.
4. Pour in concrete and allow it to harden for at least one day.
5. After concrete sets up, using chalk draw a longitudinal axis (in accordance with the axis staked out on the ground) on the upper surface of the pad. Draw a transverse axis perpendicular to the other axis.
6. See [Figure 13](#). Lay a positioning plate on the pad; center it by positioning the central hole at the intersection of both axes; align the plate along the longitudinal axis using the V-notches in the plate.
7. Mark the six locations of the screws on the slab; drill the six holes to the diameter and depth required for the expansion sleeves and insert the sleeves.
8. See [Figure 13](#) to locate flanges using mounting templates. Place and fasten the flanges with two screws.

Figure 13: Positioning Plate



Positioning Plate (PN: AW9020X)

9. Install the frangible couplings. Make sure to place the second nut, ferrule compression joint, and ferrule ring on the bottom of the EMT tube first before screwing the tube with nuts, joints, and rings onto the frangible coupling. See [Figure 14](#).

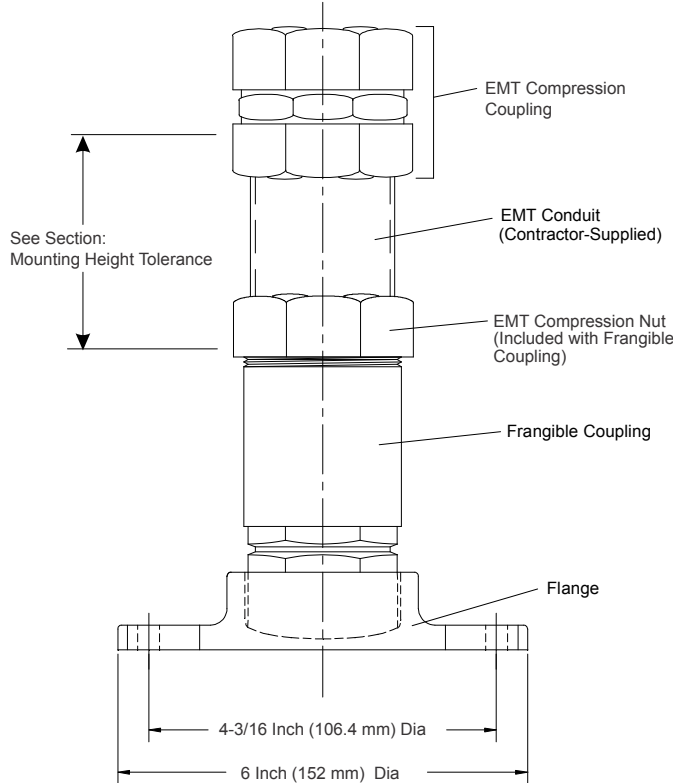


Note

The contractor supplies and installs the 2-inch (50.8 mm) diameter (2-3/16 in OD) EMT tube. Determine length at installation to adjust for uneven elevation above the runway. See [Figure 9](#). The 2-inch EMT tube (2 3/16 in OD) extends into the frangible coupling ([Figure 14](#)) 3.25 in (82.55 mm) and 1-1/2 in (38.1 mm) into the nut and ferrule compression joint to ensure stable installation. Paint the tube according to Federal standard 595A, color #12197, international orange, to reduce corrosion.

Instead of expansion sleeves, cast 3/8-16 x 6-inch anchor j-bolts into the concrete at the proper locations on a 4-3/16 in. (106.36 mm) diameter bolt circle, in two places.

Figure 14: Frangible Coupling

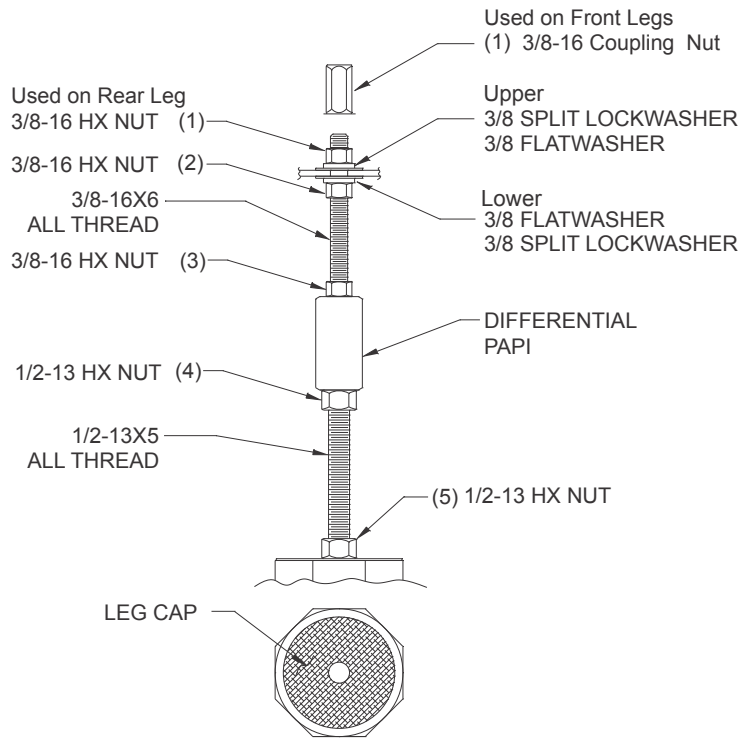


5.3.1 Adjustable Mounting Legs

See [Figure 15](#). The three adjustable mounting legs are each made up of two screw rods connected by a differential sleeve. The upper (smaller diameter) rod is fitted with nuts and locking nuts designed for coarse height setting of the unit.

The differential sleeve is used for the fine adjustment setting of the unit. The lower (larger diameter) rod is inserted into a conduit column with frangible coupling held in place by a flange bolted on a concrete pad.

Figure 15: Adjustable Mounting Legs



A4 PAPI LEG ASSY. REF

5.3.2 Assembling Adjustable Legs

Assemble the legs for each light unit as follows:

1. See Figure 15. Screw threaded rods into differentials and assemble each leg.



Note

Do not assemble upper hex nut (1), upper split lockwasher, and upper flatwasher. These items will be installed after the light unit is mounted on the legs.

The threaded rods should only be threaded in $\frac{1}{4}$ of the length of the differential so there will be room for adjustment.

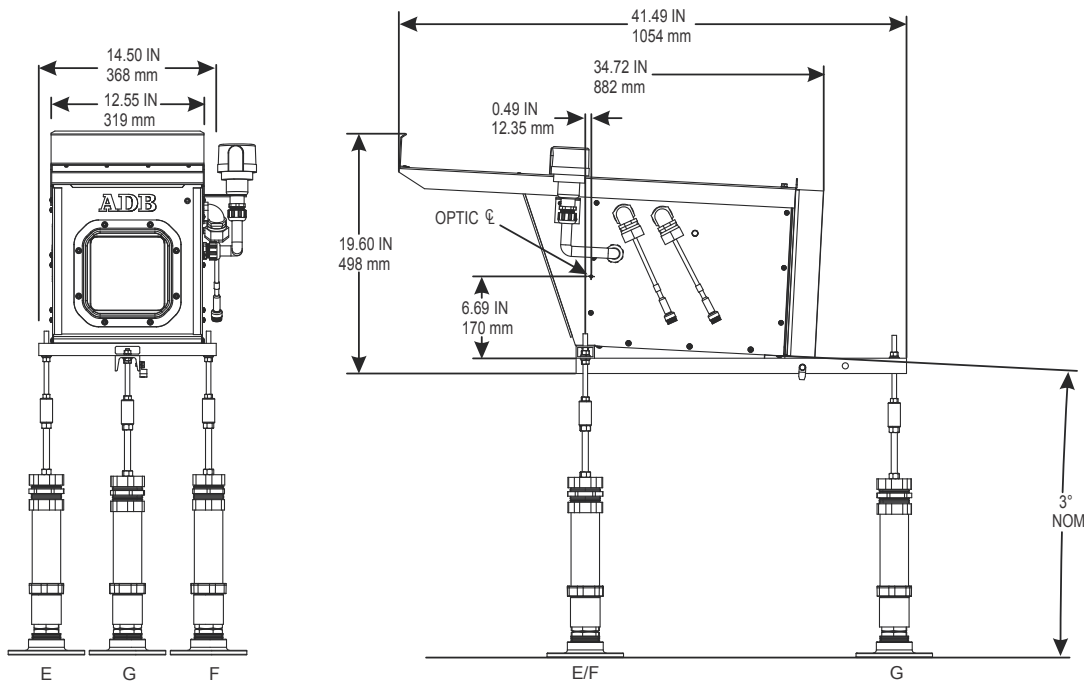
2. Screw front and rear leg assemblies into the frangible couplings installed on concrete pad.

5.3.3 Mounting Unit

To mount the unit, perform the following procedure:

1. See Figure 15. Gently mount the light unit on the three legs so that the unit rests on the top of the lower flatwasher, lockwasher, and hex nut (2).
2. Install the upper flatwasher, lockwasher, and hex nut (rear leg) (1) (coupling Nut for front legs) on the threaded rod. Do not tighten nuts.
3. Make sure the bottom of the light unit is resting on the top of the lower flatwasher of the right front leg F.
4. Make sure all locking nuts on the frangible couplings are tightened.

Figure 16: Mounting the PAPI-L Assembly to the Leg Assembly



5.4 System Wiring Connections



WARNING

Before making any wire connections, make sure that you turn off all incoming power sources. Failure to observe this warning may result in personal injury, death, or equipment damage.

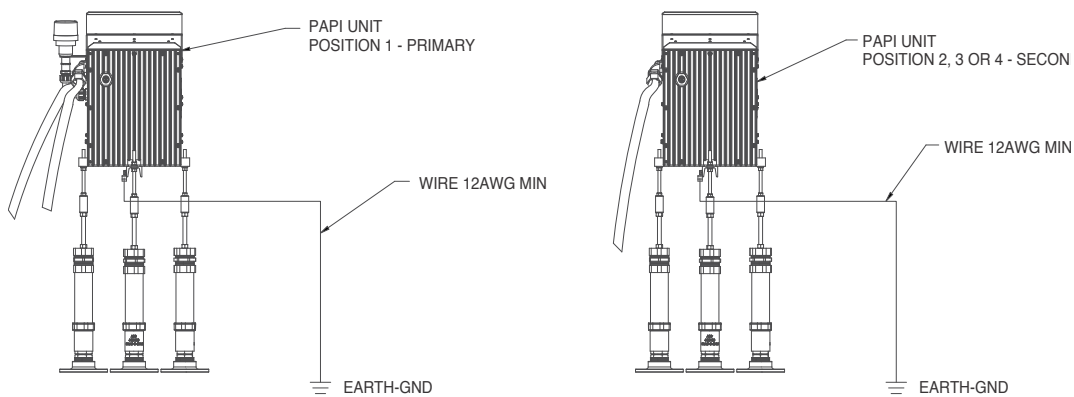
5.4.1 External Wiring Connections

External Grounding Connection for Each Light Unit

Each light unit must be grounded. To ground each light unit, attach a minimum 12 AWG (4 mm²) ground wire to the ground lug located on the rear bottom side of each light unit. Connect ground wire to appropriate earth ground.

Figure 17: External Grounding Diagram

PRIMARY AND SECONDARY LIGHT UNIT EARTH GROUND CONNECTION



Field Cabling Connections Between Light Units

All installation wiring should conform to the applicable sections of the National Electric Code (US), other national and local codes.

Reference [Field Cabling Diagrams](#).

Field splice kit(s) are for use with attaching interconnection wiring. They are ordered as a separate line item than the PAPI system.

Note

All external wiring must be a minimum 16 AWG (15 mm²) 600 V wire.

Each electrical connection to the light unit must have frangibility. Frangible couplings are provided with the light unit. See [Figure](#) and [Figure](#) for details.

Each conduit entry into the PAPI enclosure should be sealed with duct seal or appropriate methods to prevent moisture from entering the PAPI enclosure.

Figure 18: One Hub Installation

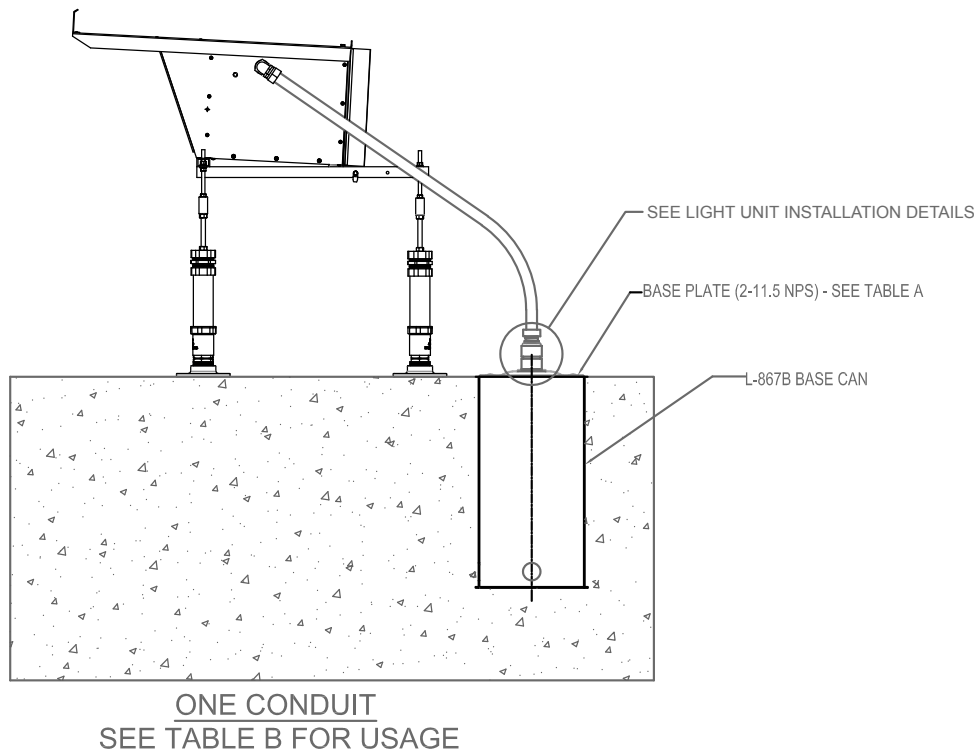
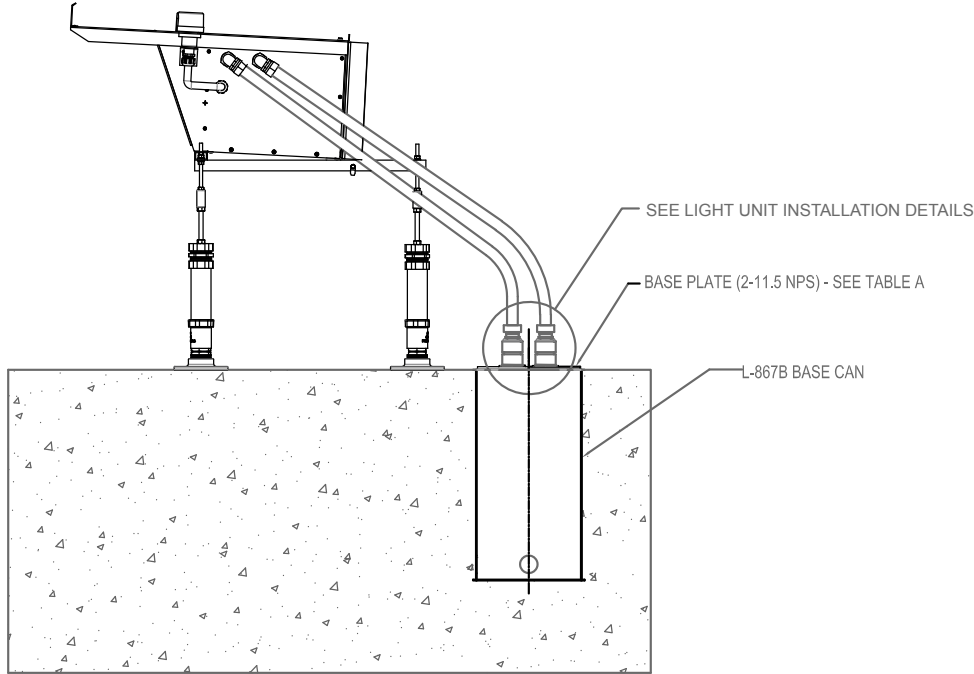


TABLE A - 12" NOM DIA BASE PLATES - SYSTEM REQUIREMENTS					
SYSTEM	QTY	JAQUITH	MILLERBERND	ALE	DESCRIPTION
2 BOX PAPI A	1	AP1932G	1932G	ALE1932G	L-867B BASE PLATE 1/8"TH 1 HUB 2" NPS 12" DIA
	1	AP1832-2G	1832G/2	ALE1832/2	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA
4 BOX PAPI A	1	AP1932G	1932G	ALE1932G	L-867B BASE PLATE 1/8"TH 1 HUB 2" NPS 12" DIA
	3	AP1832-2G	1832G/2	ALE1832G/2	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA
2 BOX PAPI B	2	AP1832-2G	1832G/2	ALE1832G/2	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA
4 BOX PAPI B	2	AP1832-2G	1832G/2	ALE1832G/2	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA
	2	AP1832-3G	1832G/3	N/A	L-867B BASE PLATE 3/8"TH 3 HUB 2" NPS 12" DIA
2 BOX PAPI B REDUNDANT	2	AP1832-2PG	N/A	N/A	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA 1 WYE THRU
4 BOX PAPI B REDUNDANT	2	AP1832-2PG	N/A	N/A	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA 1 WYE THRU
	2	AP1832-3PG	N/A	N/A	L-867B BASE PLATE 3/8"TH 3 HUB 2" NPS 12" DIA 1 WYE THRU
2 BOX PAPI B MONITORED	1	AP1832-2PG	N/A	N/A	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA 1 WYE THRU
	1	AP1832-2G	1832G/2	ALE1832/2	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA
4 BOX PAPI B MONITORED	1	AP1832-2PG	N/A	N/A	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA 1 WYE THRU
	2	AP1832-3G	1832G/3	N/A	L-867B BASE PLATE 3/8"TH 3 HUB 2" NPS 12" DIA
	1	AP1832-2G	1832G/2	ALE1832/2	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA

TABLE B - NUMBER OF CONDUITS				
POSITION	PAPI A 2 BOX	PAPI A 4 BOX	PAPI B 2 BOX	PAPI B & R 4 B
BOX 1	2	2	2	2
BOX 2	1	2	2	3
BOX 3		2		3
BOX 4		1		2

Figure 19: Two Hub Installation



**TWO CONDUITS
SEE TABLE B FOR USAGE**

TABLE A - 12" NOM DIA BASE PLATES - SYSTEM REQUIREMENTS					
SYSTEM	QTY	J AQUITH	MILLERBERND	ALE	DESCRIPTION
2 BOX PAPI A	1	AP1932G	1932G	ALE1932G	L-867B BASE PLATE 1/8"TH 1 HUB 2" NPS 12" DIA
	1	AP1832-2G	1832G/2	ALE1832/2G	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA
4 BOX PAPI A	1	AP1932G	1932G	ALE1932G	L-867B BASE PLATE 1/8"TH 1 HUB 2" NPS 12" DIA
	3	AP1832-2G	1832G/2	ALE1832G/2	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA
2 BOX PAPI B	2	AP1832-2G	1832G/2	ALE1832G/2	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA
4 BOX PAPI B	2	AP1832-2G	1832G/2	ALE1832G/2	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA
	2	AP1832-3G	1832G/3	N/A	L-867B BASE PLATE 3/8"TH 3 HUB 2" NPS 12" DIA
2 BOX PAPI B REDUNDANT	2	AP1832-2PG	N/A	N/A	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA 1 WYE THF
4 BOX PAPI B REDUNDANT	2	AP1832-2PG	N/A	N/A	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA 1 WYE THF
	2	AP1832-3PG	N/A	N/A	L-867B BASE PLATE 3/8"TH 3 HUB 2" NPS 12" DIA 1 WYE THF
2 BOX PAPI B MONITORED	1	AP1832-2PG	N/A	N/A	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA 1 WYE THF
	1	AP1832-2G	1832G/2	ALE1832/2G	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA
4 BOX PAPI B MONITORED	1	AP1832-2PG	N/A	N/A	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA 1 WYE THF
	2	AP1832-3G	1832G/3	N/A	L-867B BASE PLATE 3/8"TH 3 HUB 2" NPS 12" DIA
	1	AP1832-2G	1832G/2	ALE1832/2G	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA

TABLE B - NUMBER OF CONDUITS				
POSITION	PAPI A 2 BOX	PAPI A 4 BOX	PAPI B 2 BOX	PAPI B & R 4 B
BOX 1	2	2	2	2
BOX 2	1	2	2	3
BOX 3		2		3
BOX 4		1		2

DA00026-XXX-01

B

Figure 20: Three Hub Installation

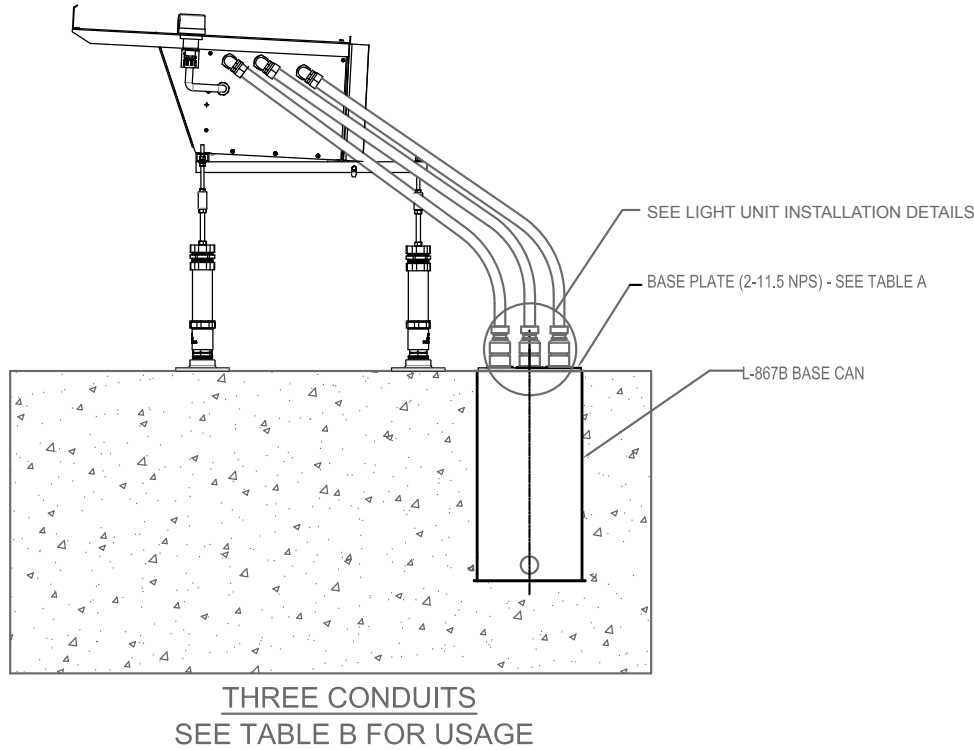


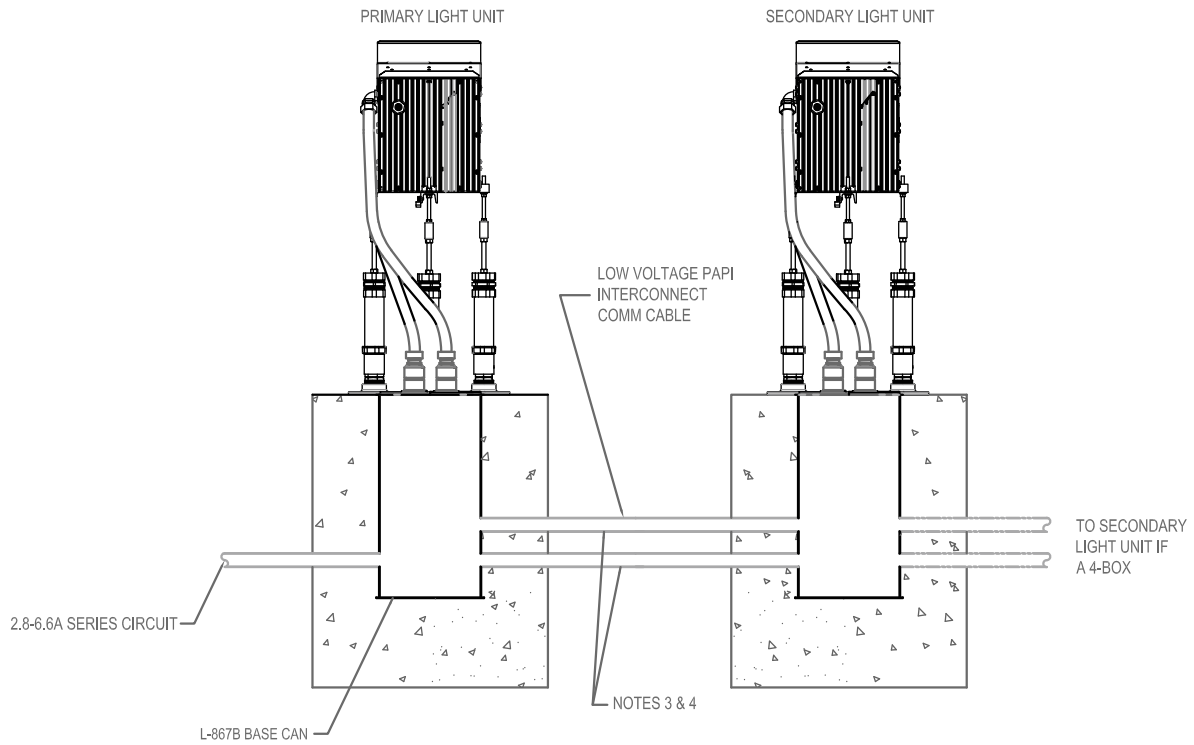
TABLE A - 12" NOM DIA BASE PLATES - SYSTEM REQUIREMENTS					
SYSTEM	QTY	JAQUITH	MILLERBERND	ALE	DESCRIPTION
2 BOX PAPI A	1	AP1932G	1932G	ALE1932G	L-867B BASE PLATE 1/8"TH 1 HUB 2" NPS 12" DIA
	1	AP1832-2G	1832G/2	ALE1832/2R	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA
4 BOX PAPI A	1	AP1932G	1932G	ALE1932G	L-867B BASE PLATE 1/8"TH 1 HUB 2" NPS 12" DIA
	3	AP1832-2G	1832G/2	ALE1832G/2	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA
2 BOX PAPI B	2	AP1832-2G	1832G/2	ALE1832G/2	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA
	2	AP1832-3G	1832G/3	N/A	L-867B BASE PLATE 3/8"TH 3 HUB 2" NPS 12" DIA
4 BOX PAPI B	2	AP1832-2G	1832G/2	ALE1832G/2	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA
	2	AP1832-3G	1832G/3	N/A	L-867B BASE PLATE 3/8"TH 3 HUB 2" NPS 12" DIA
2 BOX PAPI B REDUNDANT	2	AP1832-2PG	N/A	N/A	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA 1 WYE THRU
4 BOX PAPI B REDUNDANT	2	AP1832-2PG	N/A	N/A	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA 1 WYE THRU
	2	AP1832-3PG	N/A	N/A	L-867B BASE PLATE 3/8"TH 3 HUB 2" NPS 12" DIA 1 WYE THRU
2 BOX PAPI B MONITORED	1	AP1832-2PG	N/A	N/A	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA 1 WYE THRU
	1	AP1832-2G	1832G/2	ALE1832/2R	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA
4 BOX PAPI B MONITORED	1	AP1832-2PG	N/A	N/A	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA 1 WYE THRU
	2	AP1832-3G	1832G/3	N/A	L-867B BASE PLATE 3/8"TH 3 HUB 2" NPS 12" DIA
	1	AP1832-2G	1832G/2	ALE1832/2R	L-867B BASE PLATE 3/8"TH 2 HUB 2" NPS 12" DIA

TABLE B - NUMBER OF CONDUITS				
POSITION	PAPI A 2 BOX	PAPI A 4 BOX	PAPI B 2 BOX	PAPI B & R 4 B
BOX 1	2	2	2	2
BOX 2	1	2	2	3
BOX 3		2		3
BOX 4		1		2

DA00026-XXX-01

B

Figure 21: Conduit Installation



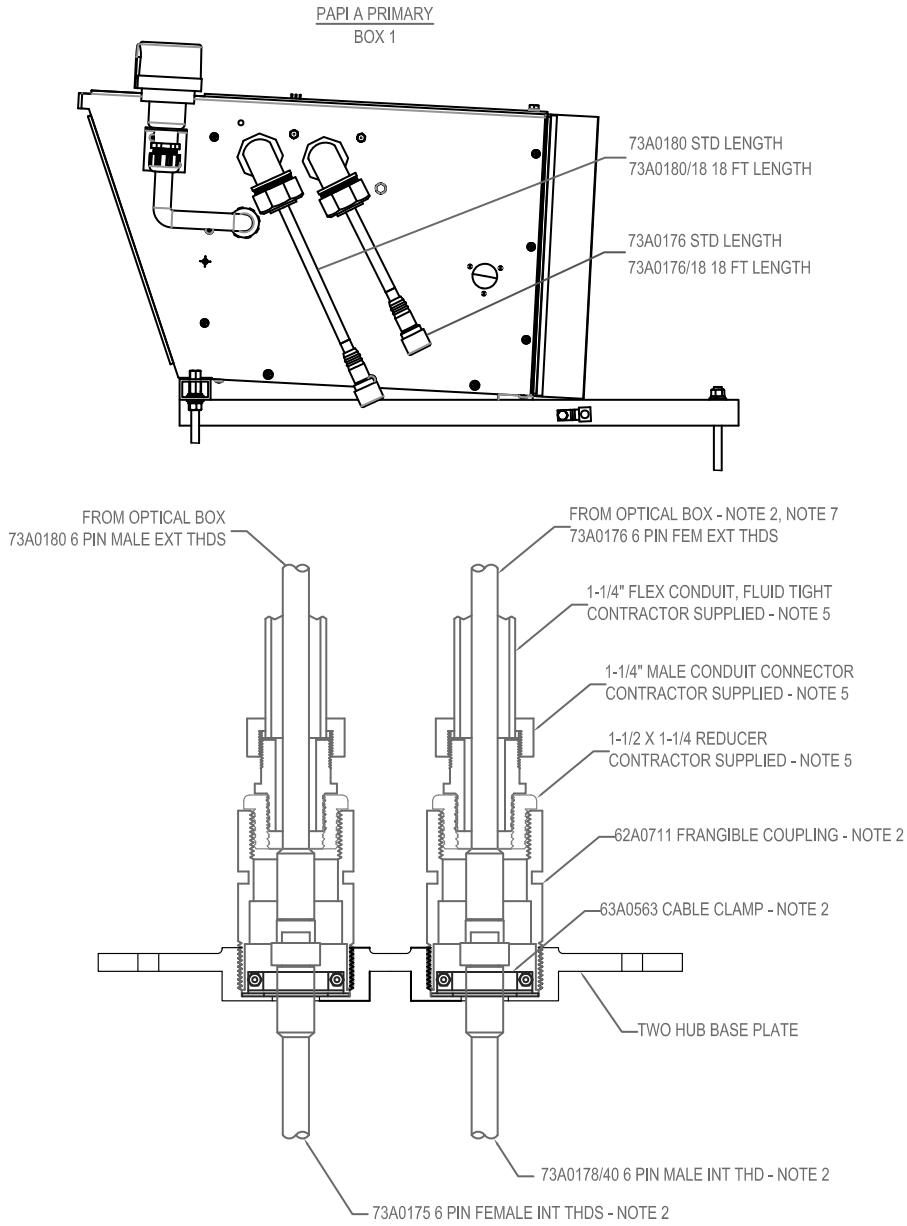
NOTES:

3. FOR SERIES CIRCUIT (TYPE B) APPLICATIONS, HIGH VOLTAGE FIELD CABLES AND LOW VOLTAGE COMMUNICATION CABLES MUST HAVE SEPARATE CONDUIT RUNS. SEE 43A4151 FOR LED PAPI STYLE B EXTERNAL WIRING DIAGRAM.
4. FOR VOLTAGE POWERED (TYPE A) APPLICATIONS, A SEPARATE HIGH VOLTAGE CONDUIT IS NOT REQUIRED.

DA00026-XXX-01

B

Figure 22: PAPI A Primary Light Unit Installation (Box 1)



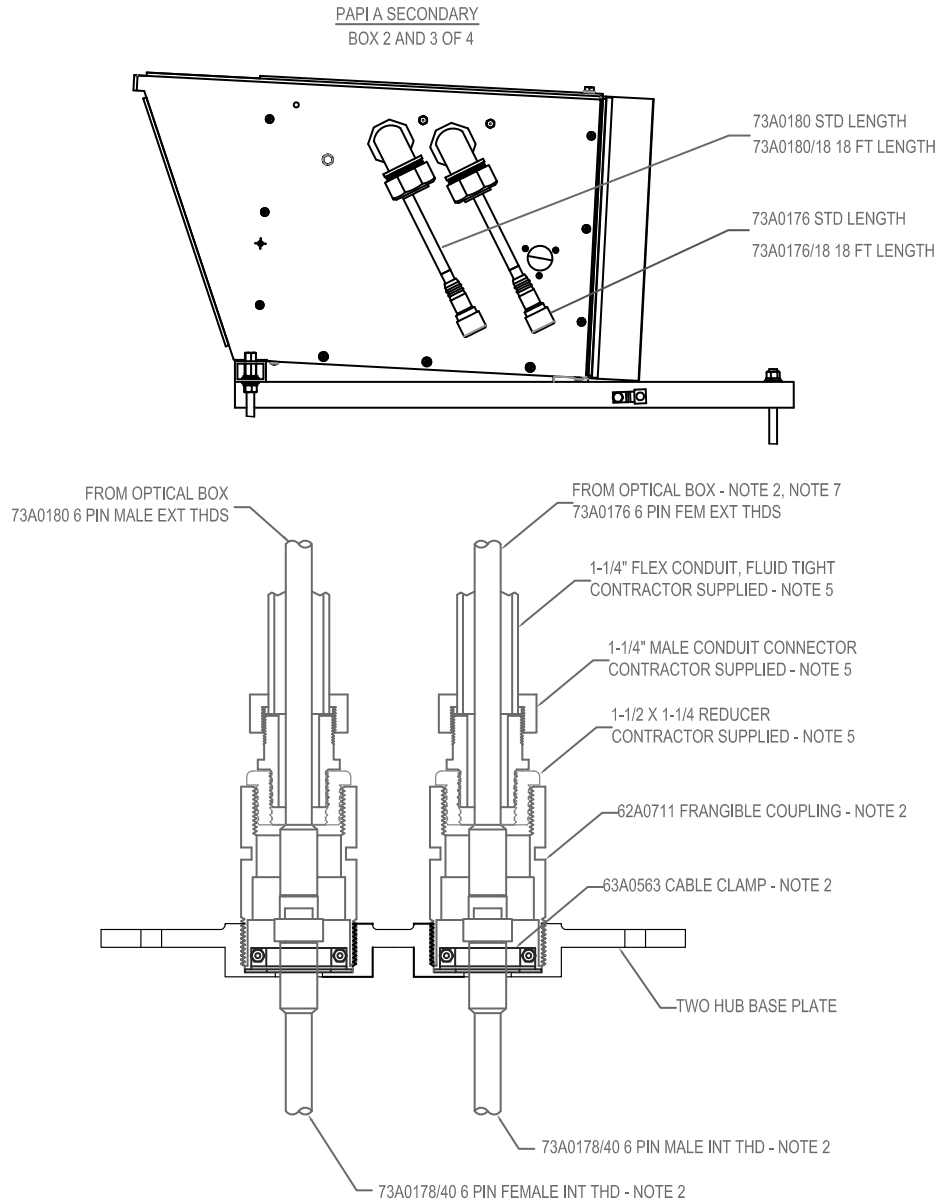
NOTES:

- 2. ITEMS PROVIDED WITH OPTICAL ENCLOSURE.
- 5. ITEMS SPECIFIED AS CONTRACTOR PROVIDED ARE AVAILABLE AS AN OPTION WHEN SPECIFYING THE TOP RPXXXXXXXXXX01 SYSTEM PART NUMBER.
- 7. THE STANDARD CORD LENGTH IS 8 FT LONG WITH 7 FT EXTENDING OUTSIDE THE ENCLOSURE. FOR THE CANADIAN MARKET, OPTIONAL (10 FT LONGER) CORDS ARE AVAILABLE AS AN OPTION WHEN SPECIFYING THE TOP RPXXXXXXXXXX01 SYSTEM PART NUMBER.

DA00026-XXX-01

B

Figure 23: PAPI A Secondary Light Unit Installation (Box 2 and 3 of 4)



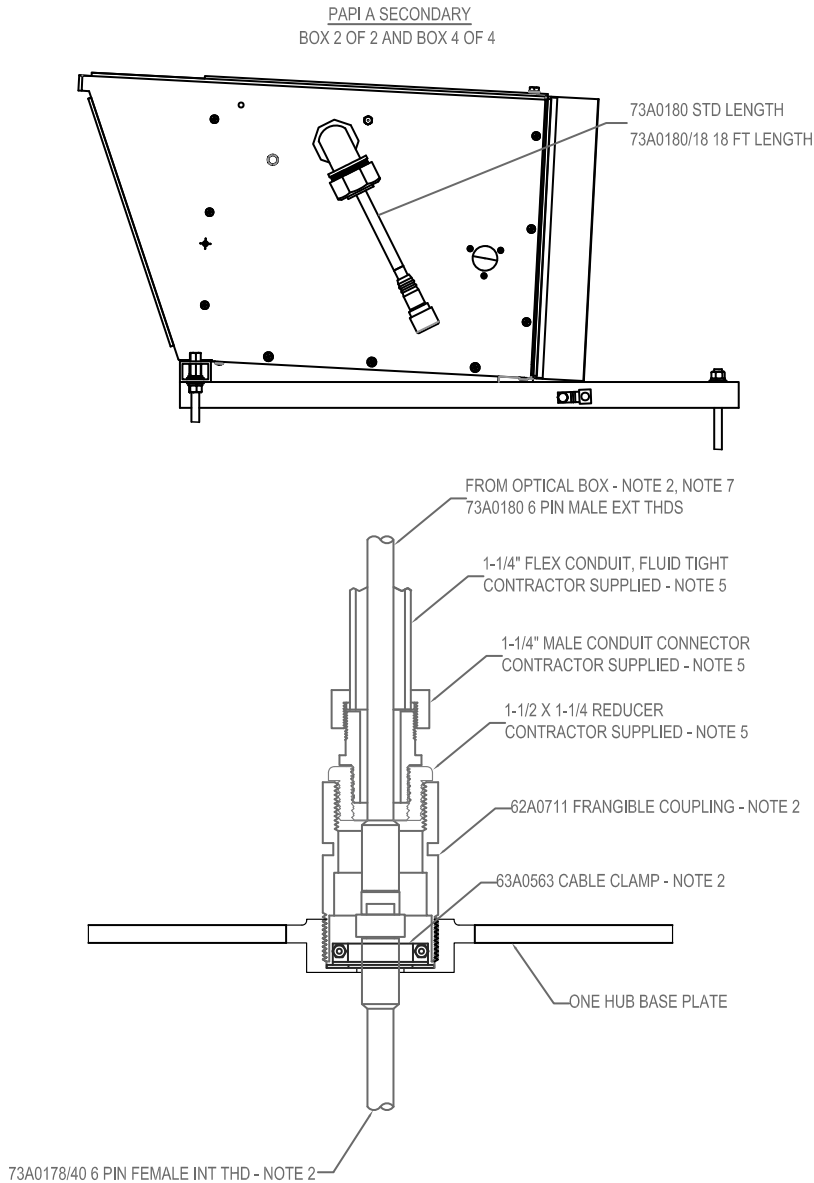
NOTES:

2. ITEMS PROVIDED WITH OPTICAL ENCLOSURE.
5. ITEMS SPECIFIED AS CONTRACTOR PROVIDED ARE AVAILABLE AS AN OPTION WHEN SPECIFYING THE TOP RPXXXXXXXXXX01 SYSTEM PART NUMBER.
7. THE STANDARD CORD LENGTH IS 8 FT LONG WITH 7 FT EXTENDING OUTSIDE THE ENCLOSURE. FOR THE CANADIAN MARKET, OPTIONAL (10 FT LONGER) CORDS ARE AVAILABLE AS AN OPTION WHEN SPECIFYING THE TOP RPXXXXXXXXXX01 SYSTEM PART NUMBER.

DA00026-XXX-01

B

Figure 24: PAPI A Secondary Light Unit Installation (Box 2 of 2 and 4 of 4)



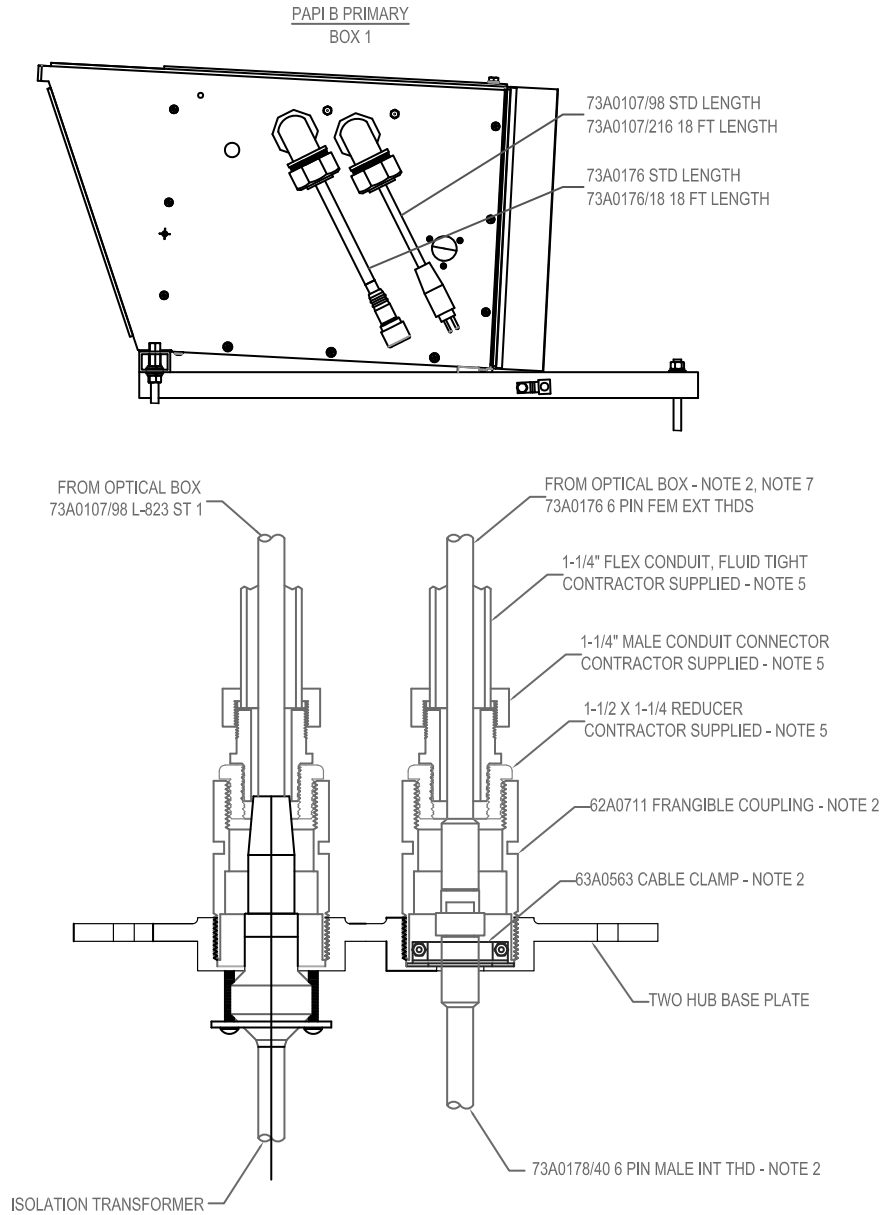
NOTES:

2. ITEMS PROVIDED WITH OPTICAL ENCLOSURE.
5. ITEMS SPECIFIED AS CONTRACTOR PROVIDED ARE AVAILABLE AS AN OPTION WHEN SPECIFYING THE TOP RPXXXXXXXXXX01 SYSTEM PART NUMBER.
7. THE STANDARD CORD LENGTH IS 8 FT LONG WITH 7 FT EXTENDING OUTSIDE THE ENCLOSURE. FOR THE CANADIAN MARKET, OPTIONAL (10 FT LONGER) CORDS ARE AVAILABLE AS AN OPTION WHEN SPECIFYING THE TOP RPXXXXXXXXXX01 SYSTEM PART NUMBER.

DA00026-XXX-01

B

Figure 25: PAPI B Primary Light Unit Installation (Box 1)



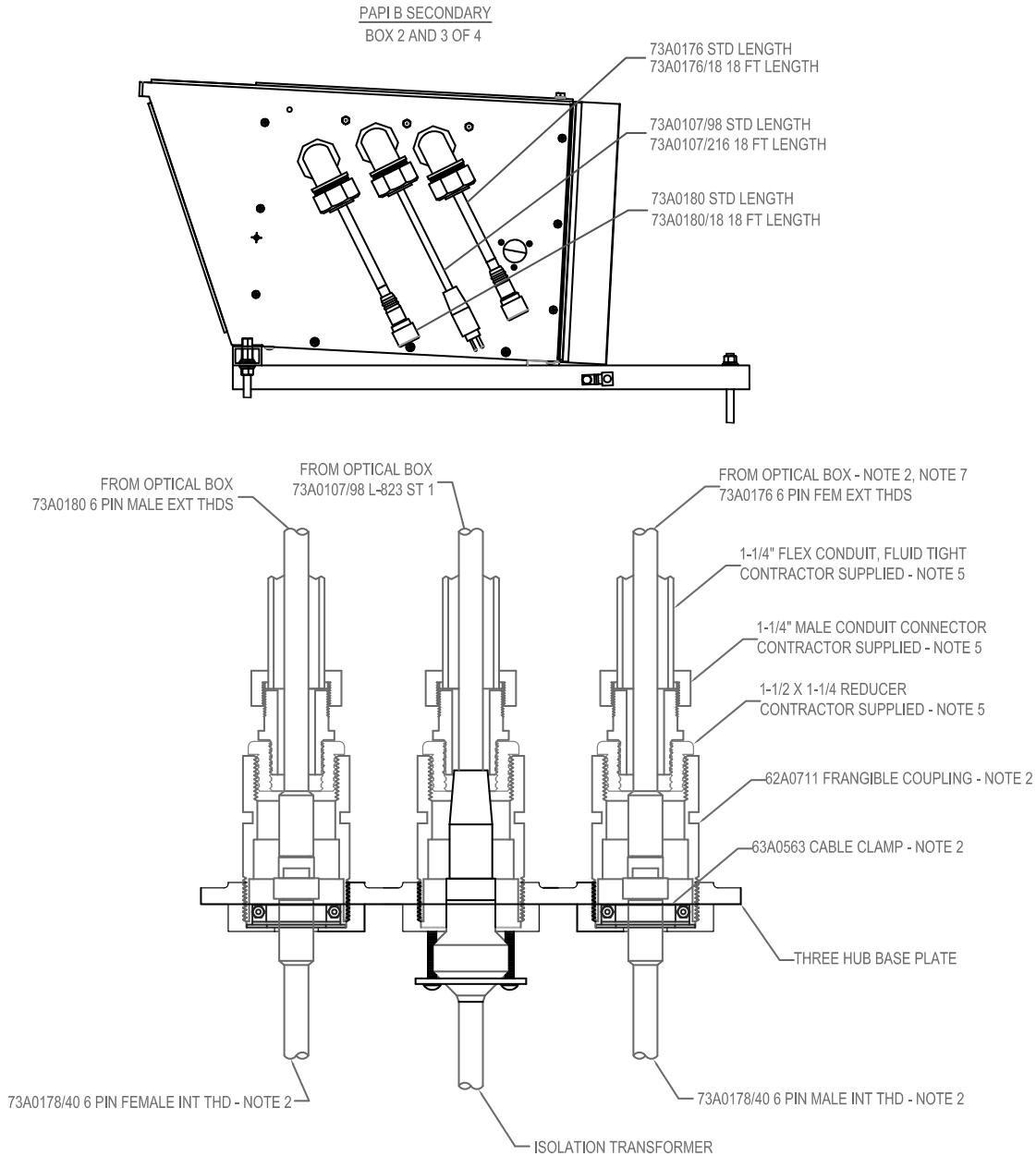
NOTES:

- 2. ITEMS PROVIDED WITH OPTICAL ENCLOSURE.
- 5. ITEMS SPECIFIED AS CONTRACTOR PROVIDED ARE AVAILABLE AS AN OPTION WHEN SPECIFYING THE TOP RPXXXXXXXXXX01 SYSTEM PART NUMBER.
- 7. THE STANDARD CORD LENGTH IS 8 FT LONG WITH 7 FT EXTENDING OUTSIDE THE ENCLOSURE. FOR THE CANADIAN MARKET, OPTIONAL (10 FT LONGER) CORDS ARE AVAILABLE AS AN OPTION WHEN SPECIFYING THE TOP RPXXXXXXXXXX01 SYSTEM PART NUMBER.

DA00026-XXX-01

B

Figure 26: PAPI B Secondary Light Unit Installation (Box 2 and 3 of 4)



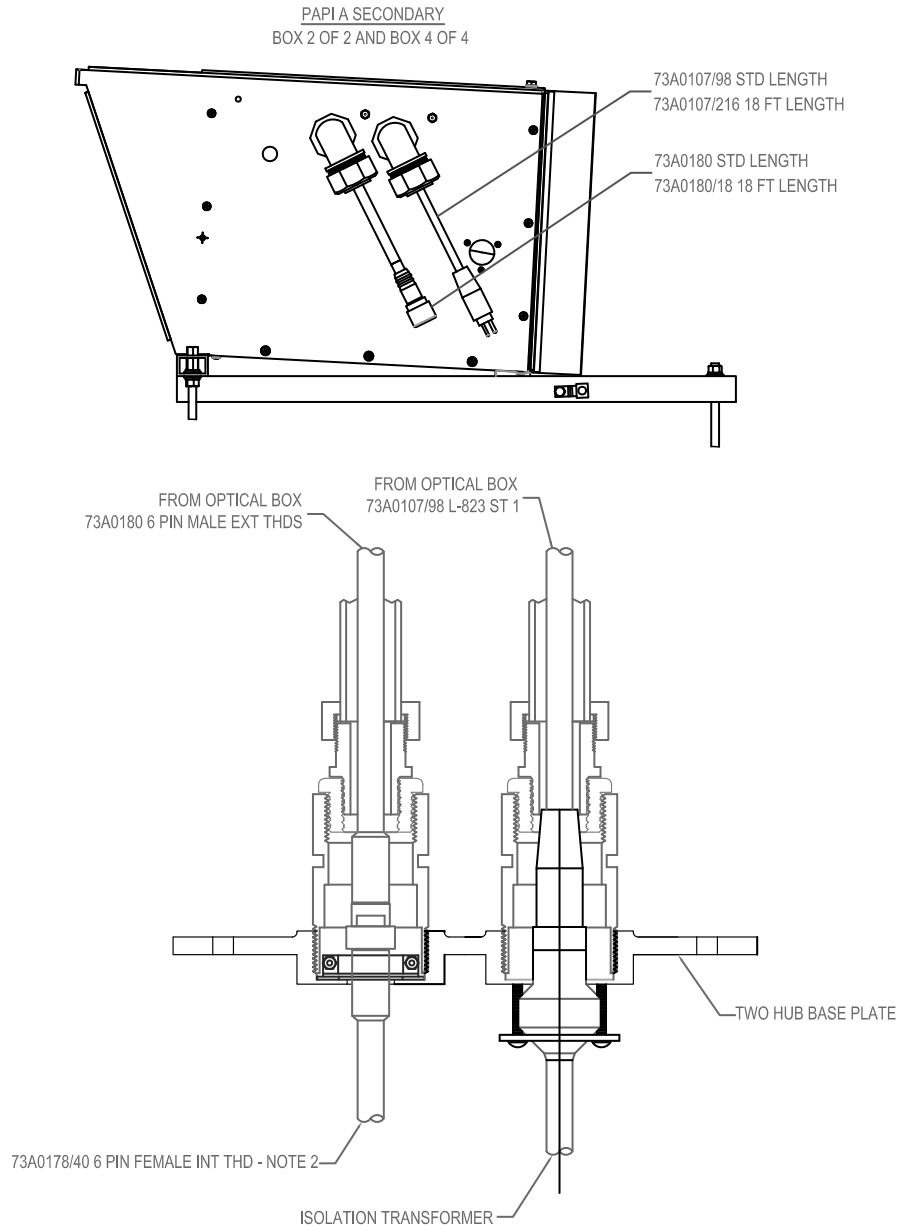
NOTES:

2. ITEMS PROVIDED WITH OPTICAL ENCLOSURE.
5. ITEMS SPECIFIED AS CONTRACTOR PROVIDED ARE AVAILABLE AS AN OPTION WHEN SPECIFYING THE TOP RPXXXXXXXXXX01 SYSTEM PART NUMBER.
7. THE STANDARD CORD LENGTH IS 8 FT LONG WITH 7 FT EXTENDING OUTSIDE THE ENCLOSURE. FOR THE CANADIAN MARKET, OPTIONAL (10 FT LONGER) CORDS ARE AVAILABLE AS AN OPTION WHEN SPECIFYING THE TOP RPXXXXXXXXXX01 SYSTEM PART NUMBER.

DA00026-XXX-01

B

Figure 27: PAPI B Secondary Light Unit Installation (Box 2 of 2 and 4 of 4)



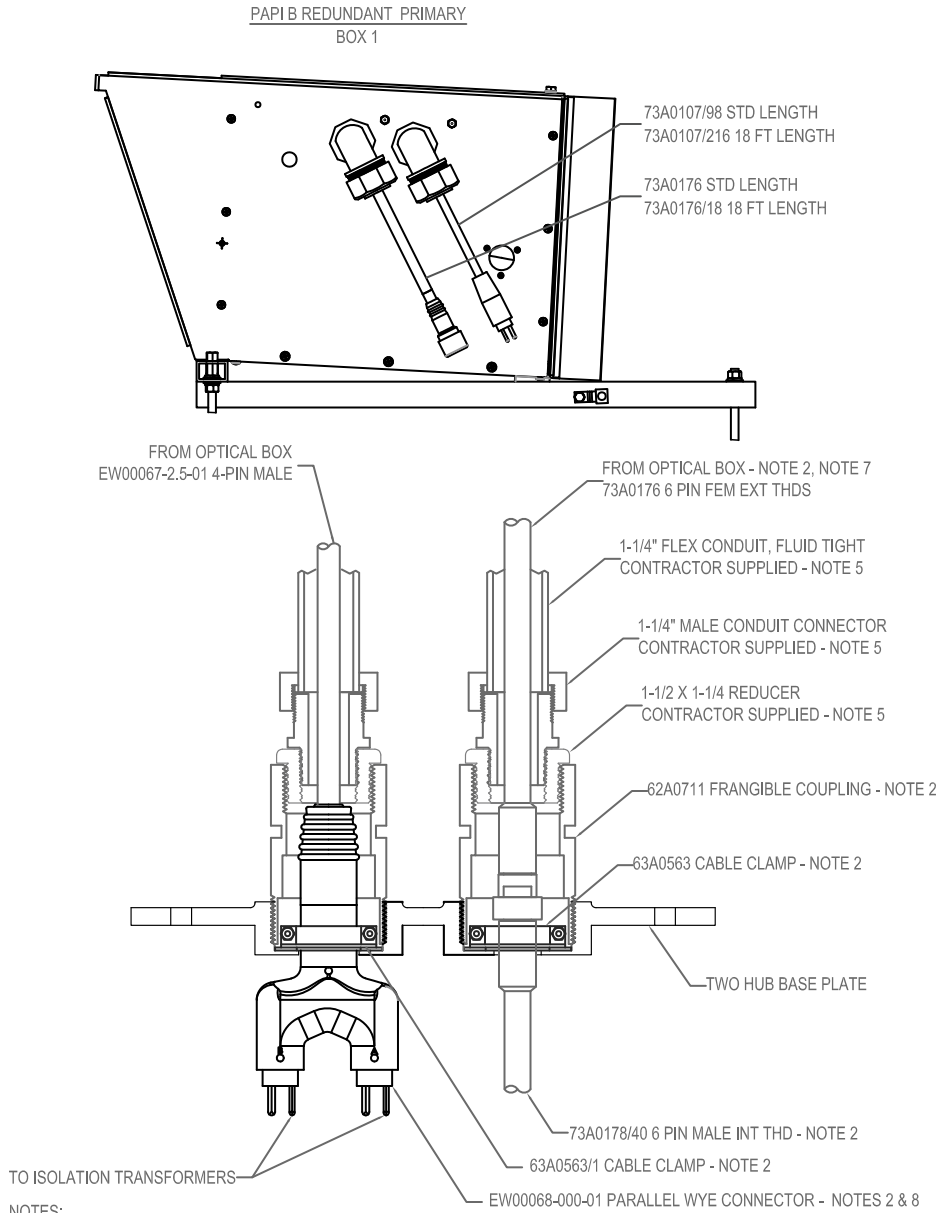
NOTES:

2. ITEMS PROVIDED WITH OPTICAL ENCLOSURE.
5. ITEMS SPECIFIED AS CONTRACTOR PROVIDED ARE AVAILABLE AS AN OPTION WHEN SPECIFYING THE TOP RPXXXXXXXXXX01 SYSTEM PART NUMBER.
7. THE STANDARD CORD LENGTH IS 8 FT LONG WITH 7 FT EXTENDING OUTSIDE THE ENCLOSURE. FOR THE CANADIAN MARKET, OPTIONAL (10 FT LONGER) CORDS ARE AVAILABLE AS AN OPTION WHEN SPECIFYING THE TOP RPXXXXXXXXXX01 SYSTEM PART NUMBER.

DA00026-XXX-01

B

Figure 28: PAPI B Redundant Primary Light Unit Installation (Box 1)

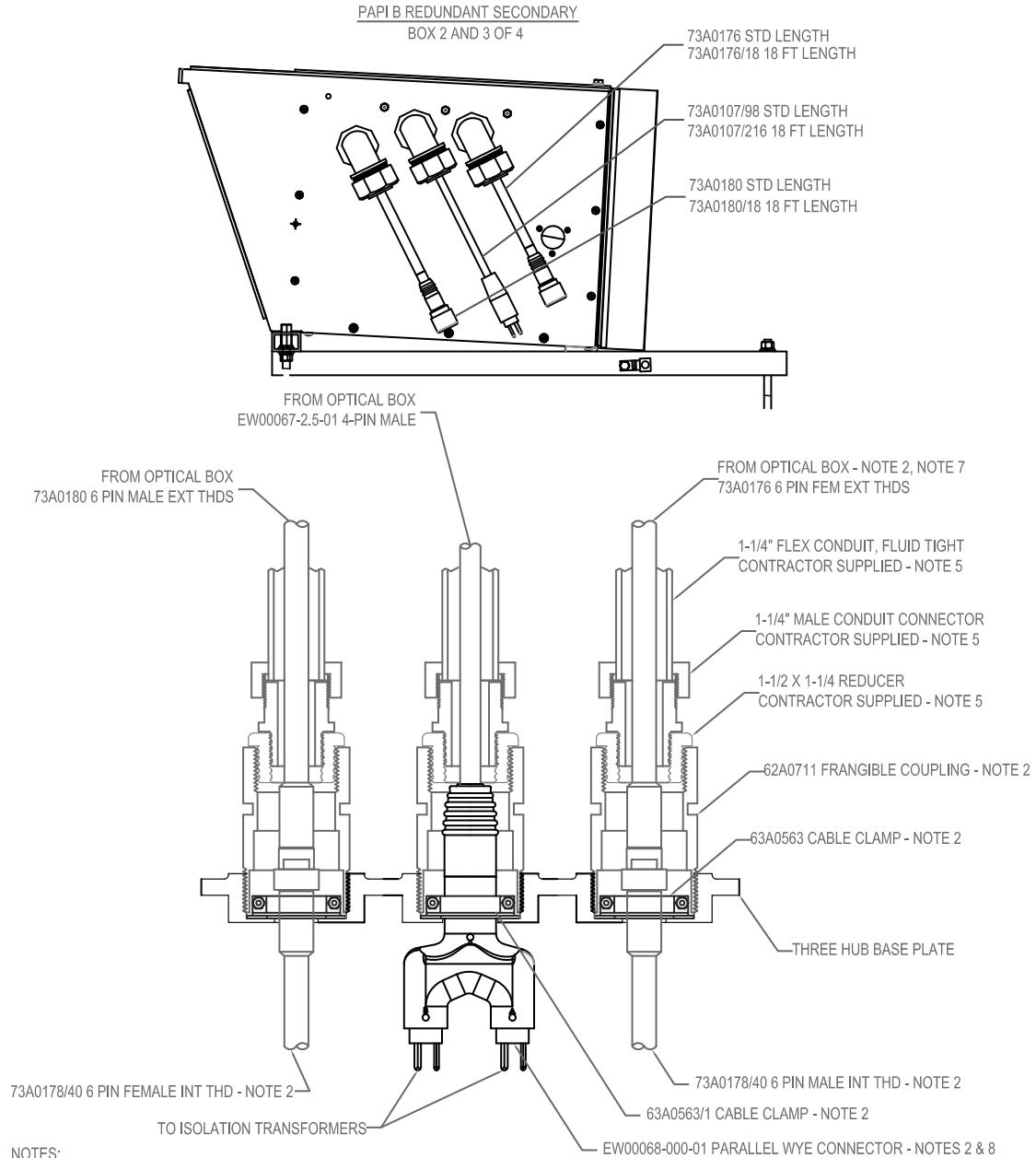


2. ITEMS PROVIDED WITH OPTICAL ENCLOSURE.
5. ITEMS SPECIFIED AS CONTRACTOR PROVIDED ARE AVAILABLE AS AN OPTION WHEN SPECIFYING THE TOP RPXXXXXXXXXX01 SYSTEM PART NUMBER.
7. THE STANDARD CORD LENGTH IS 8 FT LONG WITH 7 FT EXTENDING OUTSIDE THE ENCLOSURE. FOR THE CANADIAN MARKET, OPTIONAL (10 FT LONGER) CORDS ARE AVAILABLE AS AN OPTION WHEN SPECIFYING THE TOP RPXXXXXXXXXX01 SYSTEM PART NUMBER.
8. PAPI B REDUNDANT SYSTEM REQUIRES A 1.25" DIA THRU HOLE TO MOUNT THE EW00068-000-01 PARALLEL WYE CONNECTOR. THE BASE PLATES NOTED IN TABLE A FOR PAPI B REDUNDANT SYSTEMS HAVE THE REQUIRED 1.25" DIA THRU HOLE.

DA00026-XXX-01

B

Figure 29: PAPI B Redundant Secondary Light Unit Installation (Box 2 and 3 of 4)

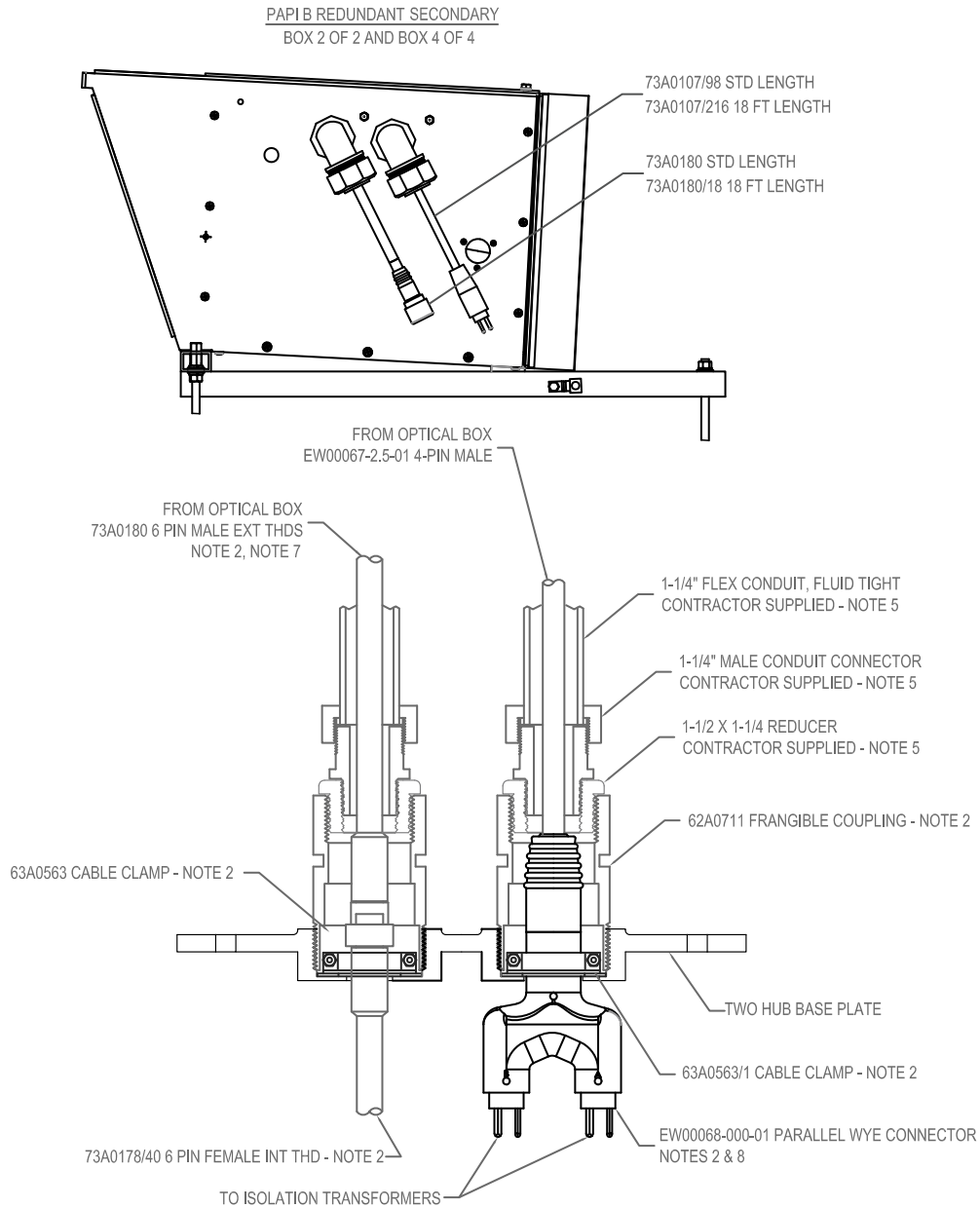


- NOTES:**
2. ITEMS PROVIDED WITH OPTICAL ENCLOSURE.
 5. ITEMS SPECIFIED AS CONTRACTOR PROVIDED ARE AVAILABLE AS AN OPTION WHEN SPECIFYING THE TOP RPXXXXXXXXXX01 SYSTEM PART NUMBER.
 7. THE STANDARD CORD LENGTH IS 8 FT LONG WITH 7 FT EXTENDING OUTSIDE THE ENCLOSURE. FOR THE CANADIAN MARKET, OPTIONAL (10 FT LONGER) CORDS ARE AVAILABLE AS AN OPTION WHEN SPECIFYING THE TOP RPXXXXXXXXXX01 SYSTEM PART NUMBER.
 8. PAPI B REDUNDANT SYSTEM REQUIRES A 1.25" DIA THRU HOLE TO MOUNT THE EW00068-000-01 PARALLEL WYE CONNECTOR. THE BASE PLATES NOTED IN TABLE A FOR PAPI B REDUNDANT SYSTEMS HAVE THE REQUIRED 1.25" DIA THRU HOLE.

DA00026-XXX-01

B

Figure 30: PAPI B Redundant Secondary Light Unit Installation (Box 2 of 2 and 4 of 4)



NOTES:

2. ITEMS PROVIDED WITH OPTICAL ENCLOSURE.
5. ITEMS SPECIFIED AS CONTRACTOR PROVIDED ARE AVAILABLE AS AN OPTION WHEN SPECIFYING THE TOP RPXXXXXXXXXX01 SYSTEM PART NUMBER.
7. THE STANDARD CORD LENGTH IS 8 FT LONG WITH 7 FT EXTENDING OUTSIDE THE ENCLOSURE. FOR THE CANADIAN MARKET, OPTIONAL (10 FT LONGER) CORDS ARE AVAILABLE AS AN OPTION WHEN SPECIFYING THE TOP RPXXXXXXXXXX01 SYSTEM PART NUMBER.
8. PAPI B REDUNDANT SYSTEM REQUIRES A 1.25" DIA THRU HOLE TO MOUNT THE EW00068-000-01 PARALLEL WYE CONNECTOR. THE BASE PLATES NOTED IN TABLE A FOR PAPI B REDUNDANT SYSTEMS HAVE THE REQUIRED 1.25" DIA THRU HOLE.

DA00026-XXX-01

B

Flexible Conduit Installation

Each PAPI light unit is shipped with multi-conductor cable connected to the unit. For installation this cable must be disconnected from the light unit and cut to length and enclosed within liquid-tight conduit (contractor supplied). Follow the procedure to install the flexible conduit.

1. Disconnect the multi-conductor cable from inside of the light unit enclosure.
2. Slide the multi-conductor cable through the liquid tight flexible conduit and the elbow on the Light Unit until the proper length is achieved.
3. Check the flexible conduit to the Light Unit, tightening the fittings securely, if necessary.
4. Cut the multi-conductor cable to the desired length. Remove 8 inches (200 mm) of insulation from the end of the cable. Strip the end of each wire 0.3 inches (8 mm).
5. Re-secure the multi-conductor cable internally with strain-relief ties.
6. Reattach the multi-conductor cable wires to the respective terminal blocks from which they were removed.

5.4.2 Input Power Connections



WARNING

Electric Shock

Before making any wire connections, make sure that you turn off the Constant Current Regulator. Failure to observe this warning may result in personal injury, death, or equipment damage.

Voltage Powered Connections

The RELIANCE LED PAPI will accept both input voltages 240 VAC and 120 VAC $\pm 10\%$. Voltage is supplied to the primary light unit through a dedicated multi-conductor cable.

See [Field Cabling Diagrams](#) section for connecting the source power supply to the multi-conductor cable.

See [Internal Wiring Diagrams](#) section for connecting the multi-conductor cable to the input power board.

Current Powered Connections

One 200 W L-830 (60 Hz) or L-831 (50 Hz) isolation transformer is required to connect the series lighting circuit to each light unit.

See [Field Cabling Diagrams](#) section for connecting the source power supply to the multi-conductor cable.

See [Internal Wiring Diagrams](#) section for connecting the multi-conductor cable to the input power board.

5.5 Aligning and Aiming the LED PAPI

Before aligning or aiming the LED PAPI light units, please thoroughly read [Operation](#) of this manual to familiarize yourself with the digital display and push buttons operation.

On the side of each LED PAPI Light Unit there is a digital LED readout display. This display is used to observe and set the horizontal level and vertical glide angle of each Light Unit. See [Understanding the LED Readout](#) for additional details. The glide angle varies by location, always refer to site-specific documents to determine the correct glide angle to aim each light unit. For standard installation aiming angles refer to [Table 6](#) for L-880(L) PAPI and [Table 7](#) for L-881(L) APAPI.

Table 6: Aiming Angles for L-880(L) PAPI Light Units

L-880(L) PAPI (4 box)	Aiming Angle (Minutes of Arc) (Standard Installation)	Aiming Angle (Minutes of Arc) (Height Group 4 Aircraft on Runway with ILS)
Unit nearest runway	30' (0.50°) above glide path	35' (0.58°) above glide path
Next adjacent unit	10' (0.17°) above glide path	15' (0.25°) above glide path
Next adjacent unit	10' (0.17°) below glide path	15' (0.25°) below glide path
Unit farthest from runway	30' (0.50°) below glide path	35' (0.58°) below glide path

Table 7: Aiming Angles for L-881(L) APAPI Light Units

L-881(L) APAPI (2 box)	Aiming Angle (Minutes of Arc) (Standard Installation)
Unit nearest runway	15' (0.25°) above glide path
Unit farthest from runway	15' (0.25°) below glide path



Note

60 minutes of arc = 1 degree. (60' = 1°)

The PAPI's LED display shows the angle in decimal degrees with one hundredth of a degree resolution (x.xx).

The conversion from minutes to decimal and decimal to minutes is calculated by the following formulas:

$$\text{DECIMAL} = \text{MINUTES} / 60$$

$$\text{MINUTES} = \text{DECIMAL} \times 60$$

Refer to [Table 8](#) to help convert decimal degrees to minutes.

Examples:

If a glide angle of 3°10' is desired, adjust the Light Unit's glide angle to 3.17 on the digital readout.

If a glide angle of 3°15' is desired, adjust the Light Unit's glide angle to 3.25 on the digital readout.



Note

If the readout shows **MIN**, this indicates that the glide slope is negative (PAPI aimed toward the ground). If the readout shows **9.99**, this indicates that the glide slope is equal to or greater than 9.99 degrees from horizon.

Table 8: Conversion Table for Decimal Degrees to Minutes

Decimal Degrees	Minutes	Decimal Degrees	Minutes
0.02	1	0.52	31
0.03	2	0.53	32
0.05	3	0.55	33
0.07	4	0.57	34
0.08	5	0.58	35

Table 8: Conversion Table for Decimal Degrees to Minutes (Continued)

Decimal Degrees	Minutes		Decimal Degrees	Minutes
0.10	6		0.60	36
0.12	7		0.62	37
0.13	8		0.63	38
0.15	9		0.65	39
0.17	10		0.67	40
0.18	11		0.68	41
0.20	12		0.70	42
0.22	13		0.72	43
0.23	14		0.73	44
0.25	15		0.75	45
0.27	16		0.77	46
0.28	17		0.78	47
0.30	18		0.80	48
0.32	19		0.82	49
0.33	20		0.83	50
0.35	21		0.85	51
0.37	22		0.87	52
0.38	23		0.88	53
0.40	24		0.90	54
0.42	25		0.92	55
0.43	26		0.93	56
0.45	27		0.95	57
0.47	28		0.97	58
0.48	29		0.98	59
0.50	30		1.00	60

5.5.1 Adjusting Azimuth Aim (Horizontal Alignment with Runway Centerline)

Make sure that the rod at 164 feet (50 m) from the light unit is still properly aligned with the side of the PAPI-L light unit. If not, loosen the fasteners securing the flanges to the concrete foundation and make adjustments as necessary to align the light unit.

Each Light Unit shall be aimed outward into the approach zone on a line parallel to the runway centerline within a tolerance of $\pm 0.5^\circ$. ADB Safegate recommends azimuth aiming to be within a tolerance of 0° to 0.5° towards centerline.



Note

It is not necessary for the alignment to be absolutely perfect. An error of 20 inches (500 mm) at 164 feet (50 m) yields an error of 0.5° , which is within FAA required tolerance.

5.5.2 Adjusting the Horizontal Level and Setting Rough Elevation Glide Slope Angle

The following instructions require the Light Unit's circuit board to be powered by the system input power. When the PAPI is initially powered on there will be a delay in which the display will show the following sequence;

ADB -> LED -> PAPI -> VER -> V.VV -> GGGG -> BOXn -> OFn -> COLD -> XXX -> SEC

After the initial delay the light engines may come on and then go off and the display will show an error explaining why the unit is in an alarm state.

Referring to [Figure 15](#) and [Figure 16](#) perform the following procedure:

1. Loosen the hex nuts (1) and (2) on all three legs (E), (F), and (G). Hex nuts (3), (4) and (5) should be finger tight.
2. With the unit powered, press the LEVEL button on the display pad to display the horizontal level angle.
3. Level the light unit by adjusting the hex nuts (1) and (2) on the left front leg. The LEVEL angle on the display pad should read $0.00^\circ \pm 0.07^\circ$.
4. Tighten hex nuts (1) and (2) simultaneously.
5. Press the GLIDE button on the display pad to display the elevation level angle (glide slope).
6. Set glide slope by adjusting hex nut (5) of the rear leg (G).
7. Position upper hex nut (1) on leg (G) against the upper flat washer. Simultaneously tighten the hex nuts on leg (G).
8. Tighten lower hex nut (4) on leg (F).

5.5.3 Adjusting Fine Elevation Glide Slope Angle

To adjust the fine elevation settings using the differential for the LED PAPI-L, perform the following procedure:

Figure 31: Elevation Setting Sequence

Elevation Setting Sequence (LED, Three-Leg PAPI-L)

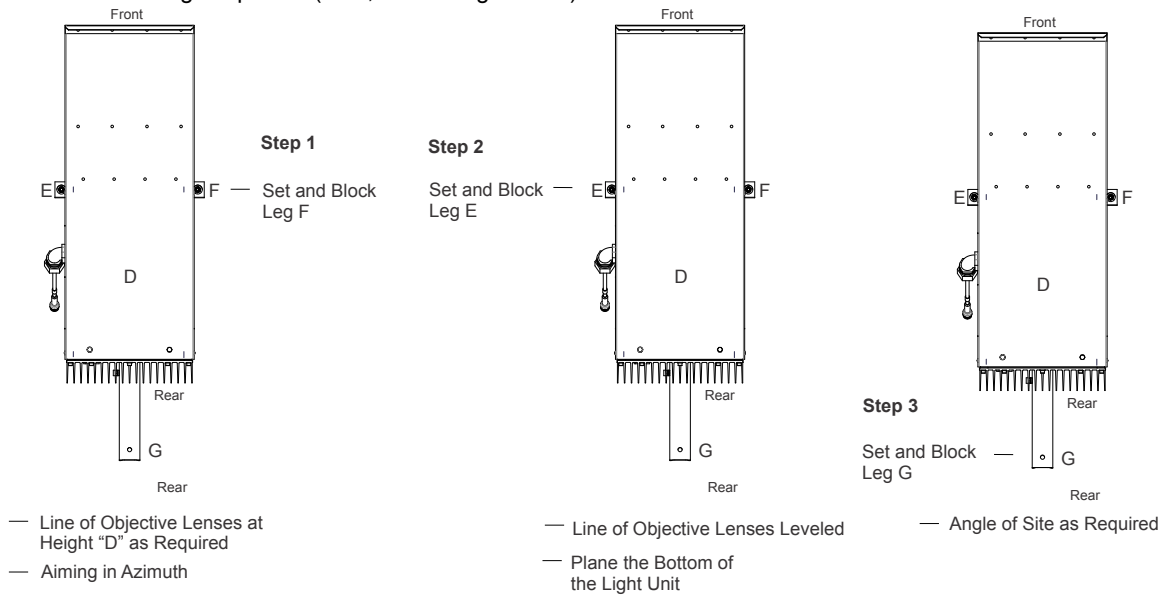
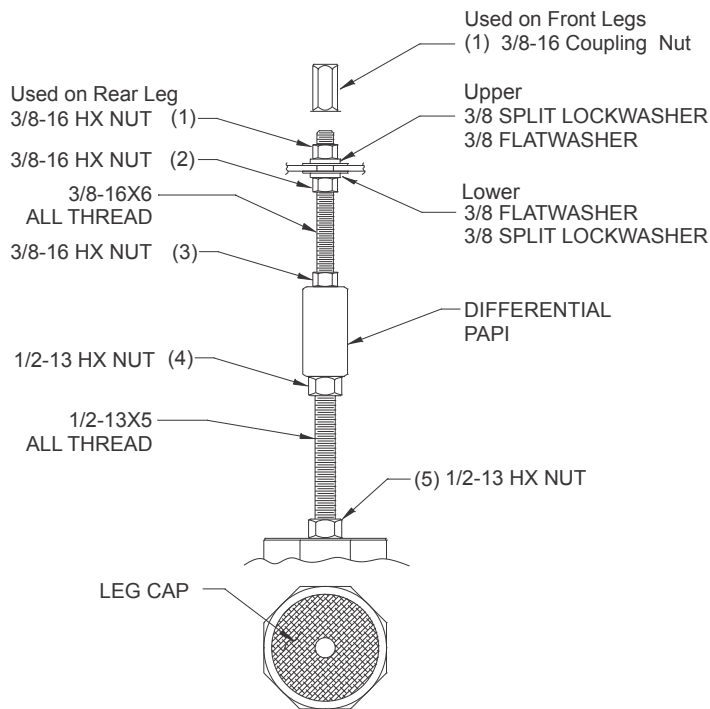


Figure 32: Adjustable Mounting Legs



A4 PAPI LEG ASSY. REF

1. Press the LEVEL button on the display pad to display the horizontal level angle.
2. Refer to [Figure 31](#) STEP 1. Make sure the locking hex nuts (3) and (4) for the differential on the right front leg (F) are tightened. The locking hex nuts (3) and (4) for the differentials on the other legs should remain loose.

3. Refer to [Figure 31](#) STEP 2. While watching the displayed LEVEL angle on the display pad, level the front of the PAPI by turning the differential left front leg (E) in the proper direction. Tighten locking hex nuts (3) and (4) on the differential on left front leg (E) when leveled.
4. Press the GLIDE button on the display pad to display the longitudinal angle (glide slope).
5. Refer to [Figure 31](#) STEP 3. While watching the displayed GLIDE angle on the display pad, adjust the differential on the rear leg (G). When leveling is complete, tighten the locking hex nuts (3) and (4) on legs (E), (G), and (F) and the differential of leg (G). Tighten the hex nuts to a torque of 132 in-lb. (15 n-m) and the GLIDE angle is displayed within ± 0.03 degrees.
6. Check the settings by pressing the LEVEL button to display the horizontal level angle.
If it is incorrect, repeat steps 1 to 5 of this section.
7. When all the readings are correct, continue installation.

5.5.4 Saving the Glide Angle to Memory

1. After all adjustments are complete, press the **SET** push-button for five seconds until **SAVE** is displayed. This stores the current glide angle in memory so that if a Light Unit becomes vertically misaligned, the inclinometer circuitry will disable the Light Unit. The horizontal (Level) angle is hard coded to disable the Light Unit if the unit is tilted more than 1.75 degrees in either direction.
2. Repeat the alignment procedure for each of the Light Units.

6.0 RELIANCE PAPI Ground Check Procedure

This procedure describes the steps to ground-check the light beam angles of the RELIANCE PAPI.

The RELIANCE PAPI incorporates an advanced optics system to create a crisp transition sector at the required evaluation distance of 300 m. However, because of the advanced optics system, the RELIANCE PAPI displays a non-linear wave-shaped pattern at the ground verification distance than that of conventional incandescent-lamp PAPI. The reason for this difference is attributed to the optical effects not producing a fully developed beam until after a distance of about 200 m. The concept of near-field vs. far-field optical effects is important to understand as this complicates the ground alignment procedure and introduces variables in the measurement of the elevation aiming process.

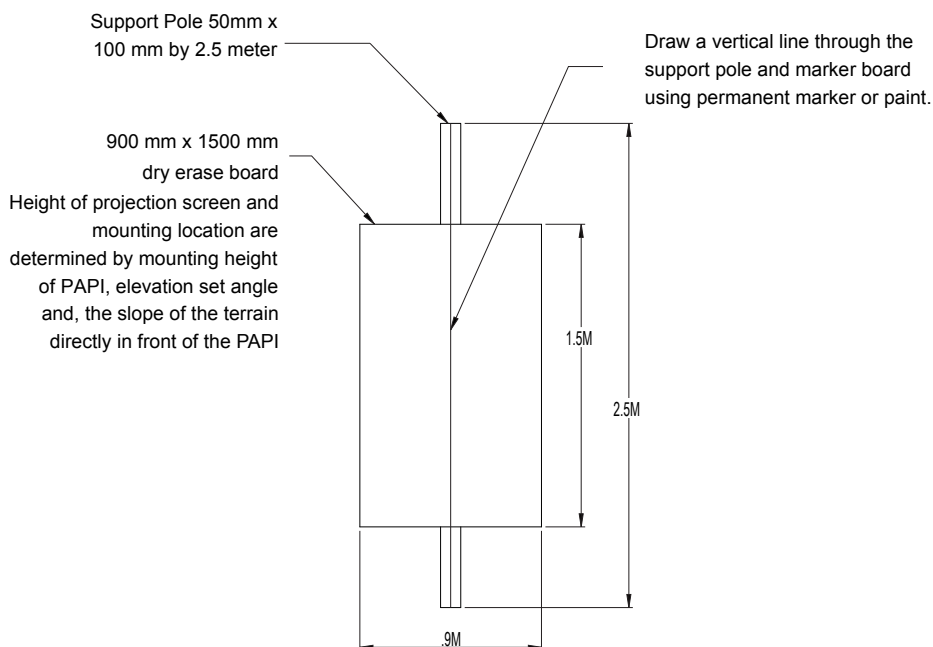
The three largest sources of variability are the measurement of the 18 m distance to target, accuracy of the placement of the laser level line to the cross-hairs of the side of the PAPI, and determine the precise center of the beam between the non-linear areas of the red and white boundaries. All of these introduce uncertainty that must be accounted for. These are the uncertainties that have led to the acceptance criteria of +/- 6 minutes of arc given in [Standards and Tolerances](#) of the LED PAPI manual. This translates to a maximum allowable difference between "H" and "H1" of 31.4 mm during operational ground checks.

6.1 Equipment Needed to Perform a Ground Check

The following equipment is used to perform the ground check (list does not include LED PAPI adjustment tools):

1. Self-Leveling Line Laser, Accuracy +/-0.2 minutes. Ref: Spectra Precision LL300S.
2. Camera Tripod with bubble level and vertical adjustment mechanism
3. Measuring Tape – 20m
4. Steel rule – 30cm
5. Marker, Dry-erase Black.
6. Carpenter's Level (2)
7. Bright Spray Paint (or other method) for marking line in grass.
8. Projection screen or marker board. Recommend dry erase board (0.9m x 1.5m) mounted on a post (50mm x 100mm). See [Figure 33](#).

Figure 33: Projection Screen



6.2 Prior to Performing A Ground Check

1. Set up and aim PAPI light units as described in the section [Aligning and Aiming the LED PAPI](#) to the Site Specific elevation angles required by the Airport.
2. Prepare and fill out columns (2), (3), and (4) of [Table 9](#) (Blank Record of PAPI Changes to Elevation from "H1" to "H"), which will be used throughout this procedure. Rows A and B are populated for 2-box systems and rows A, B, C, and D will be populated for 4-box systems.
 - a. Fill out the required elevation angles in degrees and minutes in column (2) for the installed units.
 - b. Calculate the conversion and fill out the required elevation angles in decimal degrees in column (3) for the installed units.
 - c. Calculate and record dimension "H" in column (4) by using the formula: $H = [\text{distance of observation in mm}] \times \tan[\text{angle in column 3}]$.



Note

Example: 18 m observation distance and an aiming angle of 2.50 degrees, $H = 18000 \times \tan[2.50] = 786$ mm.

Table 9: Blank Table: Record of PAPI Changes to Elevation from "H1" to "H"

Light Unit (1)	Required Elevation Angle in Minutes (2)	Required Elevation Angle in Degrees (3)	Dimension "H" Calculated Millimeters (4)	Dimension "H1" Measured Millimeters (5)	Difference Between H and H1 Millimeters (6)	Adjust Angle (7)	Adjust Up/Down (8)
A							
B							
C							
D							

Table 10: Sample Table: Record of PAPI Changes to Elevation from "H1" to "H"

Light Unit (1)	Required Elevation Angle in Minutes (2)	Required Elevation Angle in Degrees (3)	Dimension "H" Calculated Millimeters (4)	Dimension "H1" Measured Millimeters (5)	Difference Between H and H1 Millimeters (6)	Adjust Angle (7)	Adjust Up/Down (8)
A	2° 30'	2.50	786				
B	2° 50'	2.83	890				
C	3° 10'	3.17	997				
D	3° 30'	3.50	1101				



Note

Sample values shown are an example of for a nominal 3 degree approach glide slope. Actual site specific elevation angles required by the airport must be used.

6.3 Setup and Ground Check Procedure

Setup and Ground Check procedures are to be performed at night.

Figure 34: Ground Check Setup

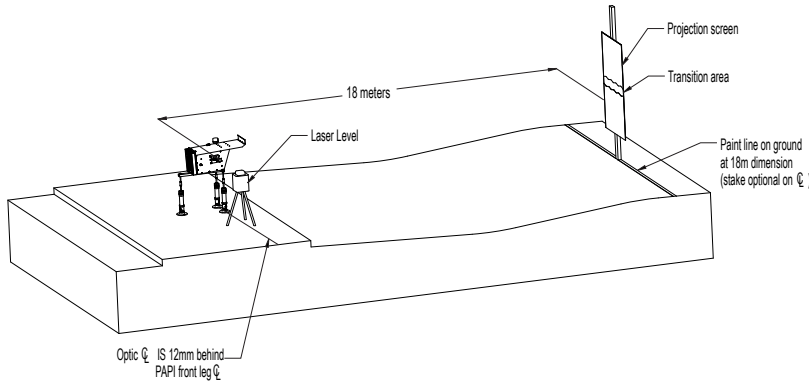


Figure 35: LED PAPI Light Beam Centerline Mark

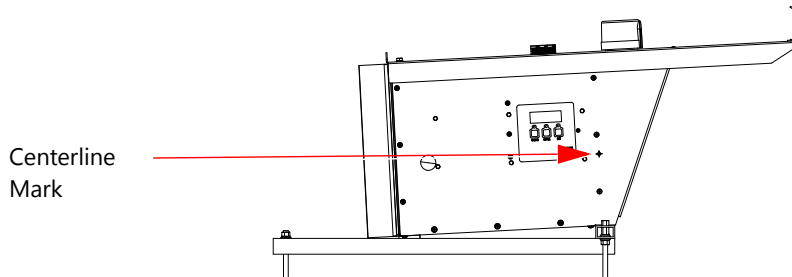


Figure 36: Laser Level



1. Place the laser level adjacent to the touchpad side of the PAPI light unit.
2. Turn on and adjust height of the laser level so the beam intersects the LED PAPI Light Beam Centerline Mark. See [Figure 35](#).



Note

Mount the Self-Leveling Line on the tripod as close to level as possible. Note that a tripod with a bubble level will assist with leveling the laser. The Self-Leveling Laser needs to be mounted within +/- 5 degrees of level for the self-leveling feature to function.

3. Mark the specified observation distance.
 - a. Measure 18 m from the centerline mark on the PAPI side panel along the light path. Note: the centerline mark is 12 mm behind the PAPI leg centerline. Mark the 18m distance with a spray paint line. Optional to install a mounting stake at the CL of the beam on the 18m line.
 - b. This is the location at which the projection screen will be located. The dry erase board can be permanently attached to the support pole by placing the pole at this location and making sure that the beam transition and the laser level indicator are both visible on the dry erase board. This step is necessary due to variations in PAPI mounting height and the slope of the terrain directly in front of the PAPI light units.
4. Place the projection screen on the paint line 18 m in front of the PAPI, see [Figure 34](#). Sight along the side of the PAPI as shown in [Figure 34](#).
5. Lock the vertical movement of the tripod holding the laser level. With the PAPI turned off, mark the projection screen at the location where the laser level crosses the permanent vertical line on the projection screen. See [Transition Boundary Figure 37](#). This will be used as the baseline from which to measure distance "H1".



Note

It is important not to move the marker board once this mark has been made. It is also important that the marker board remain within 3° of and vertical during this process.



Note

Use a carpenter's level to help maintain the vertical position.

Figure 37: Transition Boundary

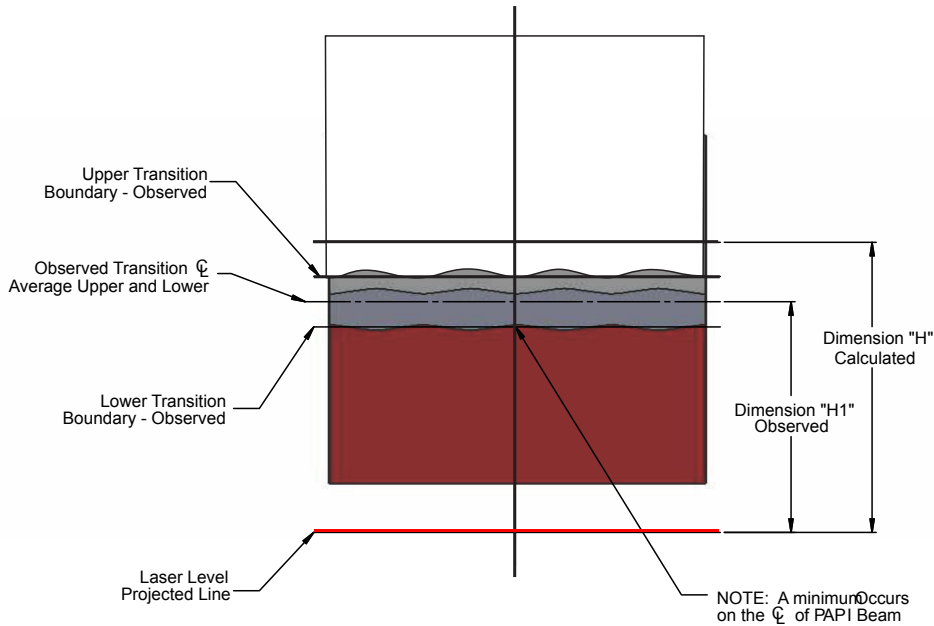
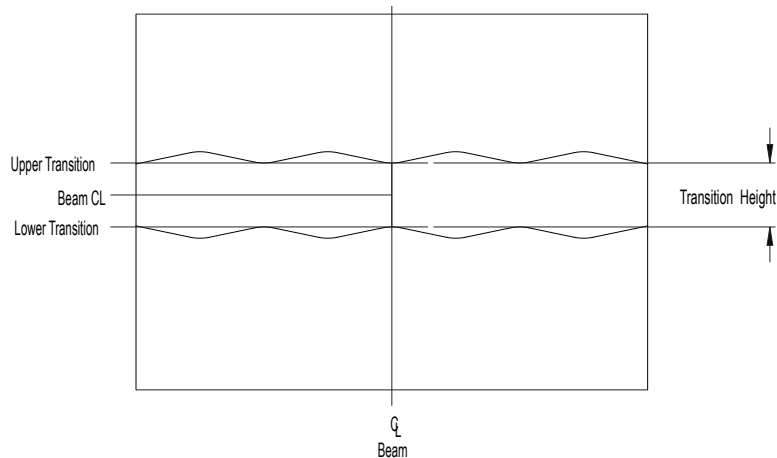


Figure 38: Transition Boundary Explanation

Notes:

1. The upper and lower transitions at 18m distance will appear as wavy lines that produce maximums and minimums. There is always a minimum on the CL of the beam - this is where the measurement is to take place. Exact location of the maximum and minimum is a judgement call, consistency among PAPI units is critical to this procedure.
2. Mark the upper transition at the location where the beam color appears as all white. Mark the lower transition at the location where the beam color appears as all red.
3. Locate and mark the Beam CL. The Beam CL is located mid point of the upper and lower transition marks.



6. Turn on the LED PAPI and adjust the brightness in order to provide the greatest contrast between the red colored area and the dark transition sector. Regulator Step 5 is recommended for the 18 m distance.
7. Determine the upper and lower transition lines and mark these with dry erase markers on the board.



Note

There are peaks and valleys to the transition area – see [Figure 38](#) for additional detail. Center the minimum area found at 0 degrees Level. See [Figure 37](#).

8. Mark the observed transition centerline. It is located mid-way between the upper and lower transition boundaries. See [Figure 37](#).
9. Complete [Table 9](#) by performing the following measurements and calculations.
 - a. Measure the distance between the laser level projected line and the marked beam centerline. Record this value in the "Dimension "H1" Measured" column in [5].
 - b. If "H" and "H1" are not equal, subtract the smaller from the larger value and record this difference in "Difference between H and H1" column [6].

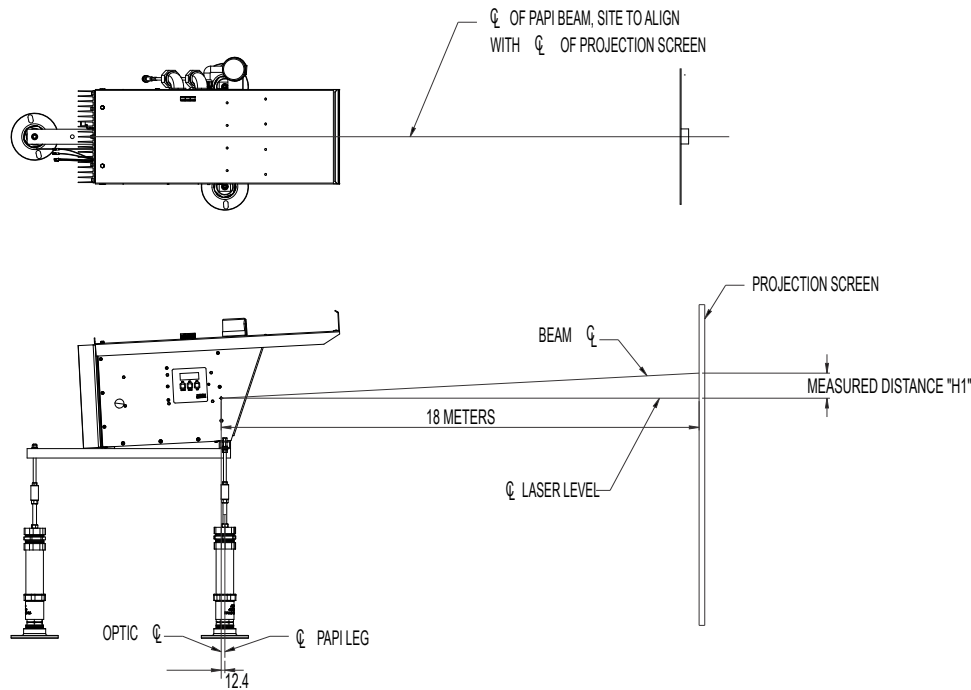
- c. If H1 is greater than H the PAPI is aimed too high, record "Down" in column (8). Then using the formula $ADJUSTMENT\ ANGLE = ARCTAN [(H1-H)/18000]$, calculate the adjustment angle in decimal format and record it in column (7).
 - d. If H1 is less than H the PAPI is aimed too low, record "Up" in column (8). Then using the formula $ADJUSTMENT\ ANGLE = ARCTAN [(H-H1)/18000]$, calculate adjustment angle in decimal format and record it in column (7).
10. Using the inclinometer display, adjust each PAPI up or down by the amount recorded in column (7) of [Table 9](#).
 11. Check PAPI observed transition centerline again to verify that the transition area is now centered at the laser level reference.



Note

There is no adjustment necessary if the calculated difference between H and H1 is less than 10 mm. An adjustment of 10 mm results in an angular change of less than 2 minutes of arc.

Figure 39: Calculate adjustment in the PAPI inclinometer elevation setting



7.0 Operation

This section provides operating information for the PAPI system, including important guidelines for normal operation, preparation for heavy snowfall and criteria for system deactivation.

- For **voltage powered** PAPI systems, follow the steps for initial startup using local control, remote control operation and optional interlock relay in [Initial Startup Using Local Control - Voltage Powered](#) through [Set Up and Test Optional Interlock Relay](#).
- For **current powered** PAPI systems, follow the steps for initial startup discussed in Section [Initial Startup Using Local Control - Voltage Powered](#).

7.1 Operation Safety Considerations



CAUTION

Improper Operation

- Only qualified personnel, physically capable of operating the equipment and with no impairments in their judgment or reaction times, should operate this equipment.
- Read this manual completely before operating the equipment. A thorough understanding of system components and their operation will help you operate the system safely and efficiently.
- Before starting this equipment, check all safety interlocks, fire-detection systems and protective devices such as panels and covers. Make sure all devices are fully functional. Do not operate the system if these devices are not working properly. Do not deactivate or bypass automatic safety interlocks or locked-out electrical disconnects.
- Never operate equipment with a known malfunction.
- Do not attempt to operate or service electrical equipment if standing water is present.
- Use this equipment only in the environments for which it is rated. Do not operate this equipment in humid, flammable or explosive environments unless it has been rated for safe operation in these environments.
- Never touch exposed electrical connections on equipment while the power is ON.

7.1.1 Normal Operation

The PAPI system must operate continuously as long as the runway is in service.

- The **voltage powered** system is controlled by a photocell that automatically sets the system to 100% intensity during daytime and either 5% or 20% intensity at night.
- The **current powered** system operates at any intensity selected by the CCR. It is recommended that a five-step CCR be used to power the Style B PAPI system.

7.1.2 Preparation for Heavy Snowfall

The LED PAPI should operate continuously at normal standby brightness even when the runway is not in use, permitting any snow, ice or condensation to melt and drain off.

If snowfall is expected to bury the Light Units, mark the location of the Light Units with sticks or flags — approximately 7 ft. (2.1m) high — to prevent damage by snow removal equipment.

Should the system show more serious defects, it must be taken out of service.

7.2 Understanding the LED Readout

Figure 40: LED Display



7.2.1 Four-Segment LED

The four-digit LED display indicates the Level (horizontal level), the Glide slope (vertical angle), and additional information regarding unit and system errors.

If GLIDE button is pushed, displays degrees of glide slope (0.00 to 9.99). If LEVEL button is pushed, displays degrees of horizontal level (0.00 to 9.99).

SAVE: Displays after the SET button is held in order to set a new glide angle.

COMM -> LOST: Indicates there is a comm error within the box displaying the error.

HEAT -> FAIL: Indicates there is an error with the defrost heater within the box displaying the error.

RED -> LED -> FAIL: Indicates there is an error with the red LED string within the box displaying the error.

WHT -> LED -> FAIL: Indicates there is an error with the white LED string within the box displaying the error.

PHOT -> FAIL: Indicates there is an error with the photocell (will only be displayed on the voltage powered primary unit).

BOX X -> TILT: Indicates the particularly box in the system that has the tilt error.



Note

(_ -> XXX) = A pause then the time in seconds remaining in the initial power sequence - the delay time where the front glass is being cleared of frost before the PAPI lights up.

It takes 15 seconds for the display to warm up in cold weather.

ICAO PAPI systems do not require tilt/detection shutdown, but may optionally be enabled if desired.

7.2.2 Push Button Functions

The GLIDE, LEVEL and SET push buttons determine the display as follows:

GLIDE

- When the GLIDE push button is pressed the four-digit LED display will show the current glide angle or LOW is the tilt angle is less than 0.00.

LEVEL

- When the level push button is pressed the four-digit LED display shows the horizontal level angle.

SET

- The SET push button stores the **glide angle** that defines proper vertical alignment for the PAPI Light Unit. If any PAPI Light Unit is raised more than $\frac{1}{2}$ degree or lowered more than $\frac{1}{4}$ degree from this angle, the inclinometer circuitry will de-energize all PAPI Light Unit lamps, if TILT is enabled.
- Push and hold the SET push button for about 5 seconds until SAVE is displayed on the four-digit LED display for the Control Board to memorize the glide angle.

7.3 Initial Startup Using Local Control - Voltage Powered

To turn ON the voltage powered RELIANCE PAPI system using local control:

1. Turn the external ON/OFF switch on the primary unit to the OFF position and circuit breaker CB1 to OFF and set DIP SW3-1 to ON, the unit will read this input and translate it to mean it is in local mode operation.
2. Select the desired intensity for nighttime operation by switching DIP SW3-2 ON for 5% and OFF for 20%.
3. Ensure that all light units are aligned properly and that the glide angle settings are memorized in each unit. See [Aligning and Aiming the LED PAPI](#) for the Light Unit setting procedure.
4. Turn CB1 to on in the primary Unit.
5. Switch the external ON/OFF switch on the primary unit to the ON position. The system should energize and all lamps should turn on after the initial countdown.

7.4 Set Up and Test Remote Control Operation

To set up and test remote control operation:

1. Turn the external ON/OFF switch on the primary unit to the OFF position and circuit breaker CB1 to OFF.
2. Set DIP SW3-1 to OFF for remote operation and connect remote control wiring to Terminals 3 & 4 on the DIN rail (The remote control should be shorted for initial testing). Disconnect the photocell.
3. Turn CB1 to on in the primary Unit.
4. Switch the external ON/OFF switch on the primary unit to the ON position. The system should energize and all lamps should turn on after the initial countdown.
5. Open the remote control connection that is connected to terminals 3 & 4 on the DIN rail. The light output should go OFF.
6. Short the remote control connection that is connected to terminals 3 & 4 on the DIN rail. The light output should come back ON.
7. The PAPI system is now ready for operation, the lights are turned on and off via the remote switch that was wired in.

7.5 Set Up and Test Optional Interlock Relay

To set up and test the operation of the interlock relay:

Note Before verifying this operation insure the unit is wired for the optional interlock relay as described in [Optional Interlock Relay](#).

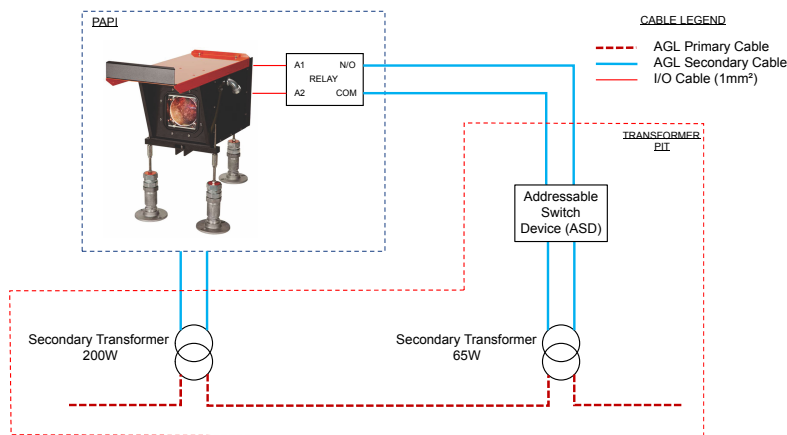
1. Turn the external ON/OFF switch on the primary unit to the OFF position and circuit breaker CB1 to OFF.
2. Ensure that the primary of a low-wattage isolation transformer is connected to the series circuit. Ensure that the secondary is connected to Terminals 3 & 4 on the DIN rail. A 6.6A secondary, 30/45W isolation transformer is typically used. However, a 10/15W or 20/25W isolation transformer may be used.
3. Set DIP SW3-1 to OFF for remote operation.
4. Cover the photocell to simulate the nighttime operation.
5. Turn CB1 to on in the primary Unit.
6. Switch the external ON/OFF switch on the primary unit to the ON position. The unit should remain OFF.
7. Turn on the CCR that controls the interlock relay. The unit should turn on and all PAPI Light Unit lamps should illuminate to the 5% or 20% intensity level as selected using DIP SW3-2.
8. Turn off the CCR. All light units should turn off.
9. Turn the external ON/OFF switch on the primary unit to the OFF position and circuit breaker CB1 to OFF.

7.6 Understanding the Fail-Open Monitoring Feature

The Monitored Fail-Open ordering option is for ILCMS installations and required an external remote for fail-open monitoring. Requires use of a remote monitor and a separate 65 W auxiliary isolation transformer for the primary light unit only. The Monitored Fail-Open feature is only available with the PAPI B Current Powered Non-Redundant systems. Compatible with ADB Safegate and other remote monitoring systems. This ordering option does not provide CCR monitoring functionality.

NOTICE The optional Fail-Open feature is provided with the light unit when specified (see ordering codes). Available with the Current-Powered non-redundant system only. Installed on the primary light unit only.

Figure 41: Fail-Open Monitoring System Layout (Primary Light Unit Only)

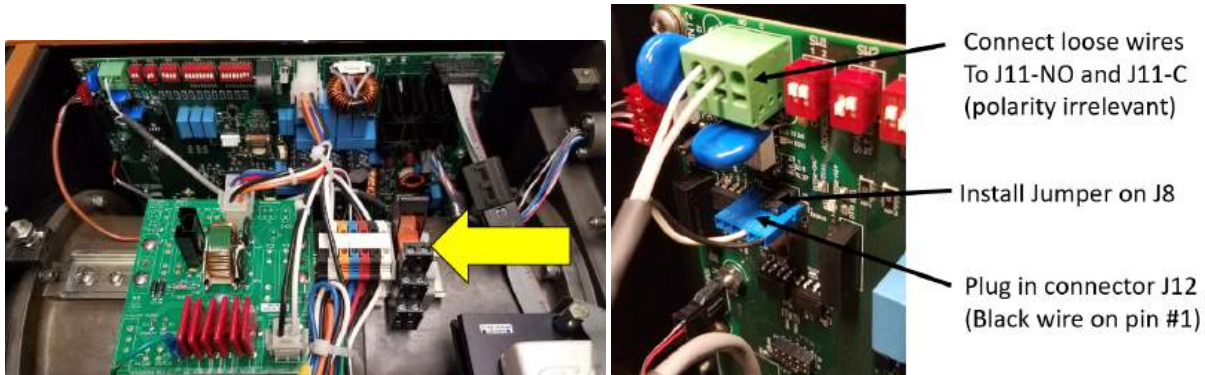


During normal operation of the LED PAPI, the fail-open relay is closed. In the event of a failure or alarm condition of the LED PAPI, the Control Board will trigger the fail-open relay to open allowing a remote monitoring system to identify a fail-open circuit type failure.

LED PAPI Alarm conditions that will result in a fail-open condition include: Heater failure, Red LED failure, White LED failure, Tilt failure (if enabled), or Comm failure (if enabled). a Photocell failure will not trigger a fail-open condition. All failure modes will indicate failure type on the digital display.

The fail-open relay is DIN rail mounted along side of the terminal block of the Input Power PCB of the primary light unit only (see Wiring Diagrams).

Figure 42: Fail-Open Relay



7.7 Set Up the Alarm Contact on the Control Board (for Systems without Fail-Open Monitoring)

Maximum capacity for the alarm contact is 48V@1A or 230V@2A.

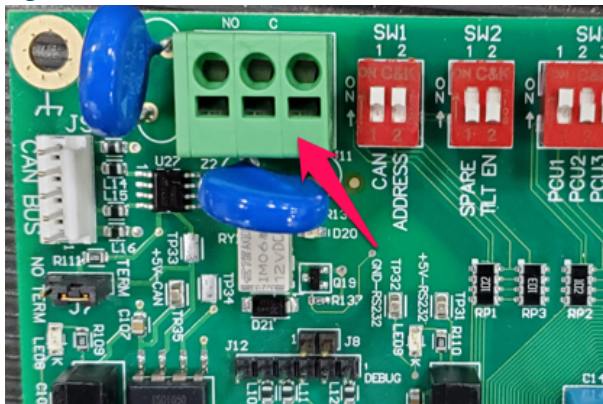
To set up the Alarm contact, follow these steps:



Note

Remote monitoring point can be added to an LED PAPI light unit (primary light unit only or one per light unit). The contacts are normally open (N.O.) and are closed during normal operation when the PAPI is on. A failure will open the relay of the failed light unit and communicate a failure condition to the primary light unit (if COMM is enabled).

Figure 43: Alarm Contact on the Control Board



1. Disconnect power from the PAPI-L.
2. Connect the wires to the Alarm Contacts 1 (NO) and 2 (C). If connecting all the units, the circuit will be in series.
3. Inset a small flathead screwdriver into the rectangular slot to open the circular opening to inset the wire into. Check that the wires hold when lightly toggled on.



CAUTION

If there is risk of external wires being pulled out of the PAPI, do not connect the incoming alarm wire directly to the PCB. Anchor a connector or terminal strip to the frame or side of the PAPI-L to allow strain relief and frangibility if the external wire gets caught on something and pulled out of the PAPI-L unit.



Note

A failure will open the circuit and all PAPI-L units in the circuit will show an alarm. To isolate the alarm cause, close the circuit inside each PAPI-L unit until the alarms clear on the other units.

7.8 Initial Startup of the Current Powered System

Each Light Unit is energized following an initial delay to clear the front glass when the constant current regulator (CCR) is activated, assuming that no Light Unit is in a tilt situation.

7.8.1 Check Light Unit Alignment

Ensure that all Light Units are aligned properly and that the glide angle settings are memorized in each Light Unit. See [Aligning and Aiming the LED PAPI](#) for the Light Unit setting procedure.

7.8.2 Verify Correct Input Current in Each Light Unit

Verify that the input current from the series circuit is correct in each of the Light Units.

To check this, perform these steps for each Light Unit:

- Turn the CCR OFF.
- Remove the lid from the Light Unit closest to the input side of the series circuit.
- Connect a true RMS amp meter current clamp around one of the wires connected to terminal 1 or 2 on the DIN rail.
- Turn the CCR ON to the lowest step (2.8A for a five-step CCR or 4.8A for a three-step CCR).
Verify that the current is correct.
- Verify that the current is correct in each of the remaining current steps.
Troubleshoot or repair the external wiring if the current is incorrect.

7.9 Commissioning the PAPI System

After the PAPI system setup is complete, perform a flight check prior to commissioning the system, if required.

8.0 Maintenance

This section provides maintenance information and procedures for L-880(L)/PAPI (4-box) and L-881(L)/APAPI (2-box) systems.

8.1 Maintenance and Repair Safety Considerations



CAUTION

Electric Shock

- Allow only qualified personnel to perform maintenance, troubleshooting and repair tasks. Only persons who are properly trained and familiar with
- ADB SAFEGATE equipment are permitted to service this equipment.
- Always use safety devices when working on this equipment.
- Follow the maintenance procedures recommended in equipment manuals.
- Do not service or adjust any equipment unless another person trained in First Aid and CPR is present.
- Connect all disconnected equipment ground cables and wires after servicing equipment. Ground all conductive equipment.
- Use only approved ADB SAFEGATE replacement parts. Using unapproved parts or making unapproved modifications to equipment may void agency approvals and create safety hazards.
- Check CCR interlock systems periodically to ensure their effectiveness.
- Do not attempt to service electrical equipment if standing water is present. Use caution when servicing electrical equipment in a high-humidity environment.
- Use tools with insulated handles when working with electrical equipment.
- Also review and follow safety guidelines in FAA AC 150/5340-26 (current edition), Maintenance of Airport Visual Aid Facilities.

8.2 Maintenance Schedule

To keep the PAPI system operating efficiently, follow the preventive maintenance schedule in [Table 11](#).

Table 11: LED PAPI Periodic Maintenance Schedule

Interval	Maintenance Task	Action
After installation and before operational use	Make flight check of system.	Readjust if needed.
After installation (first few weeks)	Check elevation angle glide slope of Light Units.	Readjust if needed. Refer to Additional Siting Considerations for Light Unit alignment. To independently check the elevation aiming angle, refer to Siting Considerations
Daily	If Light Units are not operated continuously, check for frost or dew on the outer lens.	Remove frost or dew and check airport lighting circuitry per CertAlert 02-08
	Visually check LEDs for operation.	Repair or replace any damaged components.

Table 11: LED PAPI Periodic Maintenance Schedule (Continued)

Interval	Maintenance Task	Action
Monthly	Check for any apparent damage to any Light Unit.	Repair or replace any damaged components.
	Check for water damage or insect infestation.	Remove insect infestation (if present). Repair or replace any damaged components.
	Check for presence of rodents.	Remove rodents (if present). Repair or replace any damaged components
	Check all control equipment for proper operation - including photocell for voltage powered systems.	Repair or replace any damaged components.
	Clean the outer surface of the front glass.	Use a soft cotton cloth moistened with alcohol.
	Check the glide slope and alignment angle of each Light Unit.	Use the onboard digital display. Refer to Standards and Tolerances and readjust if necessary.
	Check level and operation of tilt switch.	Repair or replace any damaged components.
	Inspect housing, LEDs, electrical connections, filters and front glass for damage, breakage or a warped shape.	Repair or replace any damaged components..
	Clean the interior of the housing.	Remove any foreign matter. Also check for water damage, insect infestation and presence of rodents.
	Make sure mounting is rigid and sturdy.	Tighten any loose hardware, nuts, screws, etc. Realign the Light Unit if hardware has loosened.
	Make sure no vegetation obscures the light beams.	Remove vegetation. Use weed killer to prevent any regrowth
	Check whether the lightning arresters and/or surge suppressors are scorched or show other signs of failure. Also check after electrical storms.	Replace as necessary.
	Record output current and input voltage of adapter (if used).	Repair or replace equipment if input is abnormal.
	Check Humidity Indicating Plug. A lavender (pink/purple) color indicates a presence of humidity in the optical chamber.	If humidity plug indicates 20% or more, a seal may be compromised. Inspect the front glass seal and the rear LED heat-sink assembly seal for damage. Replace components as necessary.
Quarterly	Check the obstacle-free approach plane for clearance from tree growth, new towers, pole lines or other obstacles. The obstacle-free plane is four miles long and extends 10 degrees on either side of the runway centerline.	Remove obstacles as necessary.
Semiannually	Check the insulation resistance of underground cables and record the results.	Remove obstacles as necessary.
	Check the resistance of the grounding system and record the results.	Remove obstacles as necessary.

8.3 Standards and Tolerances

FAA Standards and Tolerances for Precision Approach Path Indicator (PAPI)

The standards and tolerances noted in the table are specified by FAA Advisory Circular AC 150/5340-26C as a guideline to follow when performing a new installation or scheduled maintenance/inspections on an existing PAPI system. Current revisions of AC 150/5340-26 and/or applicable local standards and tolerances should always be observed.

Table 12: FAA Standards and Tolerances for Precision Approach Path Indicator (PAPI)

Parameter	Standard	Tolerance / Limit	
		Initial ^{1 2}	Operating ^{2 3}
Vertical aiming ⁴	3°		
• Unit closest to runway	3° 30'	±2' (0.03°)	±6' (0.1°)
• Unit second from runway	3° 10'	±2' (0.03°)	±6' (0.1°)
• Unit third from runway	2° 50'	±2' (0.03°)	±6' (0.1°)
• Unit farthest from runway	2° 30'	±2' (0.03°)	±6' (0.1°)
Horizontal alignment	Parallel to runway centerline	±30' (0.50°)	±30' (0.50°)
Tilt Detection	0.25° below to 0.50° above established Light Unit angle	Same as standard	Same as standard
Obstructions due to vegetation, etc.	No obstruction	Same as standard	Same as standard

Notes

- ¹ Initial tolerances should be considered during installation.
- ² ICAO ADM, Part 4, specifies, errors in excess of one minute of arc should be corrected.
- ³ Operating tolerances should be considered during Preventive Maintenance Inspections, Scheduled Maintenance, and Unscheduled Maintenance.
- ⁴ Unless a different standard is established locally, angles shown are for a 3-degree glide path.

FAA Standards and Tolerances for a Vertical Angle Aiming Tool

The standards and tolerances noted in the table are specified by FAA Advisory Circular AC 150/5345-28H as a guideline for PAPI aiming tool accuracy. The aiming tool is used to measure the vertical glide slope (vertical angle) during new installations and/or scheduled maintenance/inspections on an existing PAPI system. Current revisions of AC 150/5345-28 and/or applicable local standards and tolerances should always be observed.

Table 13: FAA Standards and Tolerances for a Vertical Angle Aiming Tool

Parameter	Tolerance / Limit	
	Initial	Operating
Vertical aim and level	±3' (0.05°)	±3' (0.05°)

The inclinometer device and digital display on the LED PAPI is considered to be a built-in aiming tool. If it is suspected that the vertical glide slope (vertical angle) on the digital display is incorrect or out of tolerance, please refer to the [Troubleshooting](#) section of this user manual or the [SUPPORT](#) section to contact ADB Safegate Technical Support.

Regular calibration services for the inclinometer aiming tool should be performed to ensure accurate performance of the LED PAPI system. Contact ADB Safegate Technical Support for assistance with a calibration service.

9.0 Troubleshooting



WARNING

Electric Shock

Allow only qualified personnel to perform the following tasks. Observe and follow the safety instructions in this document and all related documentation.

- Before attempting to service the fixture, de-energize the circuit and lock out the circuit or regulator so that the circuit cannot be energized by remote means.

9.1 Troubleshooting Tips

Refer to [Wiring Diagrams](#) for general troubleshooting procedures. This guide covers only the most common problems. The following paragraphs provide specific details on troubleshooting and repair of PAPI subsystem components. For additional help, contact your local ADB SAFEGATE representative.

9.2 Troubleshooting the Field Circuit First

To identify a faulty section, follow the guidelines given below, along with a drawing and a meter:

- Check the incoming supply power first.
- Check for voltages at the specific test points in circuit.
- While the circuit is OFF test, check for continuity of circuits, as intended, and check for insulation resistance.
- If it's not possible to perform a power OFF test, connect the supply to the circuit and do a live test of circuit.

Generally, any electrical circuit can be differentiated in two sections:

- Power circuit (voltage of current).
- Control circuit.

It is always advisable to first check the power circuit. So, if the power circuit works, as it should, then troubleshoot the control circuit.

Power circuit check list:

- Incoming power to circuit and its integrity
- Check for correct functioning of protection devices
- Check visual cable continuity
- Check for any signs of flash or burning smell of devices.

Control circuit check list:

- Control circuit power first
- Check for proper functioning of relays, timers, and switches
- Check visual cable continuity
- Check for wire interconnections and terminal connections of circuit
- Check logical operational sequence of contactor switching
- Check for timer duration settings.

If the above criteria are checked and the ADB product is still not working, then go to [Table 14](#).

9.3 Detailed Troubleshooting and Repair Procedures

This section describes procedure for troubleshooting or repairing parts in the RELIANCE PAPI enclosure.

Table 14: General PAPI System Troubleshooting Guide

Problem	Possible Cause	Solution
Voltage Powered: Current Sensing not operating	Control Board Issue	Continue to Repair section.
	Bad Isolation Transformer	Change the Isolation transformer to a known good transformer.
	Regulator Outputting incorrect current	Low input current from series circuit. Repair CCR or series circuit wiring (if an open circuit is present on the series circuit).
LEDs Dim	Dirt on Outer Glass	Clean with a soft cotton cloth moistened with alcohol.
	Current Powered: Current Level too low	Low input current from series circuit. Repair CCR or series circuit wiring (if an open circuit is present on the series circuit).
	Light Unit improperly aligned	Realign and recalibrate light unit.
LEDs Off	PAPI Light unit tilts	Realign PAPI Light Unit(s) that have tilted
	LEDs Failed	Check the local display on the PAPI where the Light Engine has failed and continue to Repair section.
	No power input	Voltage Powered: Measure the voltage between fuses F3 and F4 on the input power board 44A7392, if either fuse is blown replace the fuse, if it does not measure what the desired input voltage should be verify the system wiring or the power source is working properly (Style A Primary unit, verify the operation of the local ON/OFF switch). If the desired power is measured, replace the step down transformer. Current Powered: Measure the input current using a current clamp in either the conductor going to TB-1 or TB-2. If the desired output current is not present verify the Isolation transformer is good, the series circuit is properly connected and the Regulator is properly calibrated.
	Bad Inclinator Board	See section Troubleshooting the Inclinator Board .
	Communications lost	Determine which box has the communication error but looking at the display on the side of each PAPI, then continue to Repair section.
Display Reported Error: COMM -> LOST	CAN communication lost on the unit	See section Troubleshooting COMM LOST error .
Display Reported Error: HEAT -> FAIL	Front glass defroster error	See section Troubleshooting HEAT FAIL error .
Display Reported Error: RED -> LED -> FAIL	Red LED string error	See section Troubleshooting RED LED FAIL error .
Display Reported Error: WHT -> LED -> FAIL	White LED string error	See section Troubleshooting WHT LED FAIL error .
Display Reported Error: PHOT -> FAIL	Photocell failure, only displayed on the Style A Primary unit.	See section Troubleshooting PHOT FAIL error .
Display Reported Error: BOXn -> TILT	PAPI Light unit tilts	Realign PAPI Light Unit(s) that have tilted
	Bad Inclinator	Replace the Inclinator Assembly
Display Error: No Glide or Level Angle Displayed	Inclinator Board Disconnected	Check inclinometer ribbon connector, ensure it is connected to the Inclinator Board and the Control Board.
	Bad Inclinator Board	Replace the Inclinator Assembly

Table 14: General PAPI System Troubleshooting Guide (Continued)

Problem	Possible Cause	Solution
Voltage Powered: Remote mode operation not working	Bad switch	Replace the remote switch and all wiring to the LED PAPI system
	Blown fuse	Check Fuse F2 on the power board, if it is blown, replace the fuse.
	Bad Step Down Transformer	Measure the voltage between pin 2 on J7 and pin 1 on J2 of the power board, verify it is 48VAC ($\pm 15\%$). If it is not measuring the correct voltage, replace the step down transformer
	Control Board Issue	Continue to Repair section.

9.3.1 Troubleshoot and repair the RELIANCE PAPI

Follow these steps to troubleshoot and repair the RELIANCE PAPI:

- Visually examine all areas of the RELIANCE PAPI.
- Check for burnt or loose connections and parts.
- Check all fuses and the circuit breaker (where applicable).

If the RELIANCE PAPI does not energize at all:

Voltage Powered LED PAPI

1. Check fuses F3 and F4 on the input power board, if either fuse is blown replace the fuse.
2. Measure the voltage between fuses F3 and F4 on the input power board, if it does not measure desired input voltage, verify the system wiring or the power source is working properly.
3. Style A primary light unit, verify the operation of the local ON/OFF switch.
4. If the desired power is measured, replace the step down transformer.

Current Powered LED PAPI

1. Measure the input current using a current clamp on either the conductor going to TB-1 or TB-2. If the desired output current is not present verify the Isolation transformer is good, the series circuit is properly connected and the Regulator is properly calibrated.
2. Verify status of the indication LEDs on the Control Board.
3. Replace the Control Board as noted in [Table 15](#).

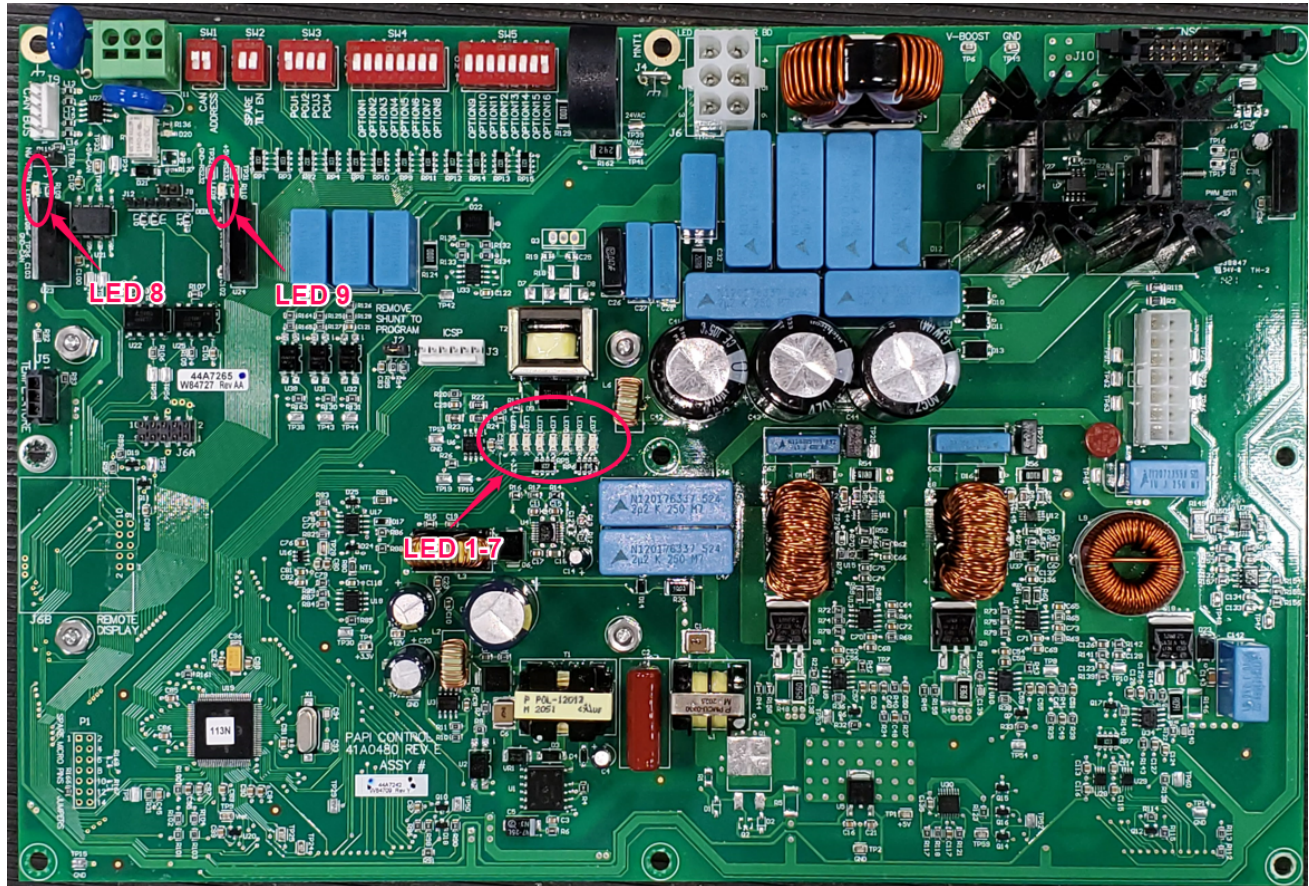
Table 15: Indication LEDs on the Control Board

LED	ON (GREEN)	OFF
LED1	+3.3V OK	+3.3V ERROR, replace Control Board
LED2	HEARTBEAT (blinking)	ERROR (fast blinking), replace Control Board
LED3	N/A	N/A
LED4	Current Powered	Voltage Powered
LED5	CAN OK	CAN ERROR
LED6	+12V OK	+12V ERROR, replace Control Board

Table 15: Indication LEDs on the Control Board (Continued)

LED	ON (GREEN)	OFF
LED7	BOOST OK	BOOST ERROR, replace Control Board
LED8	+5V CAN OK	+5V CAN ERROR,replace Control Board
LED9	+5V SERIAL OK	+5V SERIAL ERROR, replace Control Board

Figure 44: Control Board Indication LEDs



9.3.2 Troubleshooting COMM LOST error

1. Check position of DIP switch SW5-7, ensure COMM is enabled for all light units. Reference [Table 2](#).
2. Check CAN Address DIP switches SW1-1 and SW1-2 to make sure each box has a unique address.



Note

Each box will display it's box number (address) during boot up.

3. Check LED8 "+5V CAN OK" Indication LED on the Control Board, ON (GREEN) indicates Control Board is okay. Reference [Table 15](#) and [Figure 44](#). If LED is OFF, replace Control Board.

4. If no error is found in the Control Board then there is likely to be faulty wiring between boxes. Check and/or repair connections at the terminal block. Reference [Table 16](#) and [Internal Wiring Diagrams](#) section.
5. If no faulty wiring is found at the terminal block, check communication cord sets for faulty connections. Reference [Table 16](#).

Table 16: COMM LOST Troubleshooting Wiring Between Boxes

Box 1 Display	Box 2 Display	Box 3 Display	Box 4 Display	Possible Cause
COMM LOST		COMM LOST	COMM LOST	Break in communication cable between Box 2 and Box 3.
COMM LOST			COMM LOST	Break in communication cable between Box 3 and Box 4, or problem with Control Board in Box 4.
COMM LOST	COMM LOST	COMM LOST	COMM LOST	Break in communication cable between Box 1 and Box 2 or problem with Control Board in Box 1.

9.3.3 Troubleshooting HEAT FAIL error

1. Turn the PAPI light unit off, and disconnect the J1 connector from the Control Board.
2. Using a multimeter measure the resistance between pins 12 & 5.
3. Confirm the heated glass resistance specification for your LED PAPI. The specification is indicated by the firmware version, which is displayed during startup.
 - a. For LED PAPIs with firmware version 1.47 or earlier, verify the resistance reads between 13Ω and 21Ω.
 - b. For LED PAPIs with firmware version 1.50 or later, verify the resistance reads between 13Ω and 25Ω.
4. If the measurement is outside this range, there is a problem with the heated glass and it needs to be replaced.
5. If the measurement is inside this range, there is a problem with the Control Board.
6. Verify fuse F5 on the Control Board. If blown replace it. See [Figure 80](#).

9.3.4 Troubleshooting RED LED FAIL error

1. Turn the PAPI light unit off and disconnect the J1 connector from the Control Board.
2. Using a DC voltage supply limited to 65VDC and 300mA, apply voltage to pins 3(+) and 10(-) on the wire harness connector.
3. If the Red LEDs do not come on there is an error with the Light engine and it needs replaced.
4. If the Red LEDs came on in the previous step there is an error with the Control Board and it needs replaced.

9.3.5 Troubleshooting WHT LED FAIL error

1. Turn the PAPI light unit off and disconnect the J1 connector from the Control Board.
2. Using a DC voltage supply limited to 65VDC and 300mA, apply voltage to pins 4(+) and 10(-) on the wire harness connector.
3. If the White LEDs do not come on there is an error with the Light engine and it needs replaced.
4. If the White LEDs came on in the previous step there is an error with the Control Board and it needs replaced.

9.3.6 Troubleshooting PHOT FAIL error

1. Check to see if Fuse F1 on the Input Power Board is blown, replace fuse F1 if it is blown.
2. Measure the voltage between pins 1 and 3 on J2 of the Input Power Board, verify it is 24VAC.
3. If 24VAC is not measured, the step down transformer needs replaced.
4. If 24VAC is measured, replace the photocell.
5. After replacing the photocell if the problem persists then the problem is with the Control Board and it needs replaced.

9.3.7 Troubleshooting the Inclinator Board

Refer to the [Table 14](#).

9.3.8 Troubleshooting the Control Board

If a problem is suspected with the control board, refer to drawings in [Figure 45](#) and check the following indicators and test points.

1. Remove the screws and washers holding the top cover.
2. Set the top cover aside.
3. Verify operation of Control Board LEDs. See [Table 15](#).



Note

Use a non conductive inspection mirror to perform the LED checks.

4. Verify DC power supply voltage of 90 VDC \pm 5% between TP6 to TP49. Reference [Figure 45](#).

Figure 45: LED PAPI Control Board DC Power Supply Test Point



5. If 90 VDC \pm 5% is not measured, replace the Control Board.
6. Check for loose wires and disconnected Molex plugs for the board and power supply.
7. If the Control Board is found to be faulty, power down the PAPI and replace the Control Board.
8. Go to [Control Board Replacement](#) to make certain you get the correct replacement kit to proceed.
Read all of the following replacement procedures before performing any other steps.
9. Re-attach plugs to new LED PAPI control board. Reference the [Wiring Diagrams](#).

**Note**

With each control board assembly, the corresponding input power control board (44A7392/X) is provided and must be replaced.

10. Disconnect wiring from the 44A7392/X input power board.
11. Remove 44A7392/X input power board by lifting the Din Rail mount tabs to release it from the Din Rail.
12. Replace with 44A7392/X input power board provided with the kit. Install by snapping the mounting tabs onto the Din Rail.
13. Re-connect wiring to 44A7392/X Input power board. Ref to [Wiring Diagrams](#).
14. Replace the top cover gasket if necessary. Attach the top cover.
15. Go to [Understanding the LED Readout](#) and complete the setup and alignment procedures.

10.0 Repair

To troubleshoot and repair a PAPI Light Unit, follow these steps:

1. Check the display on each light unit and see if any errors are displayed. The following errors are displayed on the specific unit that is having an issue:

Display	Error
COMM -> LOST	CAN communication lost on the unit
HEAT -> FAIL	Front Glass defroster error
RED -> LED -> FAIL	Red LED string error
WHT -> LED -> FAIL	White LED string error
PHOT -> FAIL	Photocell failure, only displayed on the voltage powered Primary Unit.

2. If one of the light units is tilted all units in the system will display which box is tilted: BOX X -> TILT (Where X is the number of the tilted box).

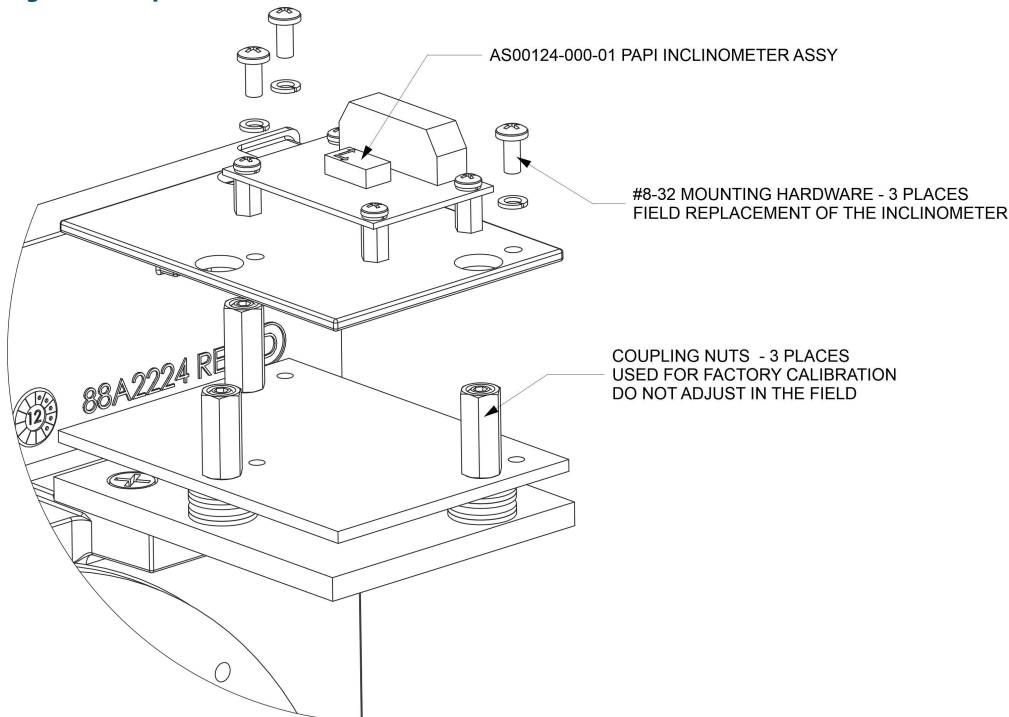
Depending on the information read on the Display, take corrective actions to repair the light unit. Details on further troubleshooting/repair are detailed in the paragraphs below.

10.1 Inclinometer Assembly Replacement

If a problem is suspected with the inclinometer board, first verify the following voltage is present on the board. Refer to [Troubleshooting the Inclinometer Board](#)

If the inclinometer needs to be replaced, install new inclinometer assembly AS00124-000-01.

Figure 46: Top Inside View



Procedure for replacing the inclinometer assembly AS00124-000-01

1. Remove the (2) top cover screws, washers and the top cover and set them aside for later reuse.
2. Disconnect the ribbon cable connector from the Inclinometer Board.
3. Remove the (3) mounting screws while insuring the coupling nuts DO NOT MOVE.

4. Replace the inclinometer assembly and replace the (3) screws, (torque to 10 to 12 in-lbs) again insuring the coupling nuts DO NOT MOVE.
5. Reconnect the ribbon cable connector to the new Inclinometer Board.
6. Replace the top cover gasket if necessary.
7. Reinstall the top cover, screws and washers.
8. Verify glide slope angle on the digital display. Accuracy of the digital display is ± 3 minutes of arc (± 0.05). If it is suspected that the glide slope angle on the digital display is incorrect or out of tolerance, please first refer to the [Standards and Tolerances](#) section for standard operating tolerances. If necessary, refer to the [Troubleshooting](#) section of this user manual, or the [SUPPORT](#) section to contact ADB Safegate Technical Support.

10.2 LED Light Engine Replacement

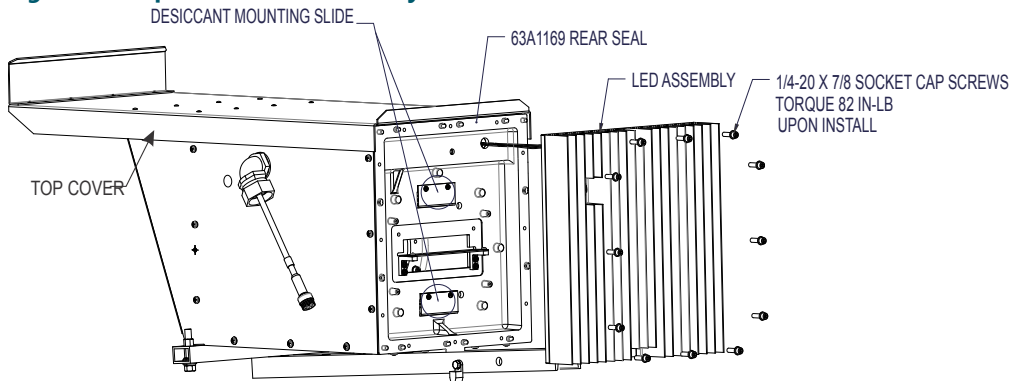
If there is a problem with the LED Assembly and it needs to be replaced, replace with AK00030-000-01 RELIANCE PAPI LED Light Engine Replacement Kit.



Note

When replacing the LED Light Engine, the desiccant packs must also be replaced. The required desiccant packs and mounting hardware are included in the LED Light Engine replacement kit AK00030-000-01.

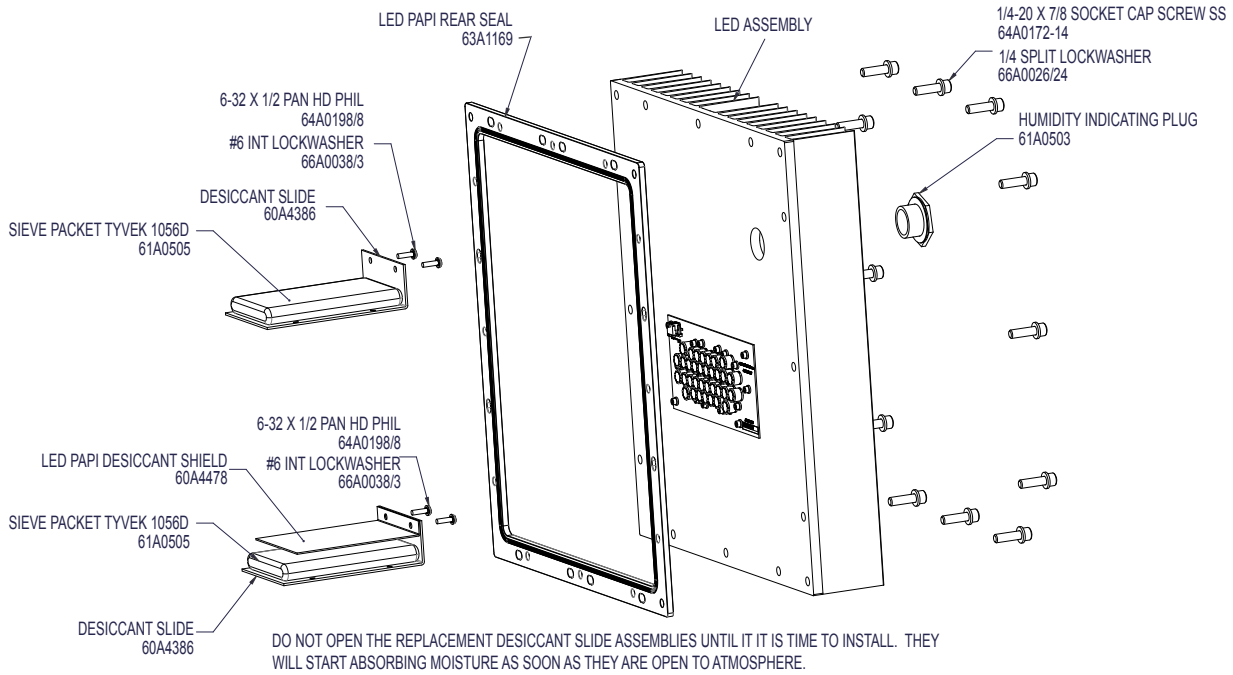
Figure 47: Replace the LED Assembly



1. Remove the (12) 1/4-20 SHCS from the rear of the LED assembly. Remove the LED assembly.
2. Disconnect the wire connector from the LED assembly and discard the non-working LED assembly.
3. Remove and discard the rear seal gasket.
4. Replace the (2) desiccant packs. (only in dry conditions and not until ready to reassemble). See [Replace the Two Desiccant Packs](#).
5. Replace the rear seal gasket.
6. Connect the wire connector to the replacement LED assembly.

7. Mount the LED assembly onto the PAPI light unit.
8. Replace the (12) 1/4-20 SHCS and washers to the rear of the LED assembly, torque to 82 in-lb.

Figure 48: Desiccant Packs and Rear Seal



10.3 Control Board Replacement

Kit 94A0666/XXX, RELIANCE PAPI Control Board Replacement Kit.



Note

Read the following sections prior to performing any tasks. Follow these procedures carefully and call ADB SAFEGATE for assistance, if required.

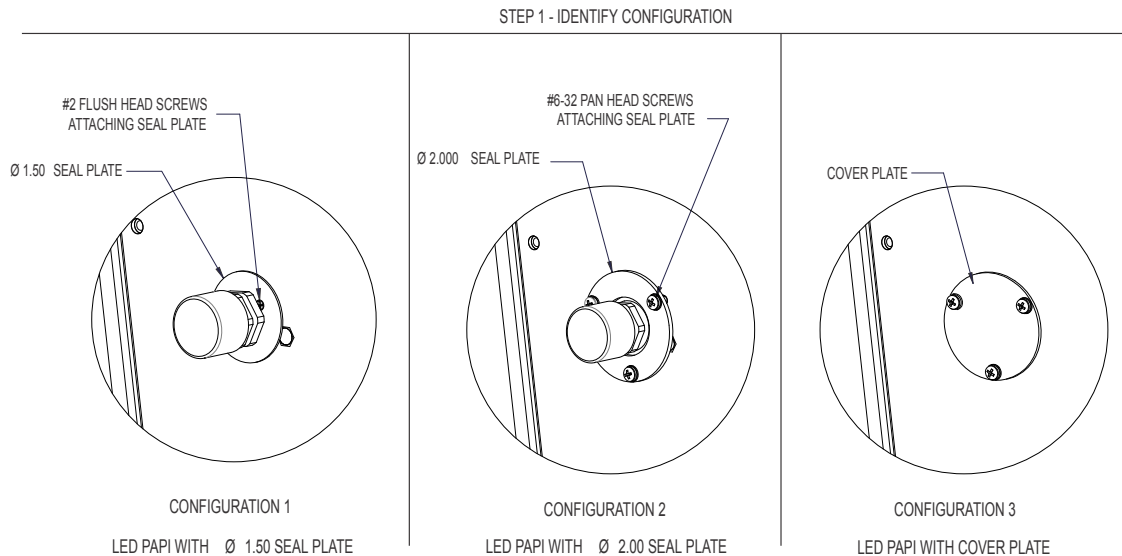
Use the following matrix to identify the compatible kit for your LED PAPI.

<p>Ordering Code</p> <p>Power</p> <p>1 = Voltage-Powered Primary PAPI</p> <p>2 = Voltage-Powered Secondary PAPI</p> <p>3 = Current-Powered PAPI</p> <p>Series Option</p> <p>0 = LPL Series PAPI (PN begins with LPL)</p> <p>2 = RP Series PAPI (PN begins with RP)</p> <p>Input Power PCB Option</p> <p>0 = Input Power PCB Not Included</p> <p> = Input Power PCB Included</p>	<p>94A0666 / <input type="checkbox"/><input type="checkbox"/><input type="checkbox"/></p> <p>●</p> <p>●</p> <p>●</p>
--	--

10.3.1 Replacing the Control Board/Display Side Panel Assembly

1. Identify the configuration of your RELIANCE PAPI enclosure.
 - a. If the enclosure is not equipped with a baffle, proceed to step 4.
 - b. If the enclosure is identified as Configuration 1, proceed to step 2.
 - c. If the enclosure is identified as Configuration 2, proceed to step 3.
 - d. If the enclosure is identified as Configuration 3, proceed to step 4.

Figure 49: Identify the Side Panel Configuration



2. Configuration 1 Baffle Plate removal instructions.

RELIANCE PAPI WITH Ø 1.5-in SEAL PLATE.

- a. Slightly loosen the sealing gland nut on the 77A0263 cord grip. Do not allow the Actuator fitting to rotate as this will break the seal.
- b. Remove the 77A0263 cord grip from the 60A4575 actuator fitting. It is necessary to secure the 60A4575 actuator fitting to prevent rotation.

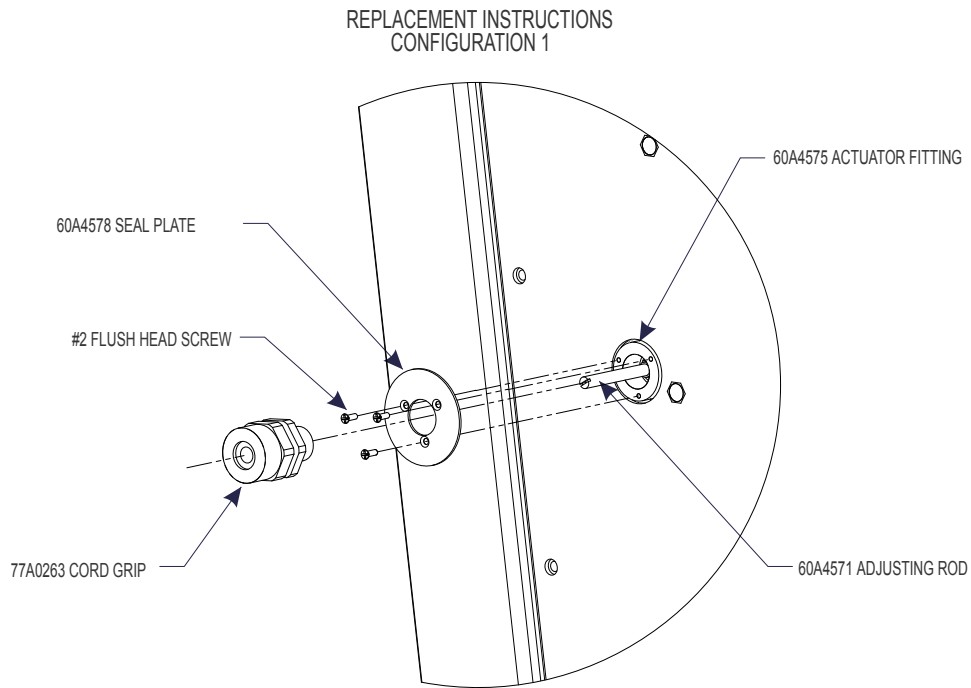


Note

Do not allow the 60A4571 adjusting rod to rotate as this will change the baffle setting.

- c. Remove the three #2 flush screws and 60A4578 seal plate - discard.
- d. Proceed to step 4

Figure 50: Remove the baffle closeout (configuration 1)



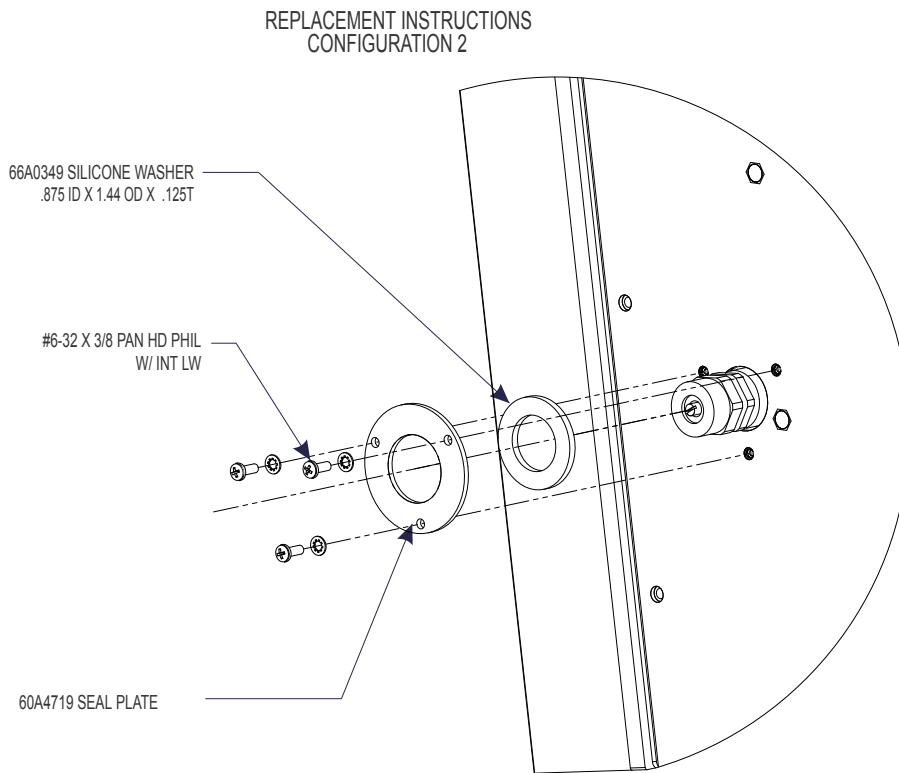
3. Configuration 2 Baffle Plate removal instructions.
 - a. Remove the #6 hardware attaching the 60A4719 closeout plate.
 - b. Remove the 66A0349 silicone washer.
 - c. Proceed to step 4, Side Panel Removal.
-



Note

Do NOT loosen the Gland Nut (77A0263), or threaded connection to the Actuator Fitting (60A4575).

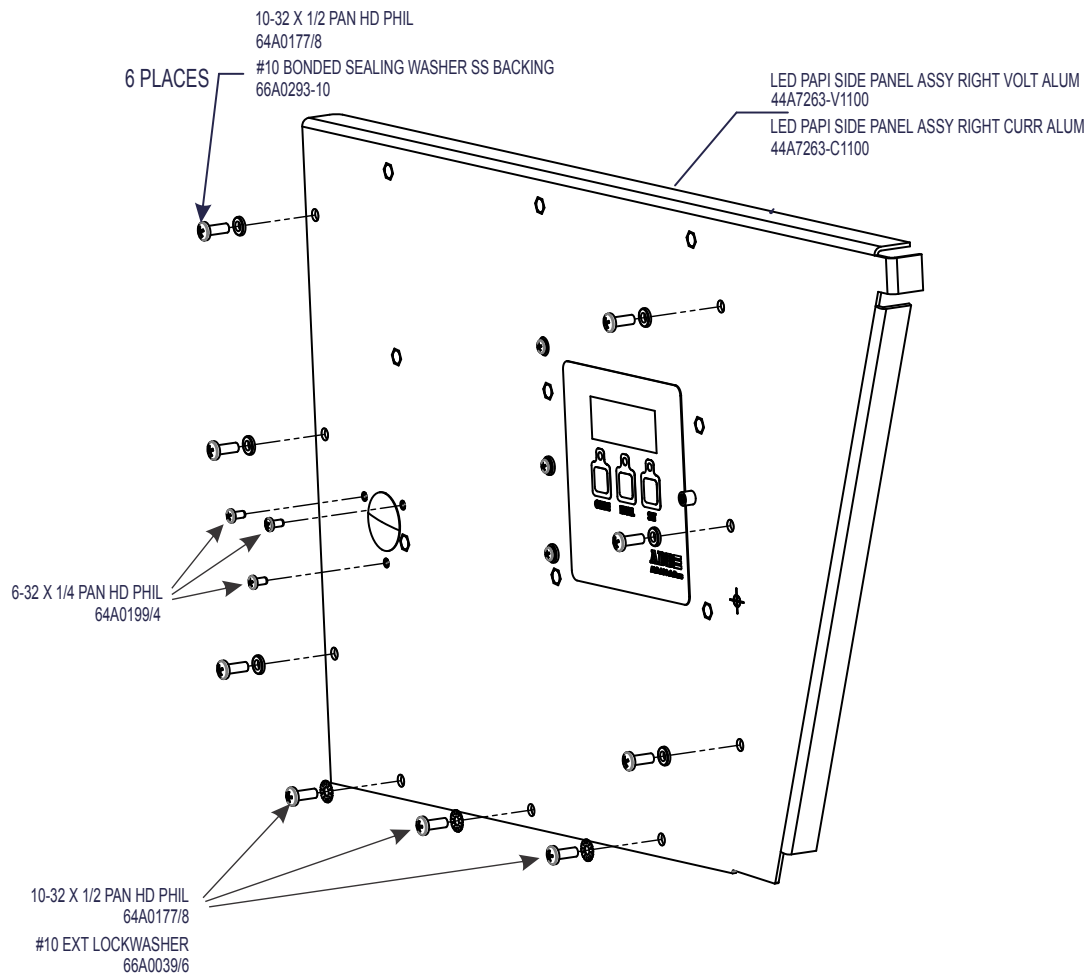
Figure 51: Remove the baffle closeout (configuration 2)



4. Side Panel Removal - all configurations.

- a. Disconnect all of the plug-in attachments to the 44A7265 Side Panel Assembly.
- b. Remove (9) #10-3 screws attaching the 44A7263 Side Panel Assembly.

Figure 52: Side Panel Removal/Replacement



5. Set DIP switches on the replacement Control Board assembly to match the DIP switches on the removed Control Board assembly. Refer to [Figure](#) for location of the DIP switches on the Control Board.

Note

If the removed Control Board switch settings are unavailable or damaged, the DIP switch settings can be found in user manual 96A0446 for the LPL series PAPI and DM00012-000-01 for the RP series PAPI. See section RELIANCE PAPI Control Board Overview.

Note

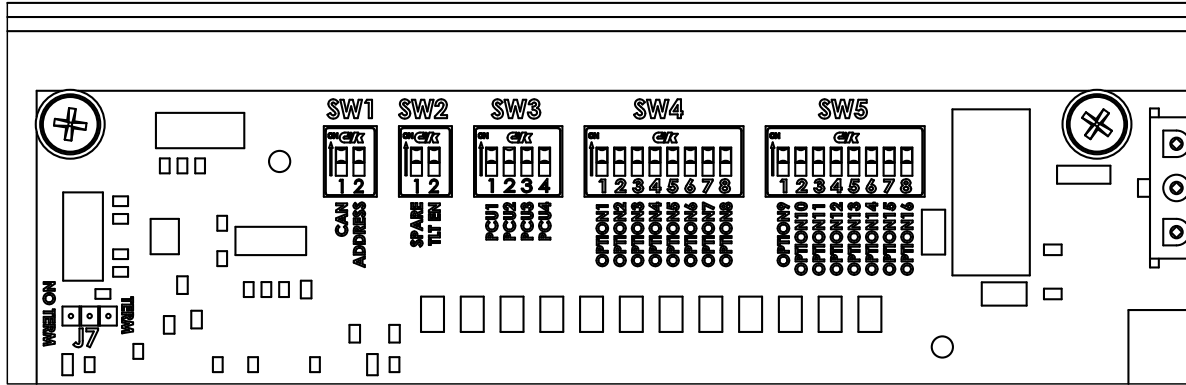
For the RP series PAPI only, ensure DIP switch SW5-7 is configured for proper site specific operation of the LED PAPI system. The default position of this switch is "OFF" for communication between boxes to be "enabled". To "disable" communication between boxes, this switch must be changed to the "ON" position. For previous versions of firmware, this switch may have been unused. For the LPL series PAPI, this switch was unused.



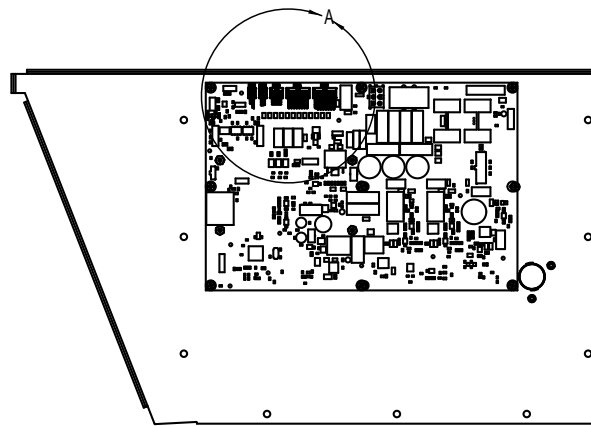
Note

For the RP series FAA PAPI only, ensure DIP switch SW4-7 is in the "ON" position for FAA operation. For previous versions of firmware, this switch may have been unused.
For ICAO operation, this switch will be in the "OFF" position.
For the LPL series PAPI, this switch was unused.

Figure 53: Control Board DIP Switch Location



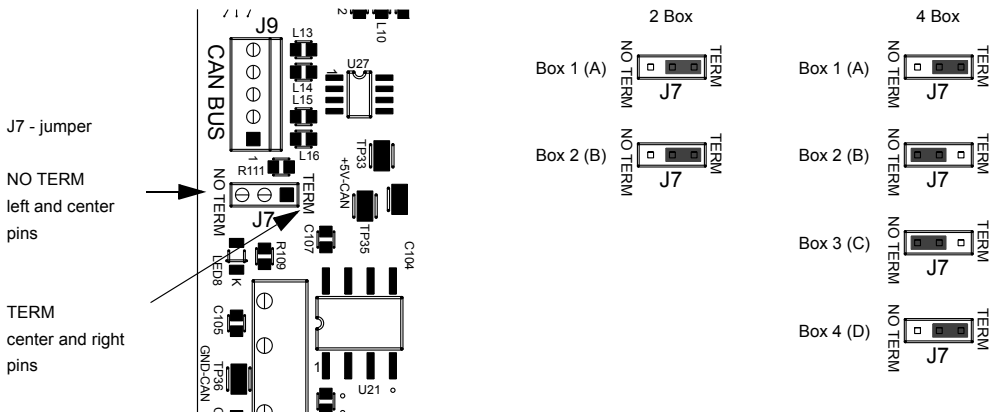
DETAIL A



6. Configure the jumper position on J7 of the Control Board.

- a. 2 Box setup: The jumper position on J7 for Box 1 and Box 2 will be on the Left and Center pins (TERM).
- b. 4 Box setup: The jumper position on J7 for Box 1 and Box 4 will be on the Left and Center pins (TERM); Box 2 and Box 3 will be on the Center and Right pins (NO TERM).

Figure 54: Control Board - J7 jumper setting



7. Reassembly of Side Panel Assembly.

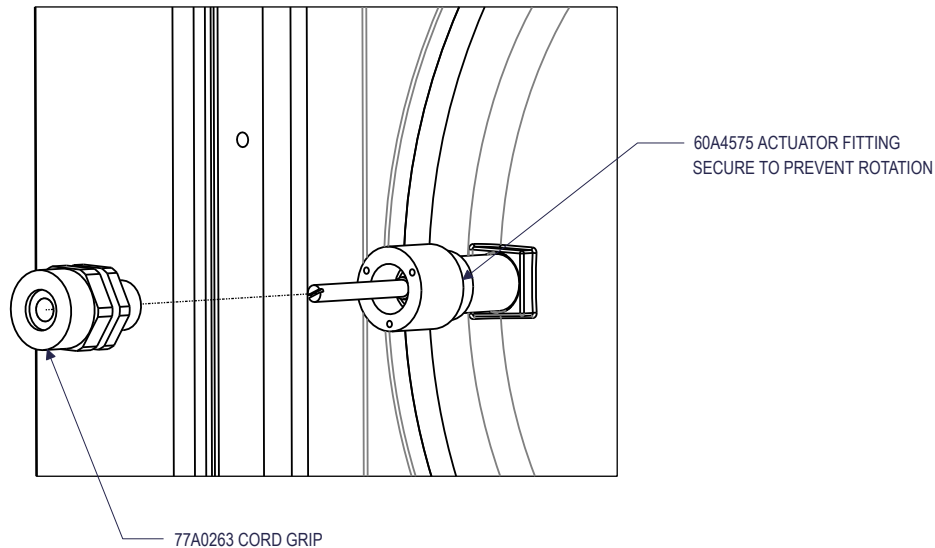
a. Enclosure without a baffle and configuration 3 Side Panel Replacement.

- Install the replacement side panel using the provided hardware - (9) # 10-32 screws.
- Re-attach cable-plugs to new RELIANCE PAPI control board. Reference the user manual 96A0446 for the LP series PAPI and DM00012-000-01 for the RP series PAPI for applicable wiring diagrams.

b. Configuration 1 Side Panel Replacement instructions.

- Apply a light coating of lubricant to the protruding 60A4571 adjusting rod.
- Install the 77A0263 cord grip using pipe thread sealant. It is necessary to secure the 60A4575 Actuator Fitting to prevent rotation. Do not allow the 60A4571 Adjusting Rod to rotate as this will change the baffle setting.

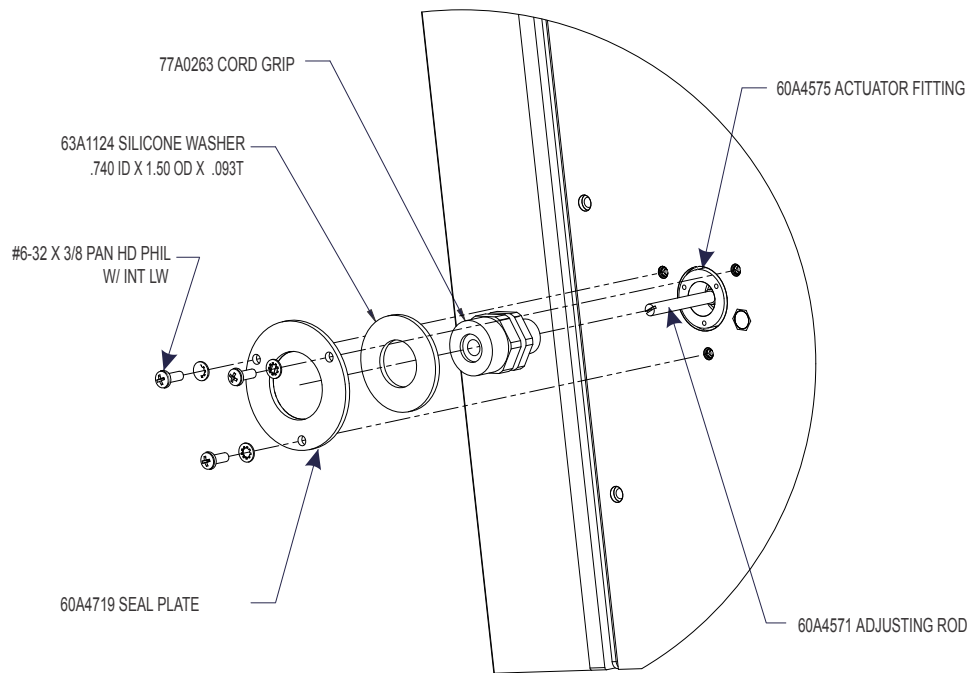
Figure 55: Reassembly of the Baffle Actuator Fitting (configuration 1)



- Install replacement side panel using provided hardware - (9) #10-32 screws.

- Stretch the 63A1124 Seal Washer over the cord grip fitting and install the 60A4719 Closeout Plate using the #6 hardware provided.
- Re-attach plugs to new RELIANCE PAPI control board. Reference the user manual 96A0446 for the LP series PAPI and DM00012-000-01 for the RP series PAPI for applicable wiring diagrams.

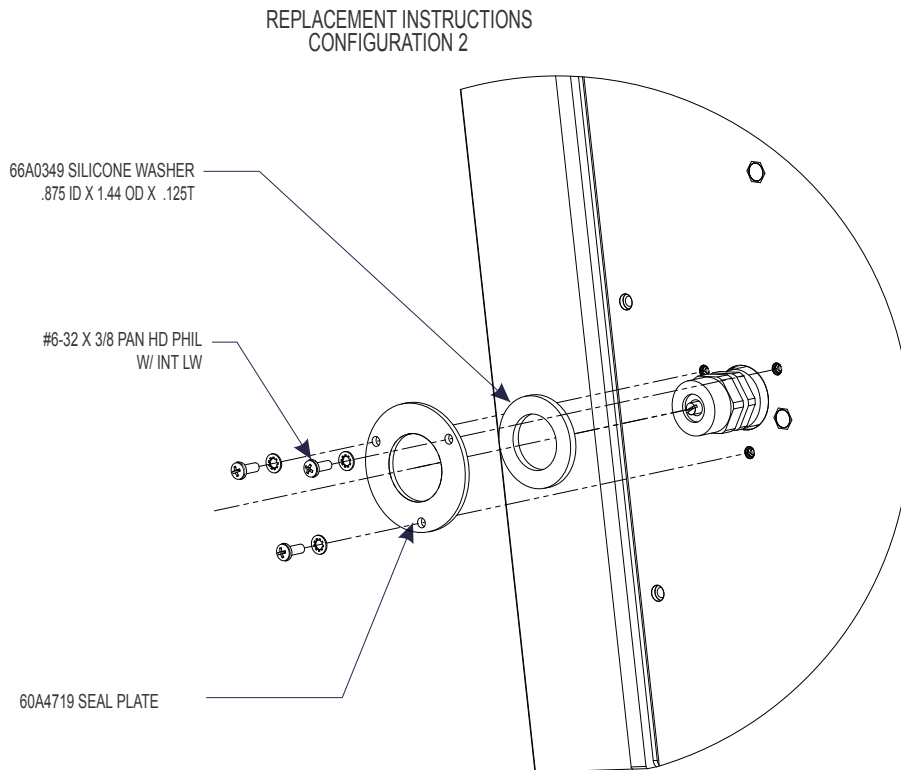
Figure 56: Reassembly of the Baffle Seal Washer and Seal Plate (configuration 1)



c. Configuration 2 Side Panel Replacement instructions.

- Install the replacement side panel using provided hardware - (9) #10-32 screws.
- Install the 66A0349 Seal Washer over the cord grip fitting and install the 60A4719 Seal Plate using the #6 hardware provided.
- Re-attach plugs to new RELIANCE PAPI control board. Reference the user manual 96A0446 for the LP series PAPI and DM00012-000-01 for the RP series PAPI for applicable wiring diagrams.

Figure 57: Reassembly of the Baffle (configuration 2)



8. Replace the input power board as necessary. If input power board is not replaced, proceed to the next step.



Note

With each control board assembly, the corresponding input power board (44A7392/X) is provided and must be replaced.

- a. Disconnect wiring from the 44A7392/X input power assembly.
 - b. Remove 44A7392/X input power assembly by lifting the DIN Rail mount tabs to release it from the DIN Rail.
 - c. Replace with 44A7392/X input power assembly provided with the kit. Install by snapping the mounting tabs onto the DIN Rail.
 - d. Re-connect wiring to 44A7392/X Input power assembly. Reference manual for applicable internal wiring diagram.
9. On the Control Board change dip switch 4-6 to the "ON" position.
10. Turn Regulator on to step B5.
11. Observe the digital display, the display will present the firmware version. If the digital display reads firmware version 1.33, skip to step 12. If the firmware version is newer (or higher) than 1.33, continue with the next step.
12. Allow time for PAPI to execute calibration process. When finished light output from PAPI will blink every second.
13. Turn regulator off.
14. Change DIP switch 4-6 to the "OFF" position.
15. Turn regulator on and verify PAPI changes light intensity at all steps.
16. Turn regulator off.
17. Replace the top cover gasket if necessary. Attach the top cover.
18. Go to Reference manual for Understanding the LED Readout and complete the setup and alignment procedures.

10.4 Front Glass Replacement

To ensure proper operation of the LED PAPI, it is important that the correct version of heated glass is installed. To determine what heated glass is needed, you must first confirm the heated glass resistance specification for your LED PAPI. The specification is indicated by the firmware version, which is displayed during startup.

At startup, the PAPI display board will show the following message:

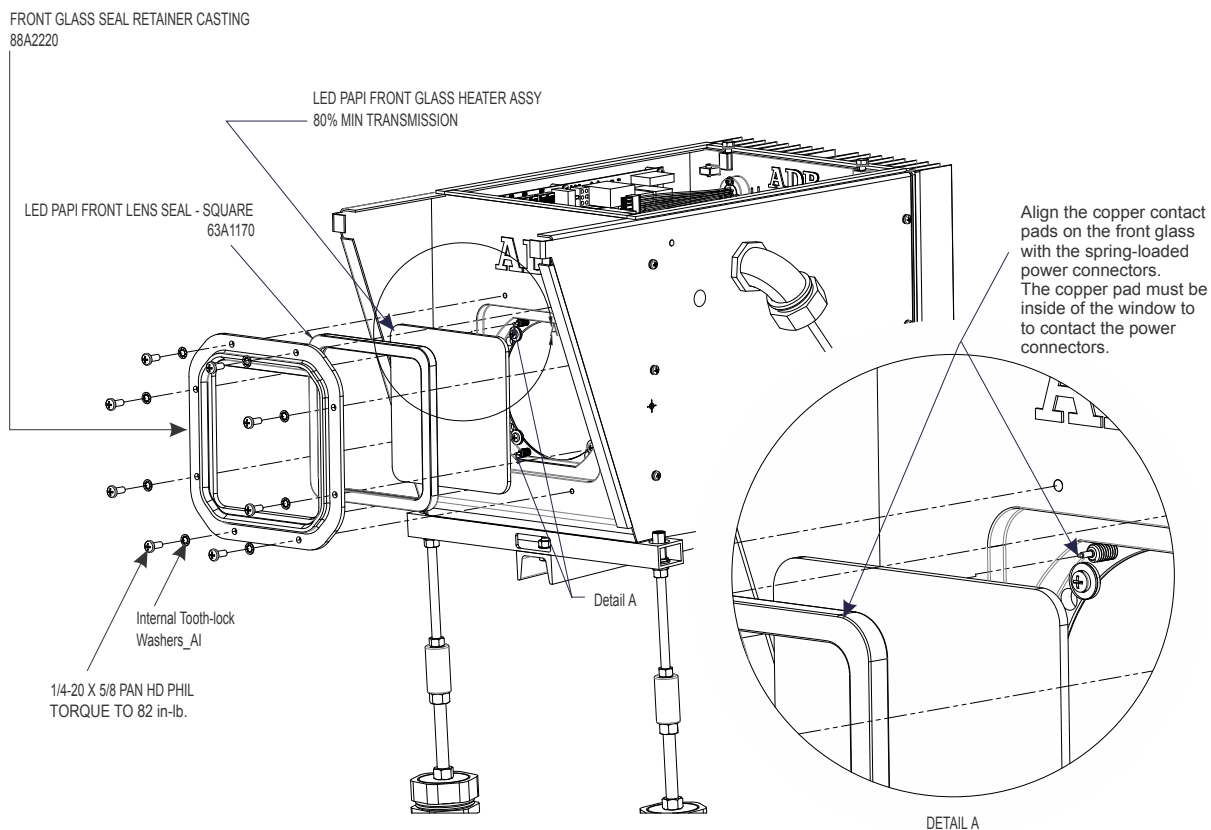
ADB -> LED -> PAPI -> VER -> V.VV -> GGGG -> BOXn -> OFn -> COLD -> XXX -> SEC.

- **V.VV** corresponds to the current control board firmware version
 - If **V.VV** = 1.47 or earlier, use heated glass spare kit 94A0674/1.
 - If **V.VV** = 1.50 or later, use heated glass spare kit 94A0674/1 or AK00054-000-01.
- **XXX -> SEC** will be repeated until the light output is activated, if the defrost timer (SW 5-8) is enabled.

Note

When replacing the LED PAPI front glass, the desiccant packs must also be replaced. The required desiccant packs and mounting hardware are included in the front glass replacement kits 94A0674/1 and AK00054-000-01.

Figure 58: Front Glass Replacement



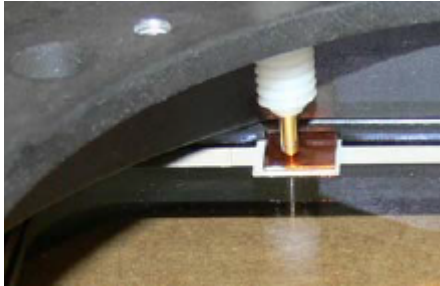
10.4.1 Replace the LED PAPI Front Glass

Instructions for replacing the front glass using heated glass kits 94A0674/1 and AK00054-000-01.

1. Remove and discard the (8) 1/4-20 fasteners and washers attaching the 88A2220 seal retainer.
2. Remove and discard the defective front glass and seal.
3. Install the new 63A1170 front lens seal by wrapping around the new front glass.

- Align the copper contact pads on the front glass with the spring loaded power connectors.

Figure 59: Copper Tab and Spring Loaded Power Connector



Note

The copper pad must be inside of the window (facing the PAPI) to contact the power connectors.

- Install 88A2220 seal retainer with new (8) 1/4-20 fasteners and washers, torque to 82 IN-LB.
- Replace the desiccant packs. See [Replace the Two Desiccant Packs](#).
- Verify fuse F5 on the control board.

10.5 Replace the Two Desiccant Packs

- Remove and discard the (12) 1/4-20 SHCS and washers from the rear of the LED assembly heat sink.
- Disconnect the wire connector from the LED assembly.
- Discard the rear seal gasket.
- Replace the two desiccant packs. (only in dry conditions and not until ready to reassemble)
 - Remove and discard the two screws holding each desiccant slides.
 - Remove and discard the desiccants, slides and shield.
 - Insert the (2) new pre-assembled desiccant packs with slides and attach each with the two fasteners and washers. Ensure the new desiccant shield is installed with the lower slide only.

Figure 60: LED Assembly

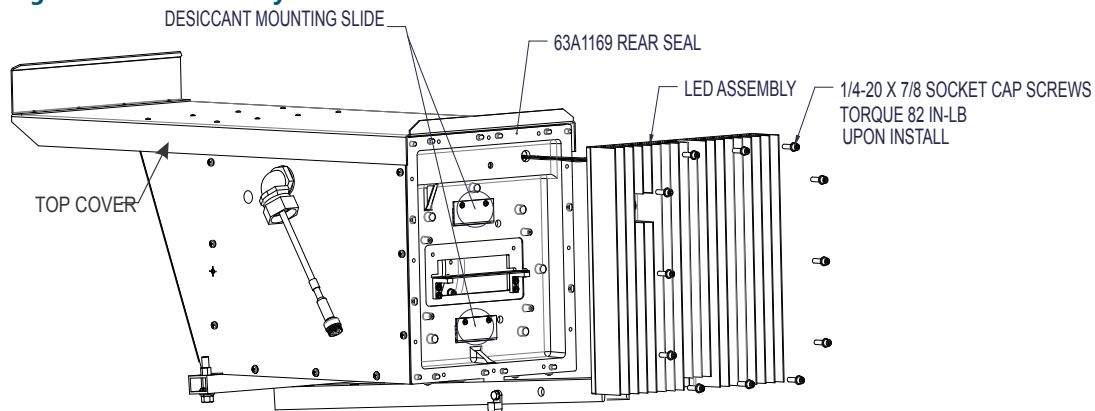


Figure 61: Desiccant Packs and Rear Seal

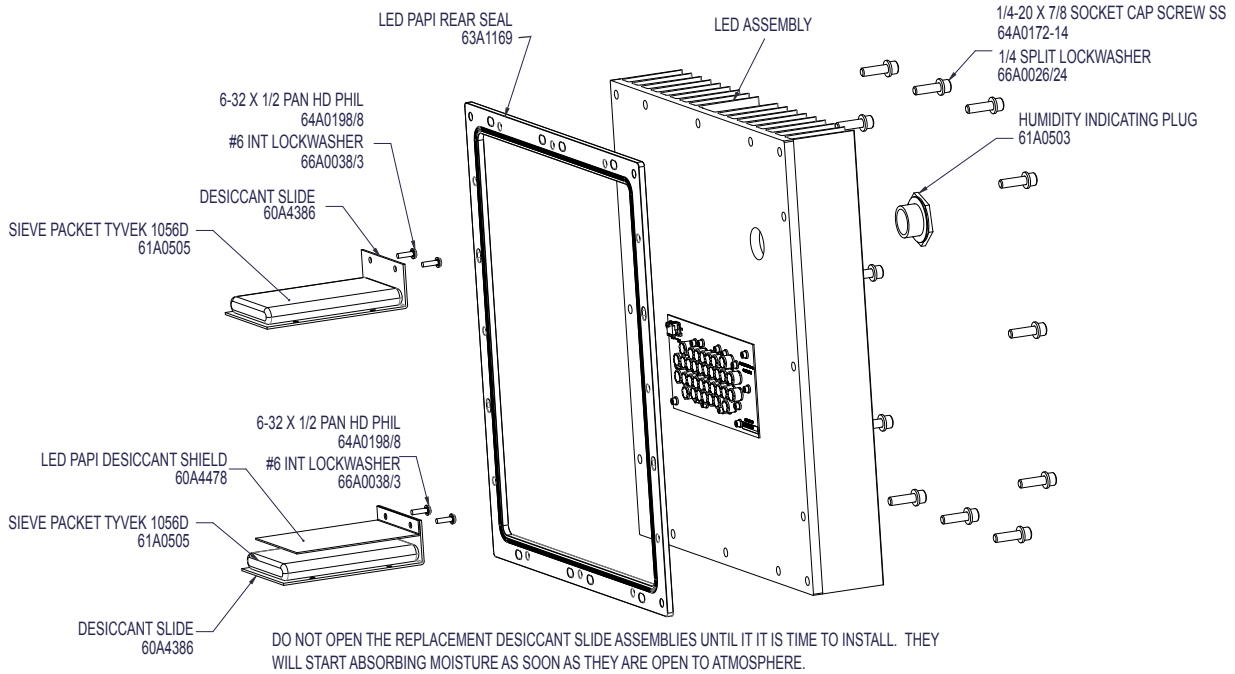
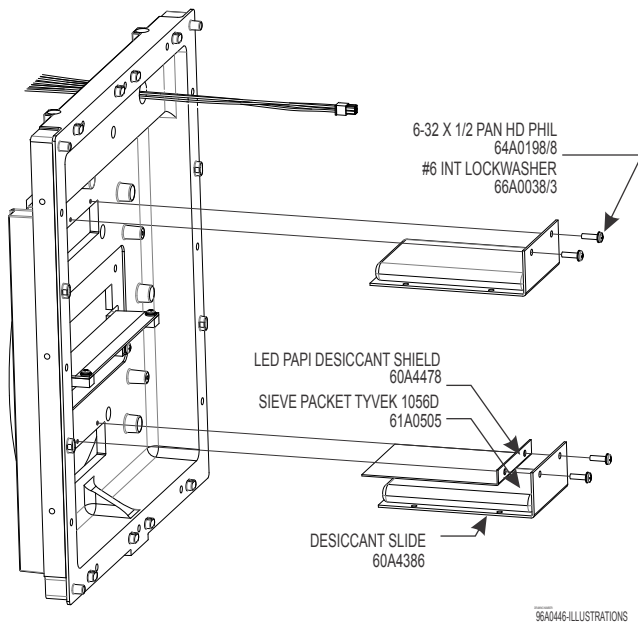


Figure 62: Desiccant Packs

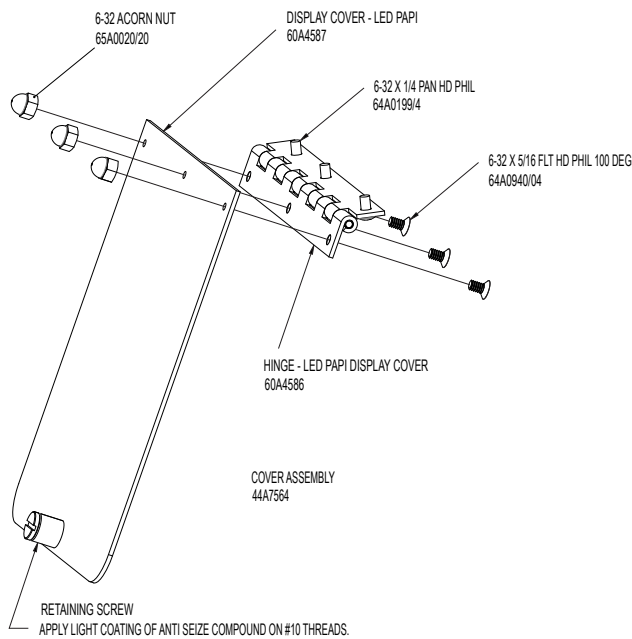


5. Replace the rear seal gasket.
6. Connect the wire connector to the LED assembly.
7. Replace the (12) 1/4-20 SHCS to the rear of the LED assembly, torque to 82 in-lb.

10.6 Optional Touchpad Cover

Unpack the optional touchpad cover assembly. Ensure all components are in the package.

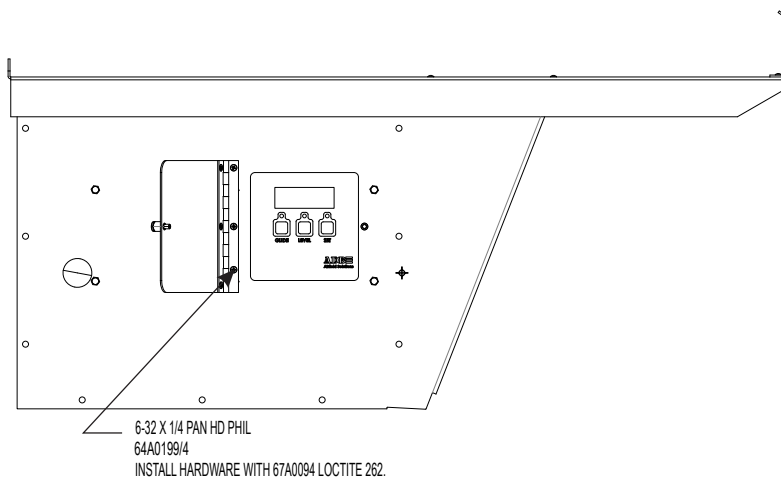
Figure 63: Touchpad Cover Assembly 44A7564



Install the optional touchpad cover assembly using the three holes to the left of the display.

1. Apply a drop of Loctite to the supplied screws.
2. Line up the touchpad cover assembly with the holes and attach with the supplied 6-32 screws.
3. Close the touchpad cover and lock closed with the retaining screw.

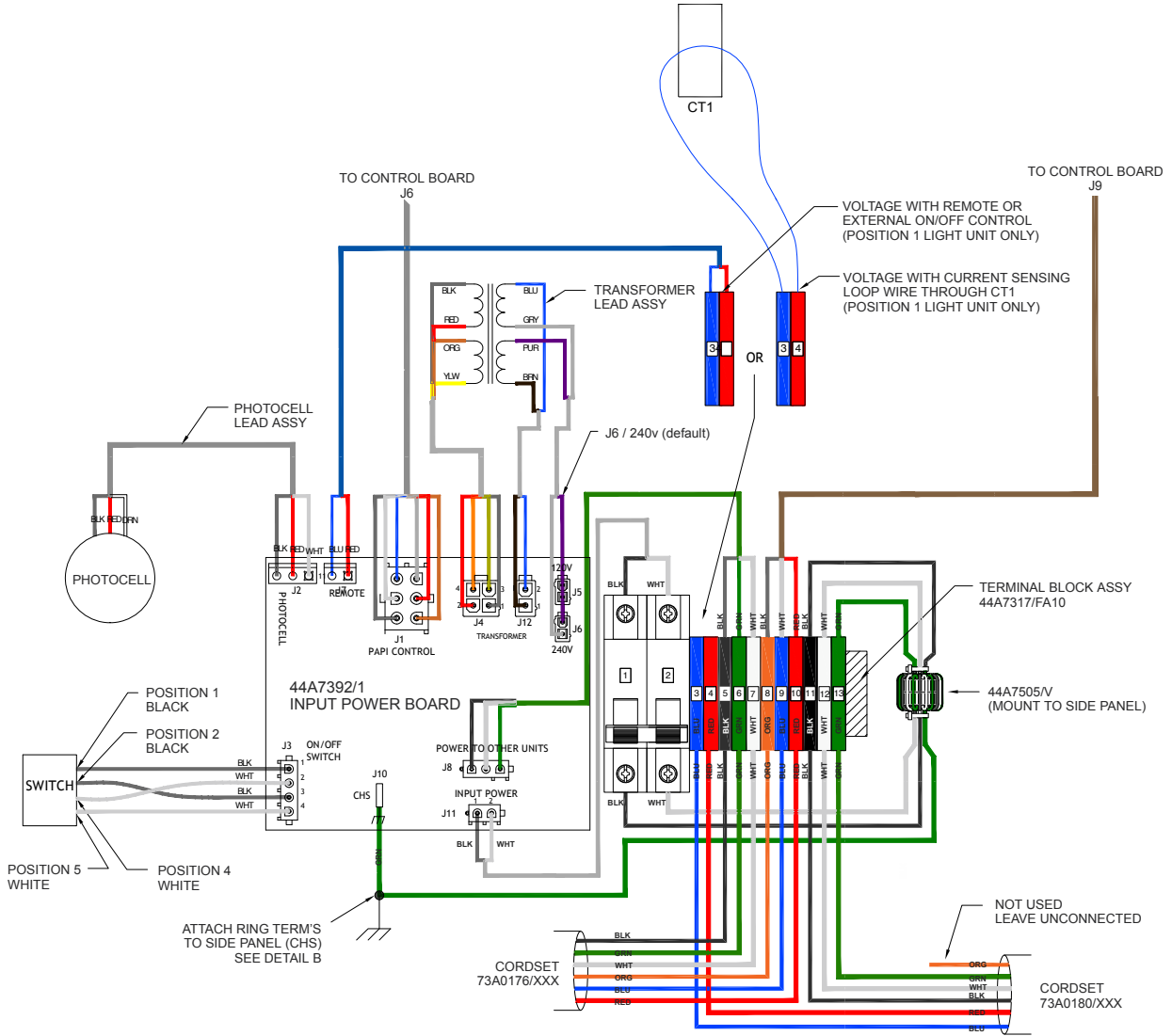
Figure 64: Touchpad Cover Assembly Installed



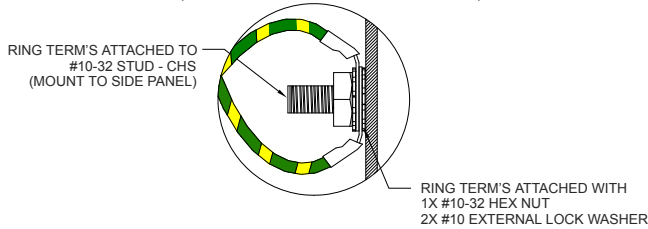
11.0 Wiring Diagrams

11.1 Internal Wiring Diagrams

Figure 65: Input Power Wiring Diagram - Voltage Powered (Primary Light Unit)

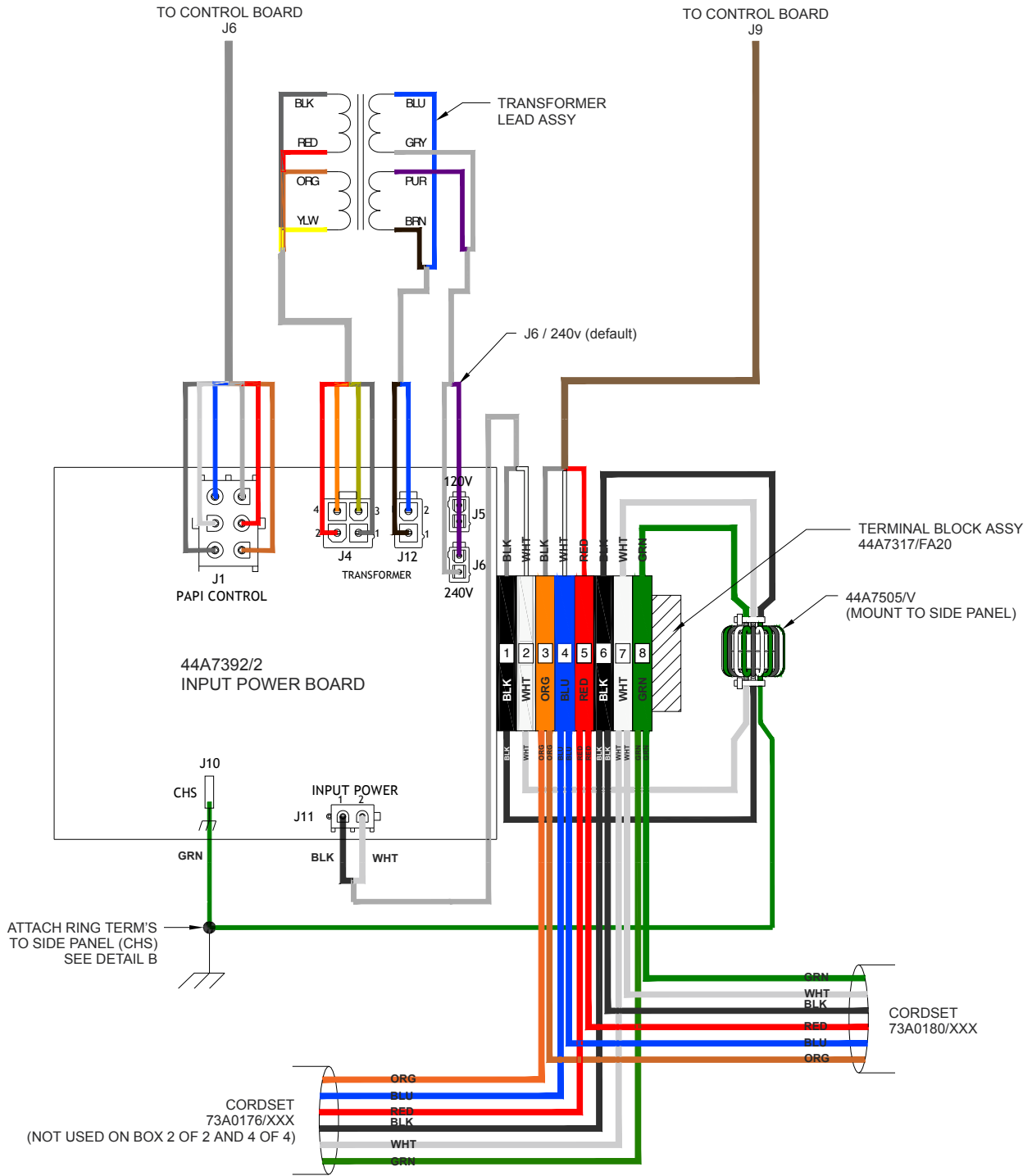


DETAIL B:
CHASSIS GROUND RING TERM'S CONNECTION, TYP.
(POWER CORD GROUND LEAD NOT SHOWN)



43A4144-XXXX REV.D

Figure 66: Input Power Wiring Diagram - Voltage Powered (Secondary Light Unit)



DETAIL B:
CHASSIS' GROUND RING TERM'S CONNECTION, TYP.
(POWER CORD GROUND LEAD NOT SHOWN)

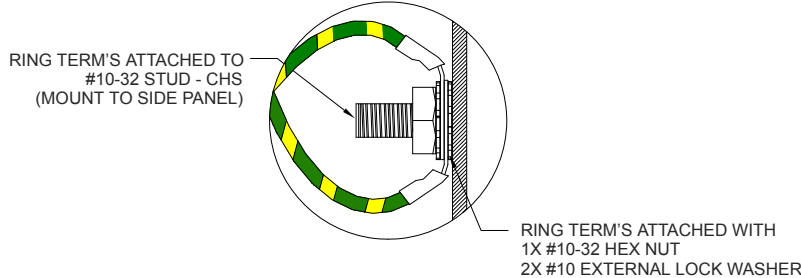
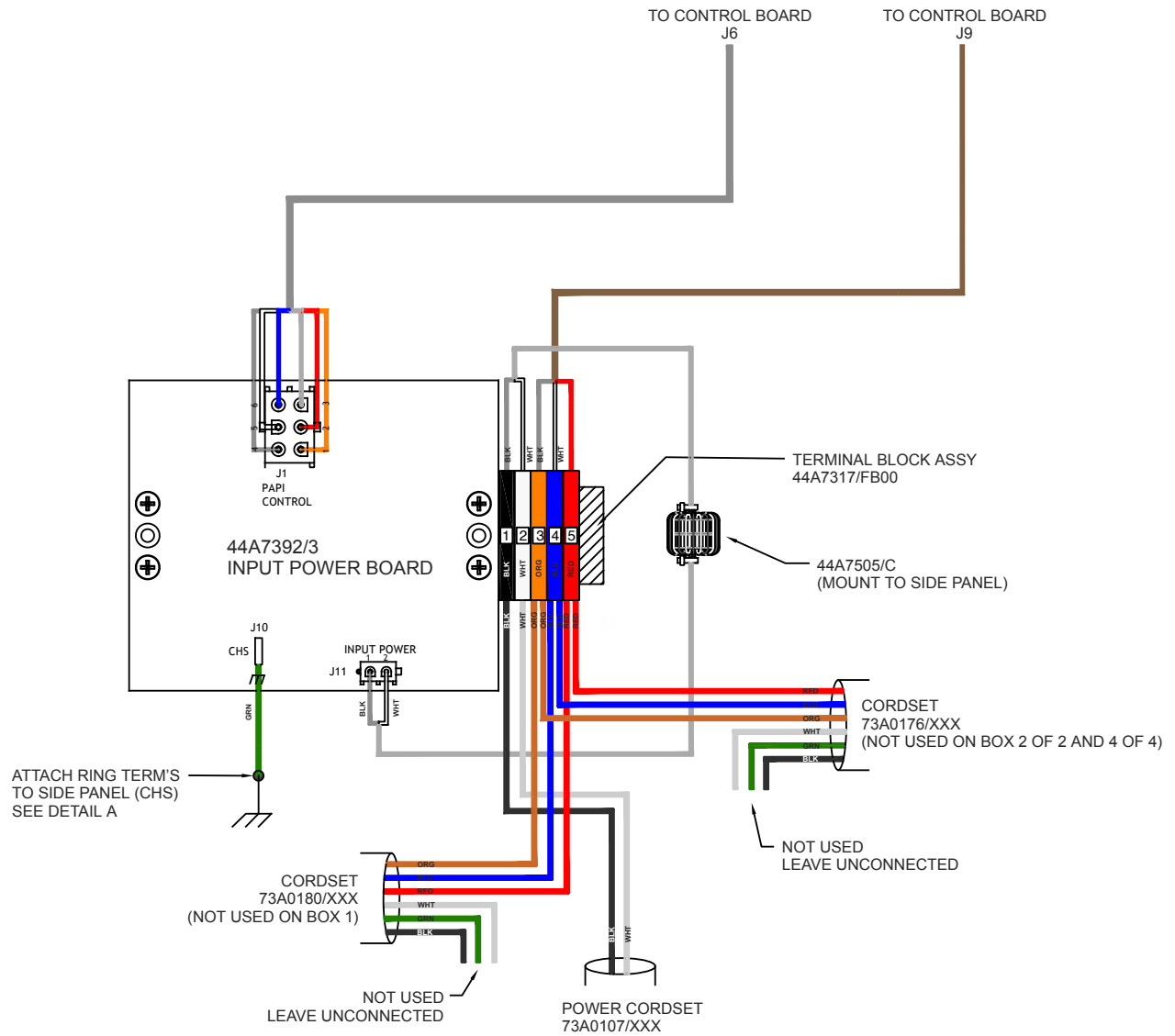
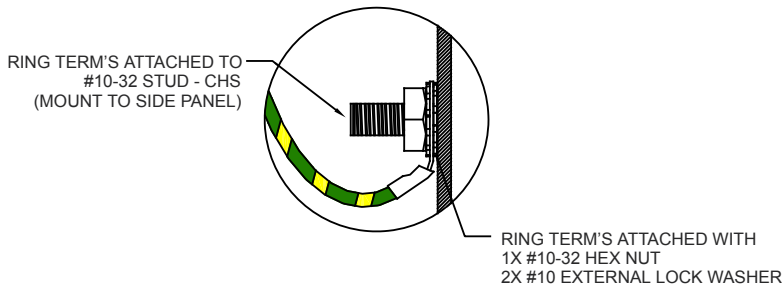


Figure 67: Input Power Wiring Diagram - Current Powered (Primary and Secondary Light Unit)

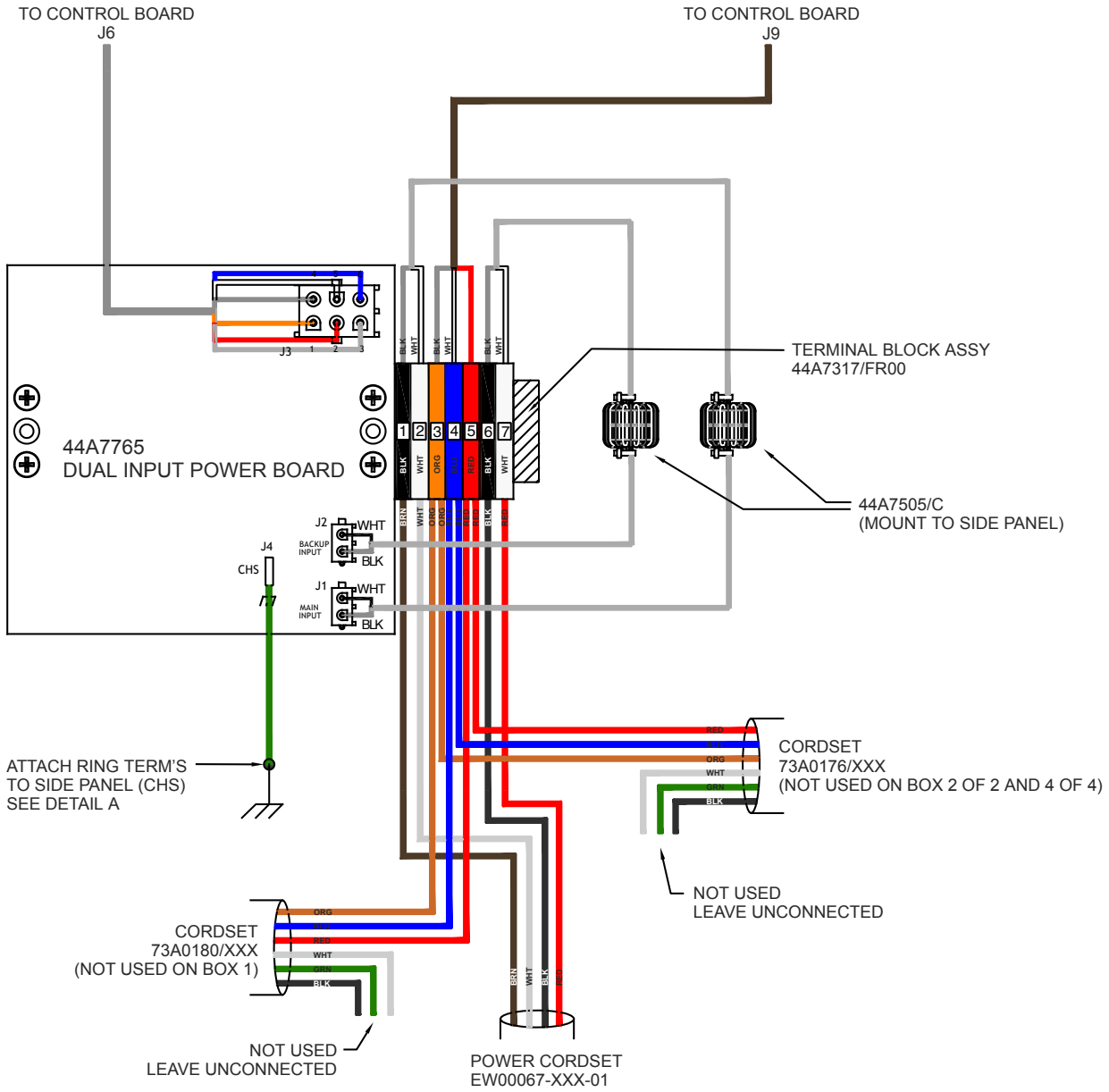


DETAIL A:
 CHASSIS GROUND RING TERM'S CONNECTION, TYP.
 (POWER CORD GROUND LEAD NOT SHOWN)

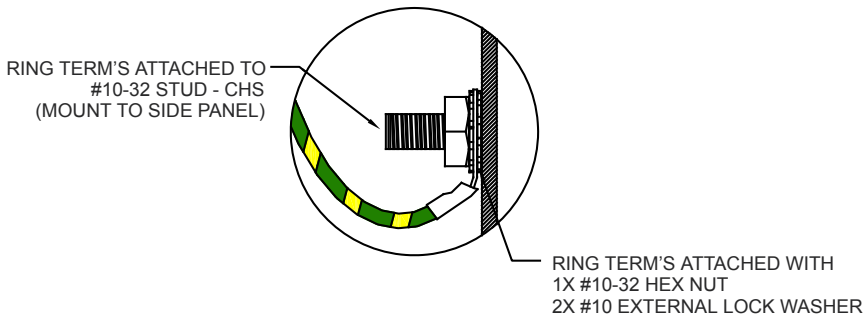


43A4165-XXXX REV.J

Figure 68: Input Power Wiring Diagram - Current Powered with Redundant Circuit (Primary and Secondary Light Unit)



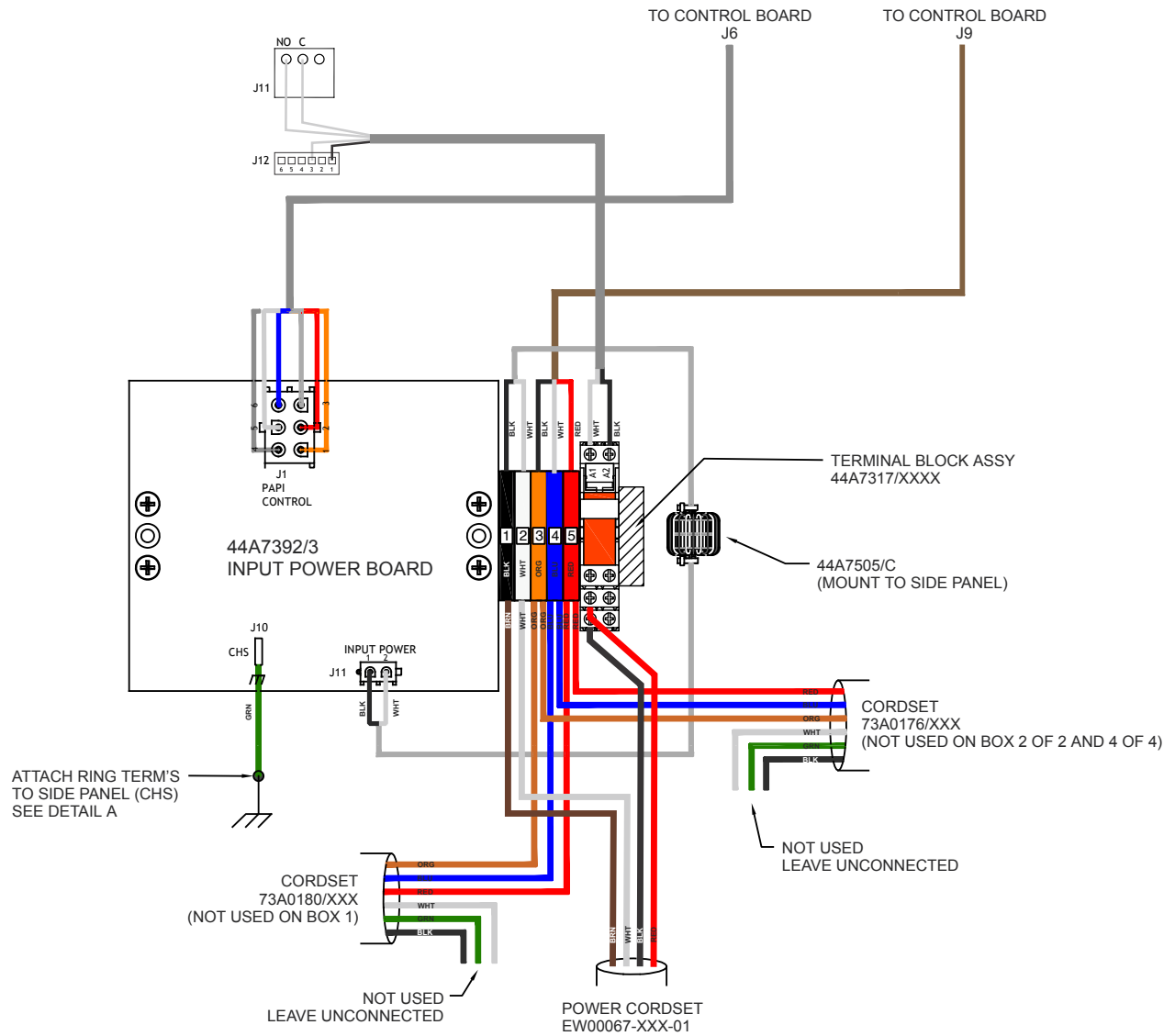
DETAIL A:
 CHASSIS GROUND RING TERM'S CONNECTION, TYP.
 (POWER CORD GROUND LEAD NOT SHOWN)



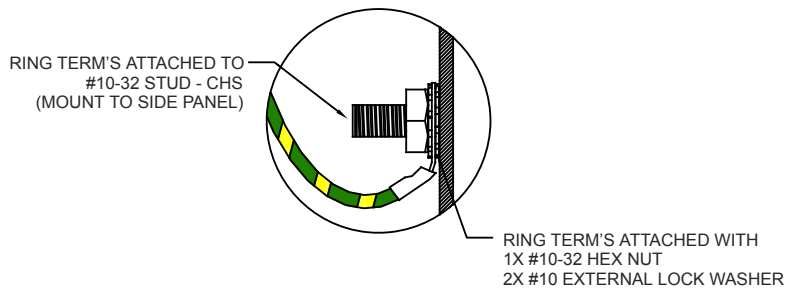
43A4165-XXXX REV.J

Figure 69: Input Power Wiring Diagram - Current Powered with Fail-Open Relay (Primary Only)

For Secondary Light units, see [Figure 67](#)



DETAIL A:
CHASSIS GROUND RING TERM'S CONNECTION, TYP.
(POWER CORD GROUND LEAD NOT SHOWN)



43A4165-XXXX REV.J

Figure 70: Control Board Wiring Diagram

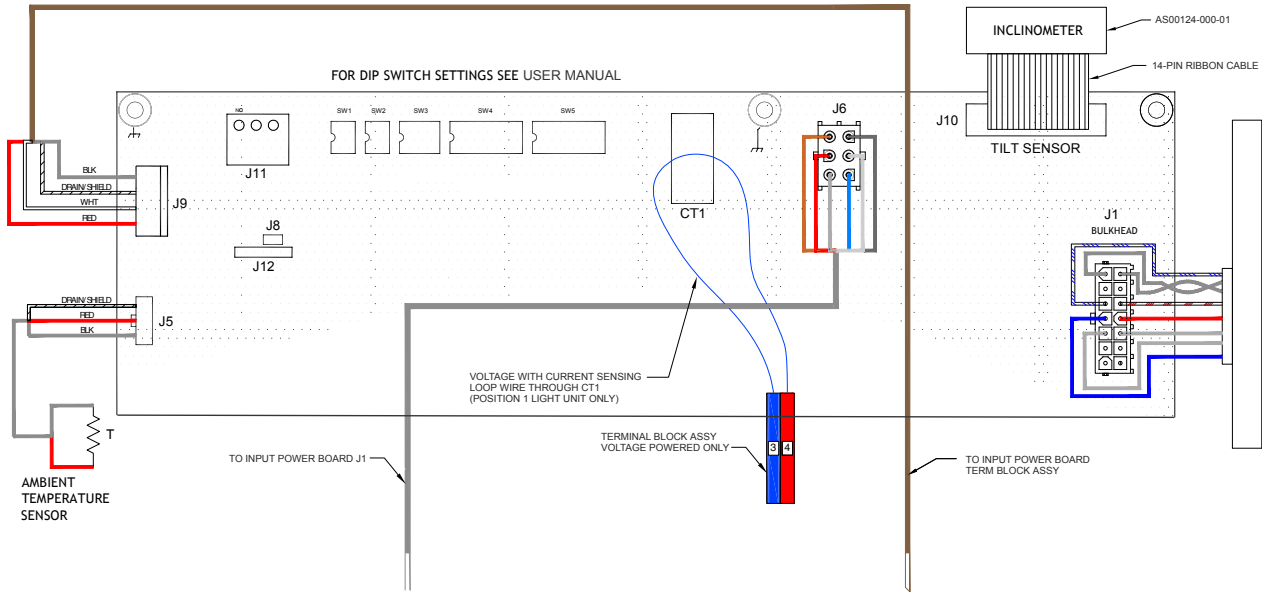
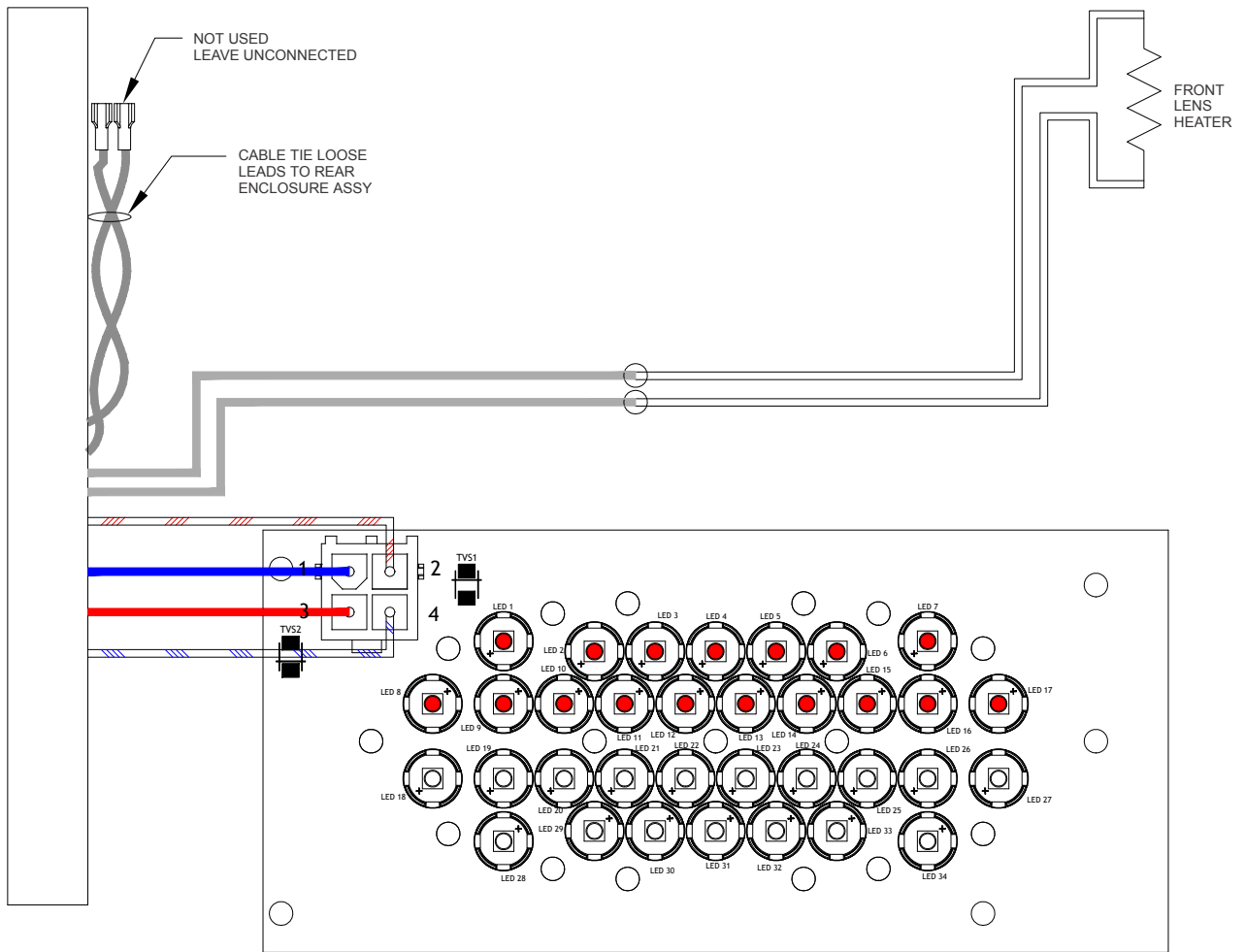


Figure 71: LED Assembly and Front Lens Heater Wiring Diagram



11.2 Field Cabling Diagrams

Figure 72: Field Cabling Diagram - Voltage Powered (2 Box)

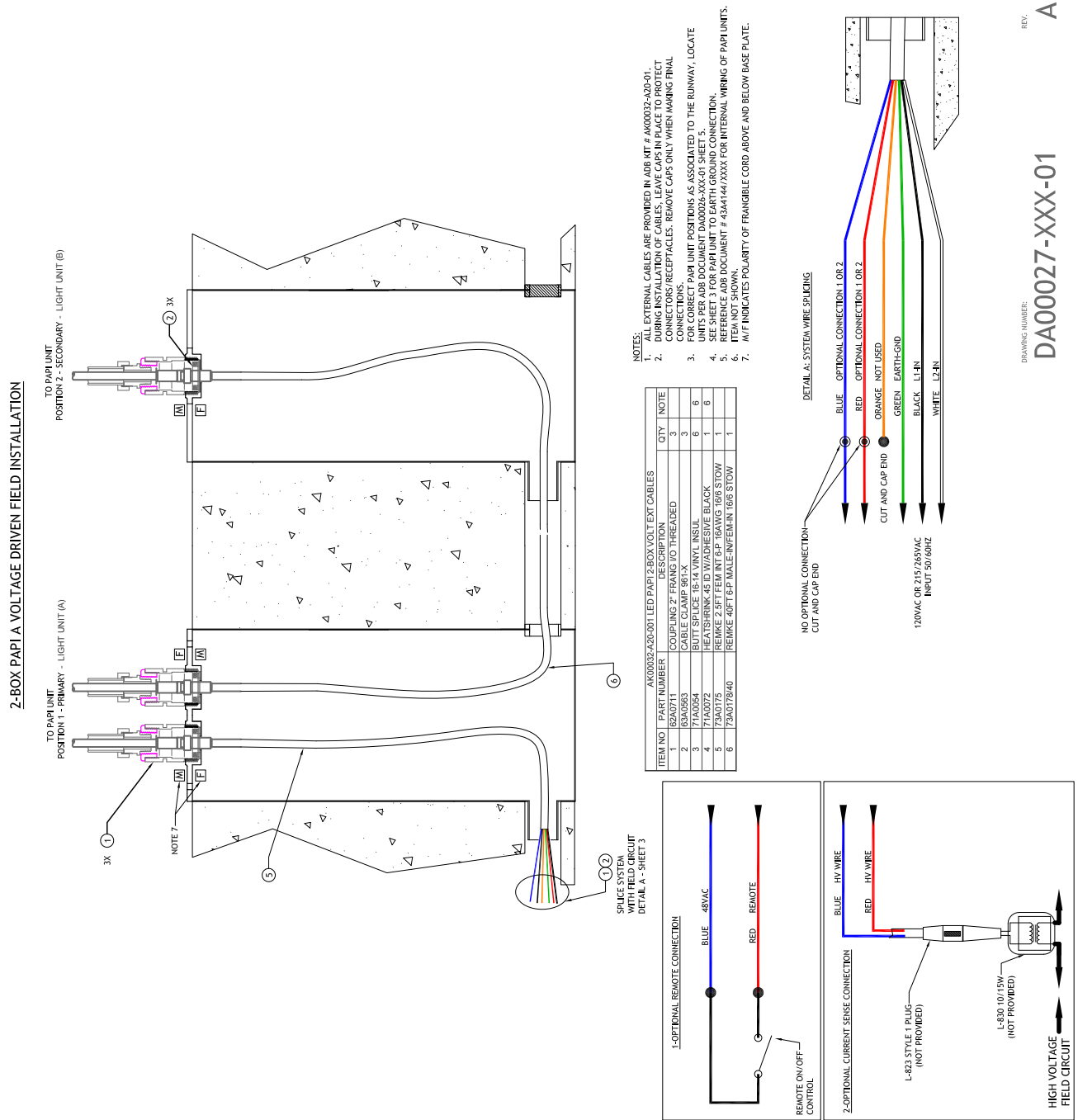
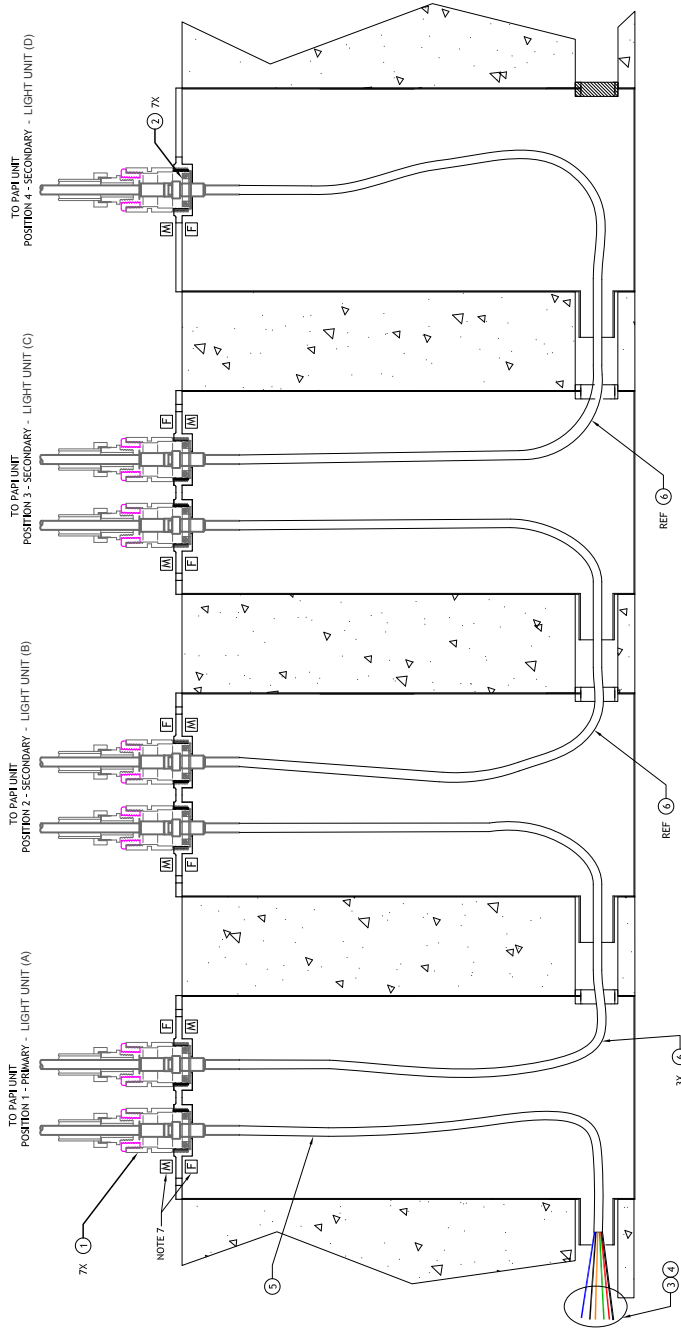


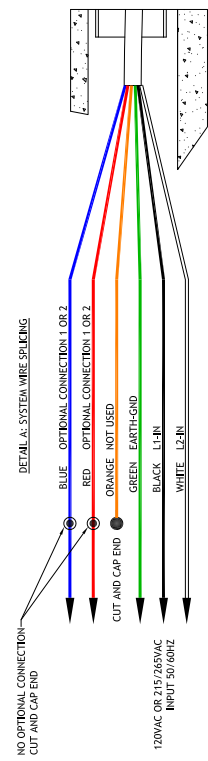
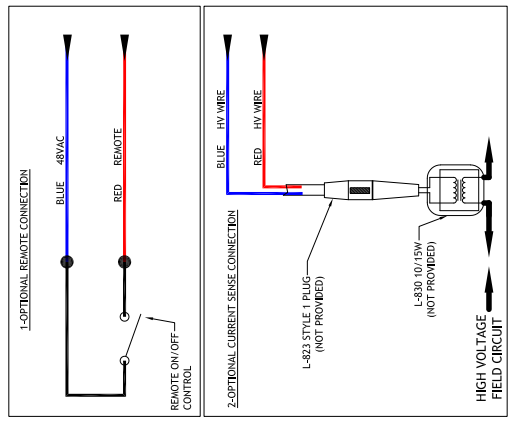
Figure 73: Field Cabling Diagram - Voltage Powered (4 Box)

4-BOX PAPI A VOLTAGE DRIVEN FIELD INSTALLATION



ITEM NO	PART NUMBER	DESCRIPTION	QTY	NOTE
1	62A0711	COUPLING 27 FRANG IO THREADED	7	
2	65A0953	CABLE CLAMP 98TX	7	
3	65A0953	HEATSHRINK ADH W/ADHESIVE BLACK	6	
4	71A0072	HEATSHRINK ADH W/ADHESIVE BLACK	6	
5	72A0715	REMKKE 2.5FT FEM INT 6-P TRAVG TBG STOW	1	
6	72A07840	REMKKE 4.0FT 6-P MALE-IN/FEM-IN TBG STOW	3	

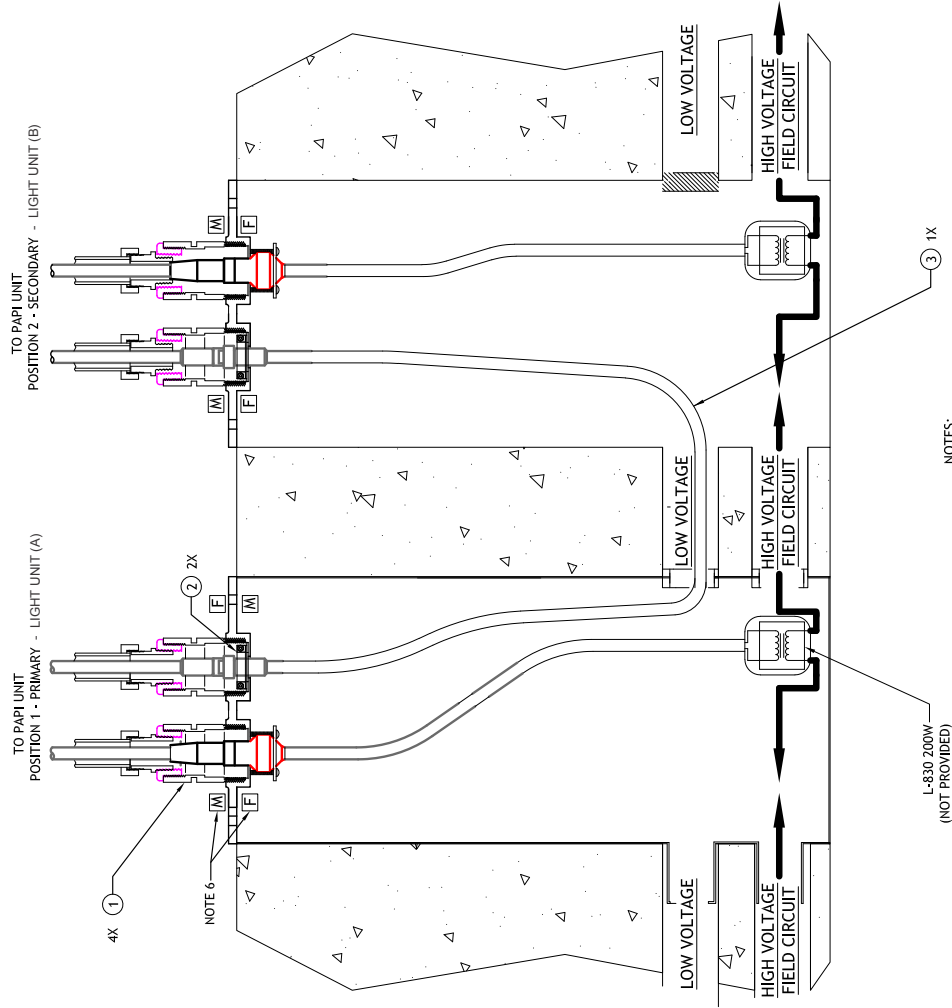
- NOTES:
1. ALL EXTERNAL CABLES ARE PROVIDED IN ADB KIT # AK00032-A40-01. DURING INSTALLATION OF CABLES, LEAVE CAPS IN PLACE TO PROTECT CONNECTORS/RECEPTACLES. REMOVE CAPS ONLY WHEN MAKING FINAL CONNECTIONS.
 2. FOR CORRECT PAPI UNIT POSITIONS AS ASSOCIATED TO THE RUNWAY, LOCATE UNITS PER ADB DOCUMENT DA00025-XXX-01 SHEET 5.
 3. PER ADB DOCUMENT DA00025-XXX-01 SHEET 5.
 4. SEE SHEET 3 FOR PAPI UNIT TO EARTH GROUND CONNECTION.
 5. REFERENCE ADB DOCUMENT # 43A144/XXXX FOR INTERNAL WIRING OF PAPI UNITS. ITEM NOT SHOWN.
 6. I/F INDICATES POLARITY OF FRANGIBLE CORD ABOVE AND BELOW BASE PLATE.
 7. I/F



REV. A
DRAWING NUMBER: DA00027-XXX-01

Figure 74: Field Cabling Diagram - Current Powered (2 Box)

2-BOX PAPI B CURRENT DRIVEN FIELD INSTALLATION (NON-REDUNDANT)



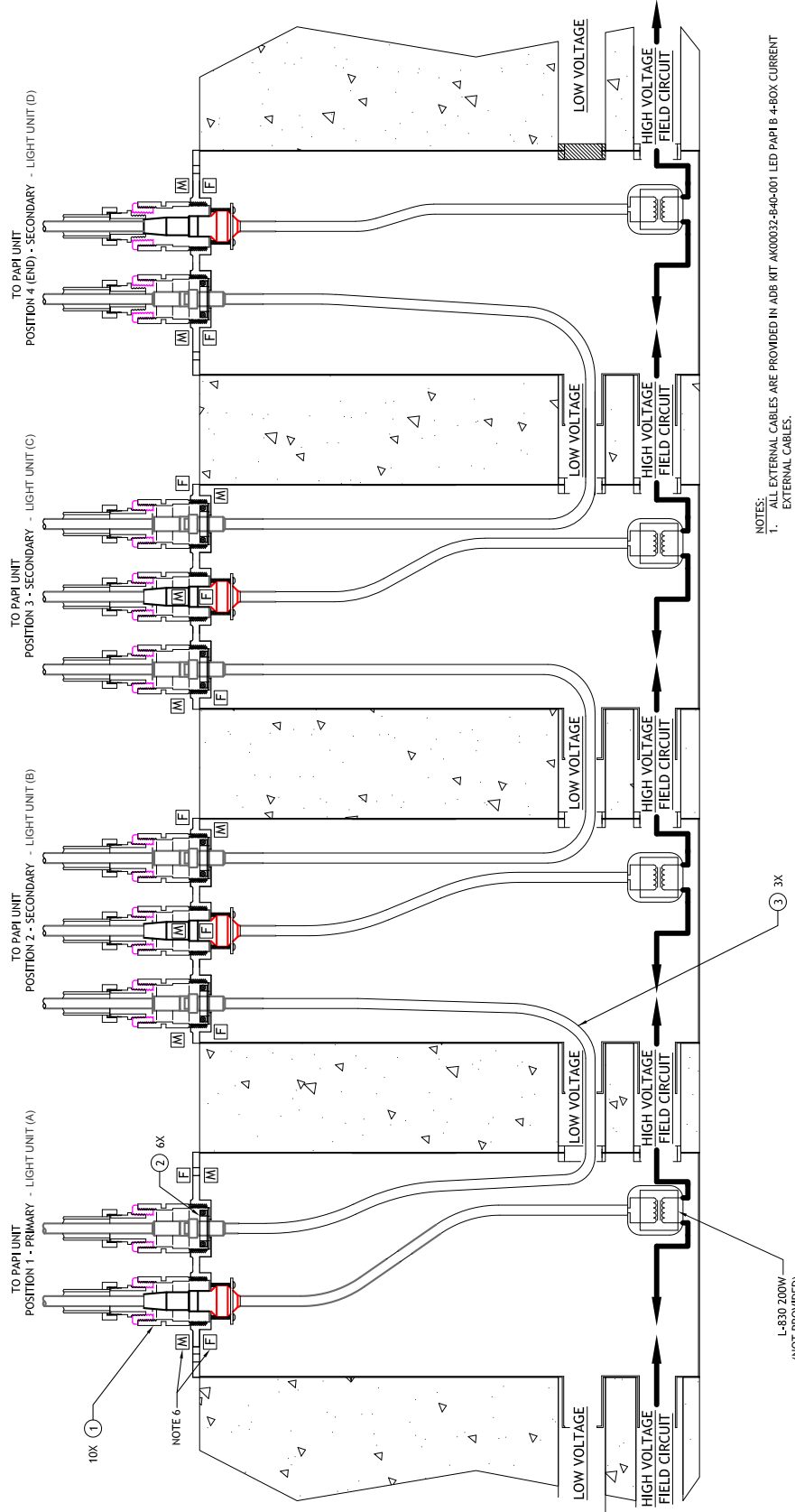
- NOTES:
1. ALL EXTERNAL CABLES ARE PROVIDED IN ADB KIT AK00032-B20-001 LED PAPI 2-BOX CURRENT EXTERNAL CABLES.
 2. DURING INSTALLATION OF CABLE SYSTEM, LEAVE CAPS IN PLACE TO PROTECT CONNECTORS/RECEPTACLES. REMOVE CAPS ONLY WHEN MAKING FINAL CONNECTIONS.
 3. FOR CORRECT PAPI UNIT POSITIONS AS ASSOCIATED TO THE RUNWAY, LOCATE UNITS PER ADB DOCUMENT DA00026-XXX-01 SHEET 5.
 4. SEE SHEET 4 FOR PAPI UNIT TO EARTH GROUND CONNECTION.
 5. REFERENCE ADB DOCUMENT # 43A4165/XXXX FOR INTERNAL WIRING OF PAPI UNITS.
 6. M/F INDICATES POLARITY OF FRANGIBLE CORD ABOVE AND BELOW BASE PLATE.

ITEM NO	PART NUMBER	DESCRIPTION	QTY
1	62A0711	COUPLING 2" FRANG I/O THREADED	4
2	63AG563	CABLE CLAMP 961-X	2
3	73A0178/40	REMK 40FT 6-P MALE-INFEM-IN 18/6 STOW	1

AWING NUMBER: DP
REV. B
DA00028-XXX-01

Figure 75: Field Cabling Diagram - Current Powered (4 Box)

4-BOX PAPI B CURRENT DRIVEN FIELD INSTALLATION (NON-REDUNDANT)

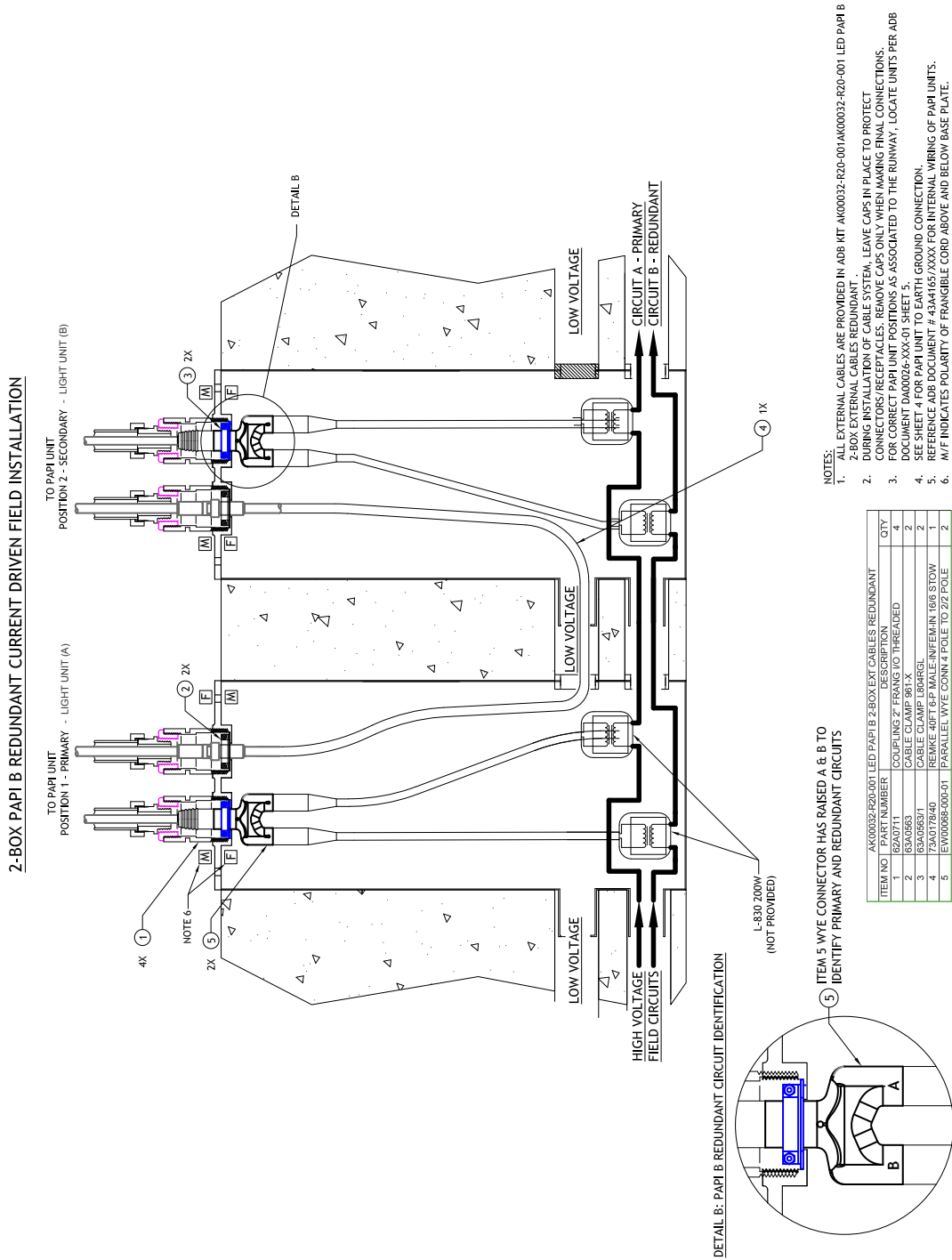


- NOTES:
1. ALL EXTERNAL CABLES ARE PROVIDED IN ADB KIT AK00032-B40-001 LED PAPI B 4-BOX CURRENT EXTERNAL CABLES.
 2. DURING INSTALLATION OF CABLE SYSTEM, LEAVE CAPS IN PLACE TO PROTECT CONNECTORS/RECEPTACLES. REMOVE CAPS ONLY WHEN MAKING FINAL CONNECTIONS.
 3. FOR CORRECT PAPI UNIT POSITIONS AS ASSOCIATED TO THE RUNWAY, LOCATE UNITS PER ADB DOCUMENT DA00026-XXX-01 SHEET 5.
 4. SEE SHEET 4 FOR PAPI UNIT TO EARTH GROUND CONNECTION.
 5. REFERENCE ADB DOCUMENT # 43441637XXX FOR INTERNAL WIRING OF PAPI UNITS.
 6. M/F INDICATES POLARITY OF FRANGIBLE CORD ABOVE AND BELOW BASE PLATE.

ITEM NO	PART NUMBER	DESCRIPTION	QTY
1	AK00032-B40-001	LED PAPI 4-BOX CURRENT EXT CABLES	10
2	62A0711	COUPLING 2" FRANG I/O THREADED	6
3	83A0563	CABLE CLAMP 861-X	3
	73A07840	REMIKE 40FT 6-P MALE-IN/FEM-IN 18/6 STOW	3

AWIRING NUMBER: DP DA00028-XXX-01 REV. B

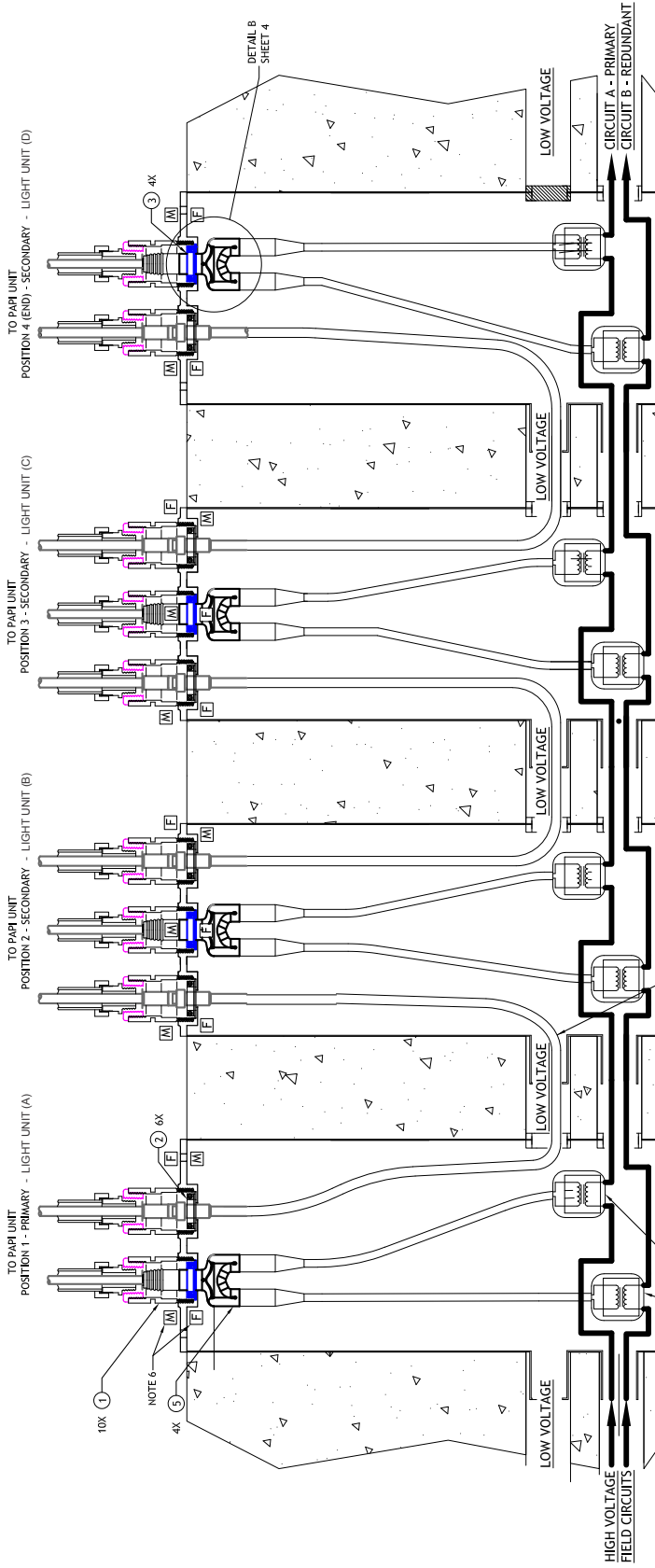
Figure 76: Field Cabling Diagram - Current Powered with Redundant Circuit (2 Box)



AWING NUMBER: DP
 REV: B
 DA00028-XXX-01

Figure 77: Field Cabling Diagram - Current Powered with Redundant Circuit (4 Box)

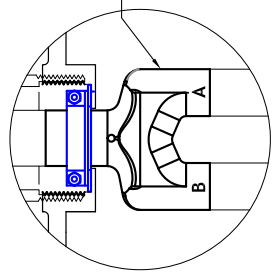
4-BOX PAPI B REDUNDANT CURRENT DRIVEN FIELD INSTALLATION



ITEM NO	PART NUMBER	DESCRIPTION	QTY
1	AK00032-R40-001	LED PAPI B 4-BOX EXT CABLES REDUNDANT	10
2	62A0711	COUPLING 2" FRANG IO THREADED	10
3	63A0563	CABLE CLAMP 961-X	6
4	63A07841	REMOVAL CAP FEM IN 1/8" STOW	3
5	EW000684-000-01	PARALLEL WYE CONN 4 POLE TO 2/2 POLE	4

- NOTES:
1. ALL EXTERNAL CABLES ARE PROVIDED IN ADB KIT AK00032-R40-001 LED PAPI B 4-BOX EXTERNAL CABLES REDUNDANT.
 2. DURING INSTALLATION OF CABLE SYSTEM, LEAVE CAPS IN PLACE TO PROTECT CONNECTORS/RECEPTACLES. REMOVE CAPS ONLY WHEN MAKING FINAL CONNECTIONS.
 3. FOR CORRECT PAPI UNIT POSITIONS AS ASSOCIATED TO THE RUNWAY, LOCATE UNITS PER ADB DOCUMENT DA00026-XXX-01 SHEET 5.
 4. SEE SHEET 4 FOR PAPI UNIT TO EARTH GROUND CONNECTION.
 5. REFERENCE ADB DOCUMENT # 43A4165/XXXX FOR INTERNAL WIRING OF PAPI UNITS.
 6. M/F INDICATES POLARITY OF FRANGIBLE CORD ABOVE AND BELOW BASE PLATE.

DETAIL B: PAPI B REDUNDANT CIRCUIT IDENTIFICATION



ITEM 5 WYE CONNECTOR HAS RAISED A & B TO IDENTIFY PRIMARY AND REDUNDANT CIRCUITS

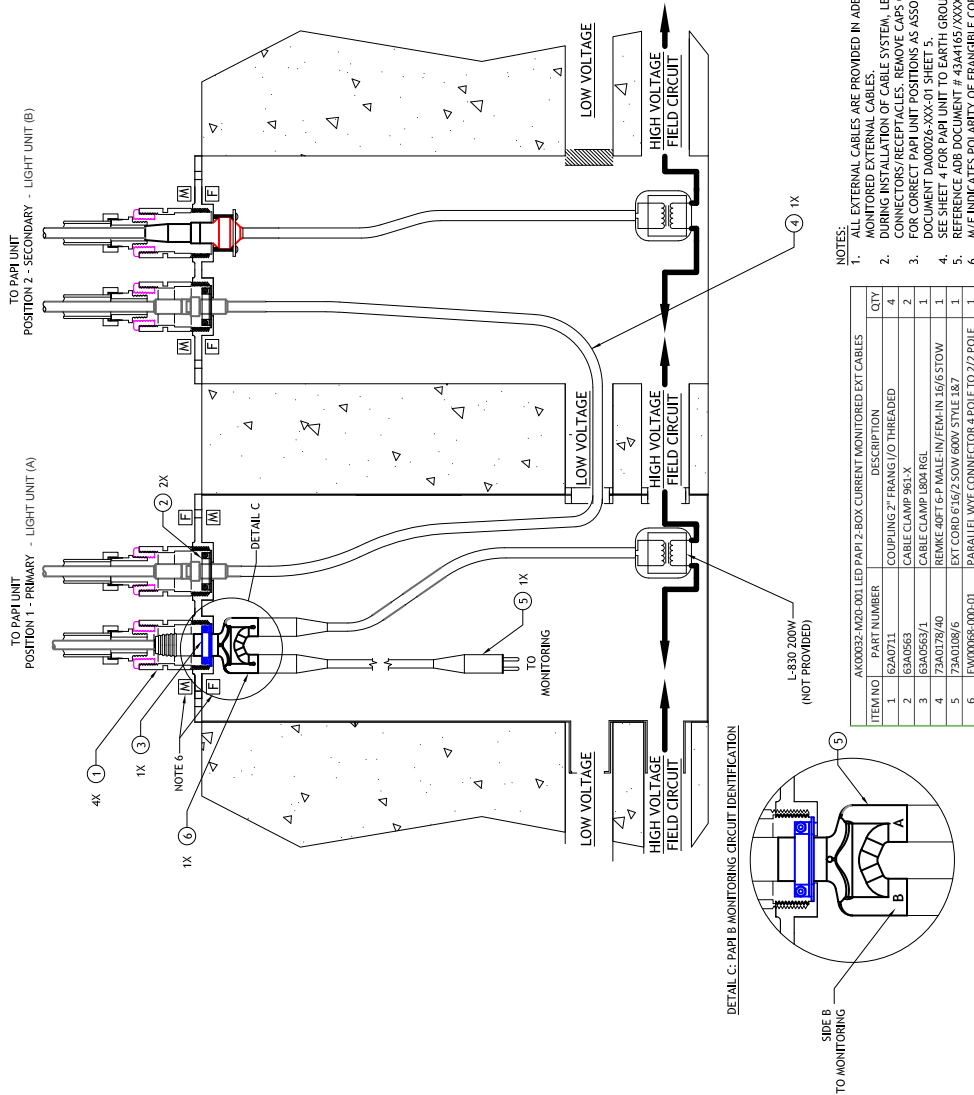
L-830 200W (NOT PROVIDED)

JAWING NUMBER: DP REV. B

DA00028-XXX-01

Figure 78: Field Cabling Diagram - Current Powered with Fail-Open Monitoring (2 Box)

2-BOX PAPI B CURRENT DRIVEN FIELD INSTALLATION (MONITORED, NON-REDUNDANT)



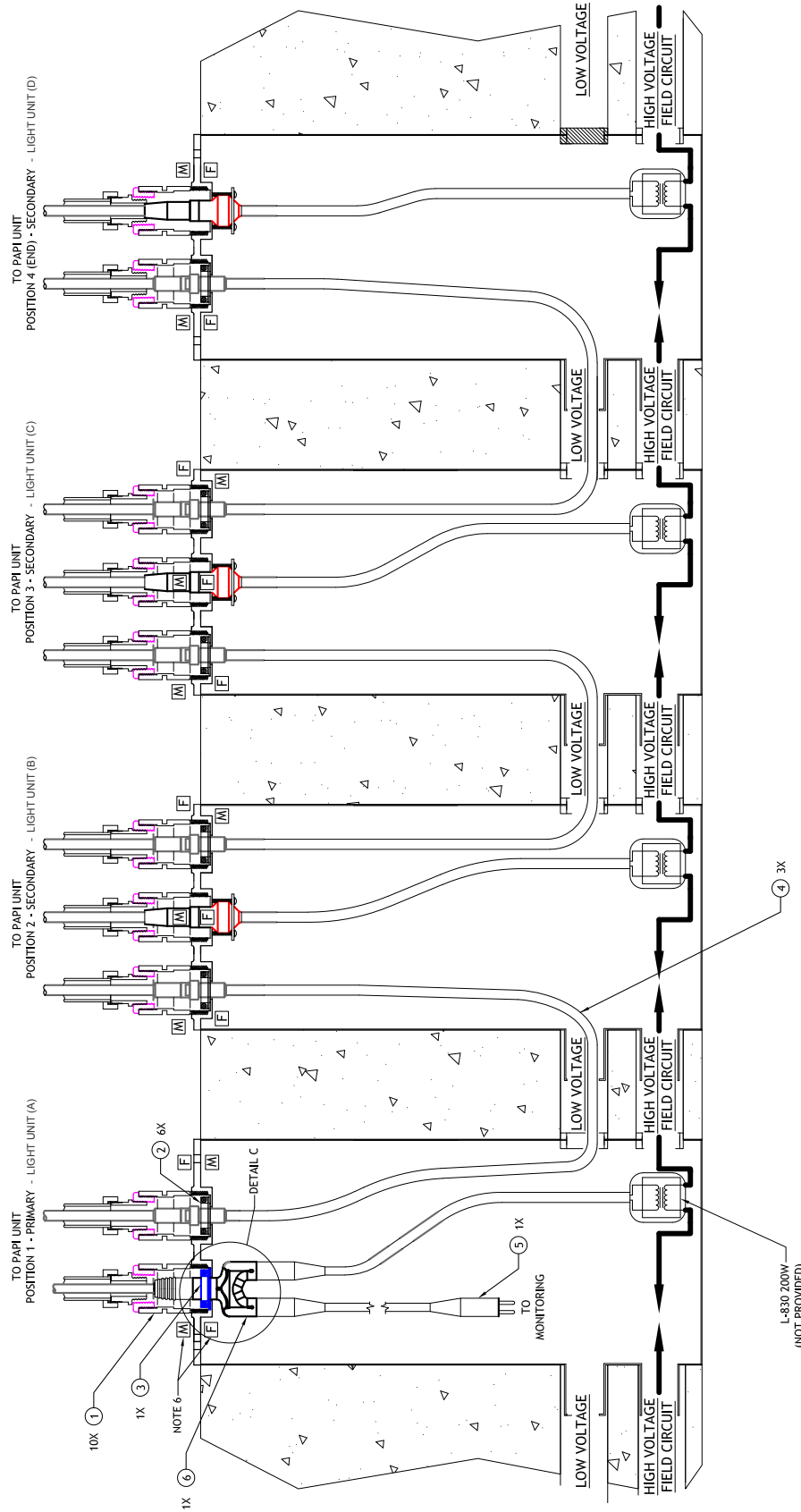
ITEM NO	PART NUMBER	DESCRIPTION	QTY
1	62A0711	COUPLING 2" FRANG I/O THREADED	4
2	63A0563	CABLE CLAMP 961-X	2
3	63A0563/1	CABLE CLAMP 1804-RGL	1
4	73A0178/40	RENKLE 40BT 6-P MALE-IN/FEEM-IN 16/6 STOW	1
5	73A0108/6	EXT CORD 6' 16/2 SOW 600V STYLE 187	1
6	EW00068-000-01	PARALLEL WYE CONNECTOR-4 POLE TO 2/2 POLE	1

- NOTES:
1. ALL EXTERNAL CABLES ARE PROVIDED IN ADB KIT AK00032-4020-001 LED PAPI 2-BOX CURRENT DRIVEN EXTERNAL CABLES.
 2. DURING INSTALLATION OF CABLE SYSTEM LEAVE CAPS IN PLACE TO PROTECT CONNECTORS/RECEPTACLES. REMOVE CAPS ONLY WHEN MAKING FINAL CONNECTIONS.
 3. FOR CORRECT PAPI UNIT POSITIONS AS ASSOCIATED TO THE RUNWAY, LOCATE UNITS PER ADB DOCUMENT DA00026-XXX-01 SHEET 5.
 4. SEE SHEET 4 FOR PAPI UNIT TO EARTH GROUND CONNECTION.
 5. REFERENCE ADB DOCUMENT # 43M165/XXXX FOR INTERNAL WIRING OF PAPI UNITS.
 6. M/F INDICATES POLARITY OF FRANGIBLE CORD ABOVE AND BELOW BASE PLATE.

REV. B
DRAWING NUMBER: DP
DA00028-XXX-01

Figure 79: Field Cabling Diagram - Current Powered with Fail-Open Monitoring (4 Box)

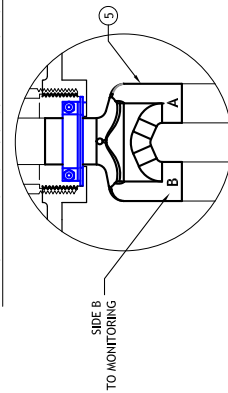
4-BOX PAPI B CURRENT DRIVEN FIELD INSTALLATION (MONITORED, NON-REDUNDANT)



- NOTES:
1. ALL EXTERNAL CABLES ARE PROVIDED IN ADB KIT AK00032-1M4G-001 LED PAPI B 4-BOX CURRENT MONITORED EXTERNAL CABLES.
 2. UPON INSTALLATION OF CABLE SYSTEM, LEAVE CAPS IN PLACE TO PROTECT CABLES FROM MOISTURE. REMOVE CAPS ONLY WHEN MAKING FINAL CONNECTIONS.
 3. FOR CORRECT PAPI UNIT POSITIONING AS ASSOCIATED TO THE RUNWAY, LOCATE UNITS PER ADB DOCUMENT DA00026-XXX-01 SHEET 5.
 4. SEE SHEET 4 FOR PAPI UNIT TO EARTH GROUND CONNECTION.
 5. REFERENCE ADB DOCUMENT # 43A4165/XXX FOR INTERNAL WIRING OF PAPI UNITS.
 6. M/F INDICATES POLARITY OF FRANGIBLE CORD ABOVE AND BELOW BASE PLATE.

ITEM NO	PART NUMBER	DESCRIPTION	QTY
1	62A0711	COUPLING 2" FRANG/I/O THREADED	10
2	63A0563	CABLE CLAMP 951-X	6
3	63A0563/1	CABLE CLAMP 1804 RGL	1
4	73A0178/40	REMKE 40FT 6-F MALE-1N/FEM-1N 16/6 STOW	3
5	73A0108/6	EXT CORD 6'16/2 50W/600V STYLE 1&7	1
6	E1W0068-000-01	PARALLEL WYE CONNECTOR 4 POLE TO 2/2 POLE	1

DETAIL C: PAPI B MONITORING CIRCUIT IDENTIFICATION



AWING NUMBER: DP DA00028-XXX-01 REV. B

12.0 RELIANCE PAPI Parts

Ordering Code

R P

Power

- A= Style A (Voltage) 240 VAC or 120 VAC, 50/60 Hz¹
- B= Style B (Current) 2.8-6.6 A, 50/60 Hz
- R= Style B (Current) 2.8-6.6 A, 50/60 Hz with Redundant Circuit²

Application

- 2 = L-881(L)/APAPI (2 Light Units)
- 4 = L-880(L)/PAPI (4 Light Units)

Primary Standard

- 2 = FAA
- 3 = ICAO³

Market Specific

- 1 = BAP⁴

Housing

- A = Aluminum (Standard)
- S = 316 Stainless Steel⁵

Power Cord

- 1 = 8 ft (2.4 m) (standard)
- 2 = 18 ft (5.5 m)

Operation/Control Mode

- 1 = Style A (Voltage), with Current Sensing Night Control Mode
- 2 = Style A (Voltage), with Current Sensing Day/Night Control Mode
- 3 = Style A (Voltage), with External On/Off Control Mode
- 4 = Style A (Voltage) with no Control Mode or Style B (Current) with CCR Control

Monitoring

- S = Non-Monitored
- M = Monitored Fail-Open⁶

Fixed Digit = 0

Baffles

- N = No Baffles
- B = Baffles on Both Sides

Touchpad Cover

- 0 = No Cover
- 1 = With Cover

Contractor Kit Materials

- 0 = Not Included
- 1 = Included

Fixed Digit = 0

Version

- 1 = Version 1

Ordering Code Notes

1. Factory preset for 240 VAC $\pm 10\%$, easily field modified for 120 VAC $\pm 10\%$.
2. Requires a complete redundant airfield circuit for redundant power operation.
3. Complies with requirements of ICAO, TP312, EASA, and MOS.
4. Meets Buy American Preference - For FAA Airport Improvement Projects (AIP).
5. Not ETL certified configuration.
6. Only available with Style B non-redundant systems.

Power Cord

The power cord is available in 8 ft (2.4 m) or 18 ft (5.5 m) length. The 8 ft (2.4 m) length is adequate for most installations. For installations that require a longer power cord, the 18 ft (5.5 m) length can be supplied and cut-to-length on-site during installation.

When the longer power cord and Contractor Kit Items are specified together, a longer length conduit is provided to accommodate the longer length power cord.

Monitored Fail-Open

The Monitored Fail-Open ordering option is for ILCMS installations and required an external remote for fail-open monitoring. Requires use of a remote monitor and a separate 65 W auxiliary isolation transformer for the primary light unit only or for each light unit as determined by the monitoring system used. Compatible with ADB Safegate and other remote monitoring systems. This ordering option does not provide CCR monitoring functionality.

Baffles

Baffles modify the horizontal light beam from the PAPI light unit for obstacle avoidance in the approach area. ADB Safegate LED PAPI baffles provide an adjustment capability to reduce the light beam from a full-width beam down to ± 4.0 degree of visible light. Note: FAA Engineering Brief No.95 cautions that a light beam of less than ± 3.0 degrees of visible light may not satisfy flight inspection criteria.

PAPI systems specified with baffles will include factory installed left and right side baffles on all light units. Each side can be adjusted independently. The baffles cannot be installed in the field, they are factory installed only.

Touchpad Cover

The optional touchpad cover provides added protection for the LED display.

Contractor Kit Materials

Items specified as "Contractor Supplied" are not included with the light unit. These items are typically provided by the contractor. However, as a convenience these items are available from ADB Safegate as an option within the ordering code or they can be provided as an optional "Contractor Kit". See the user manual for more information on contractor kit items.

The following items are considered contractor supplied:

- EMT for legs
- Flexible conduit
- Conduit fittings
- Reducer bushings

Contractor Kit

AK00031 - - 01

Power

A = Style A (Voltage) 240 VAC or 120 VAC, 50/60 Hz

B = Style B (Current) 2.8-6.6 A 50/60 Hz

R = Style B (Current) 2.8-6.6 A 50/60 Hz with Redundant Circuit

Application

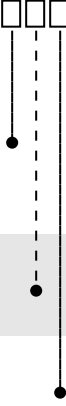
2 = L-881(L) / APAPI (2 Light Units)

4 = L-880(L) / PAPI (4 Light Units)

Power Cord

1 = 8 ft (2.4 m) (standard)

2 = 18 ft (5.5 m)



Optional Touchpad Cover

44A7564

12.1 Spare Parts

This section provides schematic drawings, along with part numbers. Refer to the [Wiring Diagrams](#).

Table 17: Spare Parts

Description	Part No.
Mounting Flange (For Leg Assembly)	62B0107/2
Frangible Coupling (For Leg Assembly)	44B0180
EMT Compression Coupling (For Leg Assembly)	77A0009
PAPI Leg Adjustment Assembly 18-8 SS	44C2362/SS
Electrical Frangible Coupling	62A0711
Complete PAPI Light Unit Assembly	Contact ADB Safegate
Control Board Replacement Kit	94A0666/XXX ¹
Terminal Block Assembly	44A7317/XXXX ²
LED Light Engine Replacement Kit - FAA (See Table 20)	AK00030-200-01 ³
LED Light Engine Replacement Kit - ICAO (See Table 20)	AK00030-000-01 ³
Heated Glass Replacement Kit (for firmware version 1.47 or earlier)	94A0674/1 ³
Heated Glass Replacement Kit (for firmware version 1.50 or later)	AK00054-000-01 ³
Inclinometer Assembly	AS00124-000-01
LED PAPI Rear Seal	63A1169
Humidity Indicating Plug	61A0503
Desiccant Pack Replacement (includes QTY (2) desiccant packs, mounting hardware and seal)	61A0505S
Top Cover Silicone Gasket (1 ft)	RM0212
40 ft 6-Pin Inter-Box Cable	73A0178/40
6-Pin Female Power Cord (8 ft) – Typically used with FAA Installations	73A0176
6-Pin Female Power Cord (18 ft) – Longer length is typically used with Transport Canada TP312 and ICAO Installations	73A0176/18
6-Pin Male Power Cord (8 ft) – Typically used with FAA Installations	73A0180
6-Pin Male Power Cord (18 ft) – Longer length is typically used with Transport Canada TP312 and ICAO Installations	73A0180/18
Cable Clamp (961-X)	63A0563
Ground Lug	72A0134
Control Board Fuse (F1, F2) 800mA 125VAC Radial Box Fast Blow	47A0243
Control Board Fuse (F5) 3.15A 250VAC Radial Can Fast Blow	47A0242
Top Cover – ICAO (Yellow)	44A7231/21
Top Cover – FAA (Orange)	44A7231/11

Notes

¹ See Control Board Replacement section.

² See Spare Part Drawings section.

Table 17: Spare Parts (Continued)

Description	Part No.
³ Kit includes the desiccant pack assemblies required for repair. Always replace the desiccant packs if the sealed optical tube is opened	

Table 18: Voltage Powered Style A Only

Description	Part No.
Photocell (24 VAC/VDC)	31A0022
Photocell Receptacle	44A7397
Input Power Board (Voltage Powered) (Primary)	44A7392/1
Input Power Board (Voltage Powered) (Secondary)	44A7392/2
Input Power Board Fuse (F1, F2) 3A 250VAC 3AB 3AG 1/4x1-1/4 Slow Blow	47A0233
Input Power Board Fuse (F3, F4) 500mA 250VAC 5x20mm Slow Blow	47A0234
Step Down Transformer with Lead Assembly	44A7396
6-Pin Female Power Cord, For Field Circuit Splice (2.5 ft)	73A0175

Table 19: Current Powered Style B Only

Description	Part No.
Input Power Board (Current Powered)	44A7392/3
16/2 Power Cord (8 ft) - Typically used with FAA Installations	73A0107/98
16/2 Power Cord (18 ft) - Longer length is typically used with Transport Canada TP312 and ICAO Installations	73A0107/216
14/4 Power Cord (8 ft) - Used with Redundant Circuits and Monitored Systems	EW00067-2.5-01
14/4 Power Cord (18 ft) - Used with Redundant Circuits and Monitored Systems	EW00067-5.5-01
Wye Connector - Used with Redundant Circuits and Monitored Systems	EW00068-000-01
Cable Clamp L804RGL - Used with Wye Connector	63A0563/1

Table 20: LED Light Engine Replacement Kit AK00030-XXX-01 Parts

Description	AK00030-000-01	AK00030-200-01
	Qty	Qty
LED Engine/Heat Sink Assembly	1 (ICAO)	1 (FAA)
LED Desiccant Mounting Slide	2	2
LED PAPI Desiccant Heat Shield	1	1
Humidity Indicating Plug	1	1
56 G Molecular Sieve Packet TYVEK 1056D	2	2
LED PAPI Rear Seal	1	1
1/4-20 X 7/8 Socket Head Cap Screw (SHCS) Stainless Steel (SS)	12	12
6-32 X 1/2 PAN HD PHIL	4	4
1/4 SPLIT LOCKWASHER	12	12
#6 INT LOCKWASHER	4	4
Wire Tie 0.13x8.5 inch Black UV Resistant	4	4

12.1.1 Spare Part Drawings

Figure 80: RELIANCE PAPI Exploded View - Parts

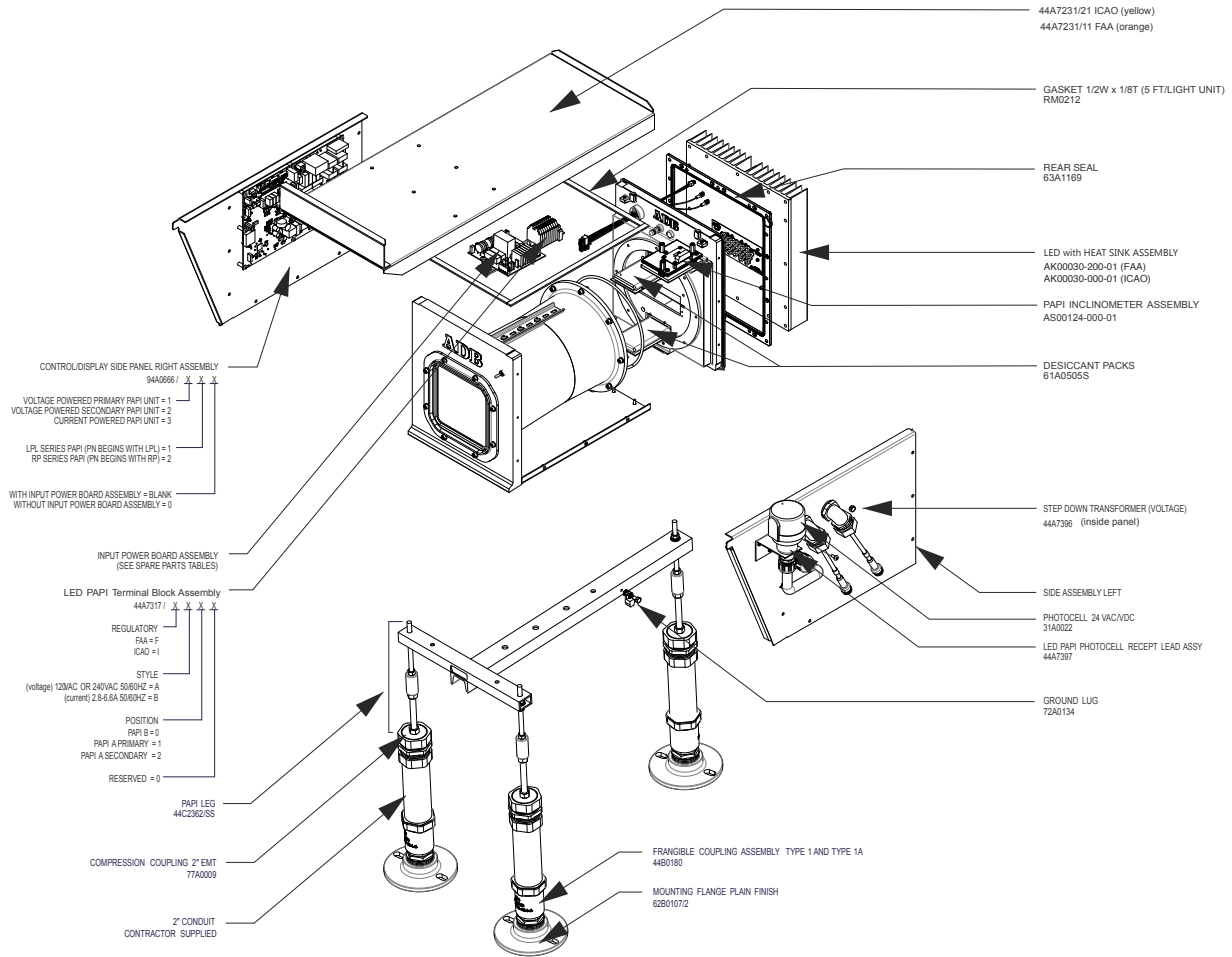


Figure 81: RELIANCE PAPI Exploded View - Hardware

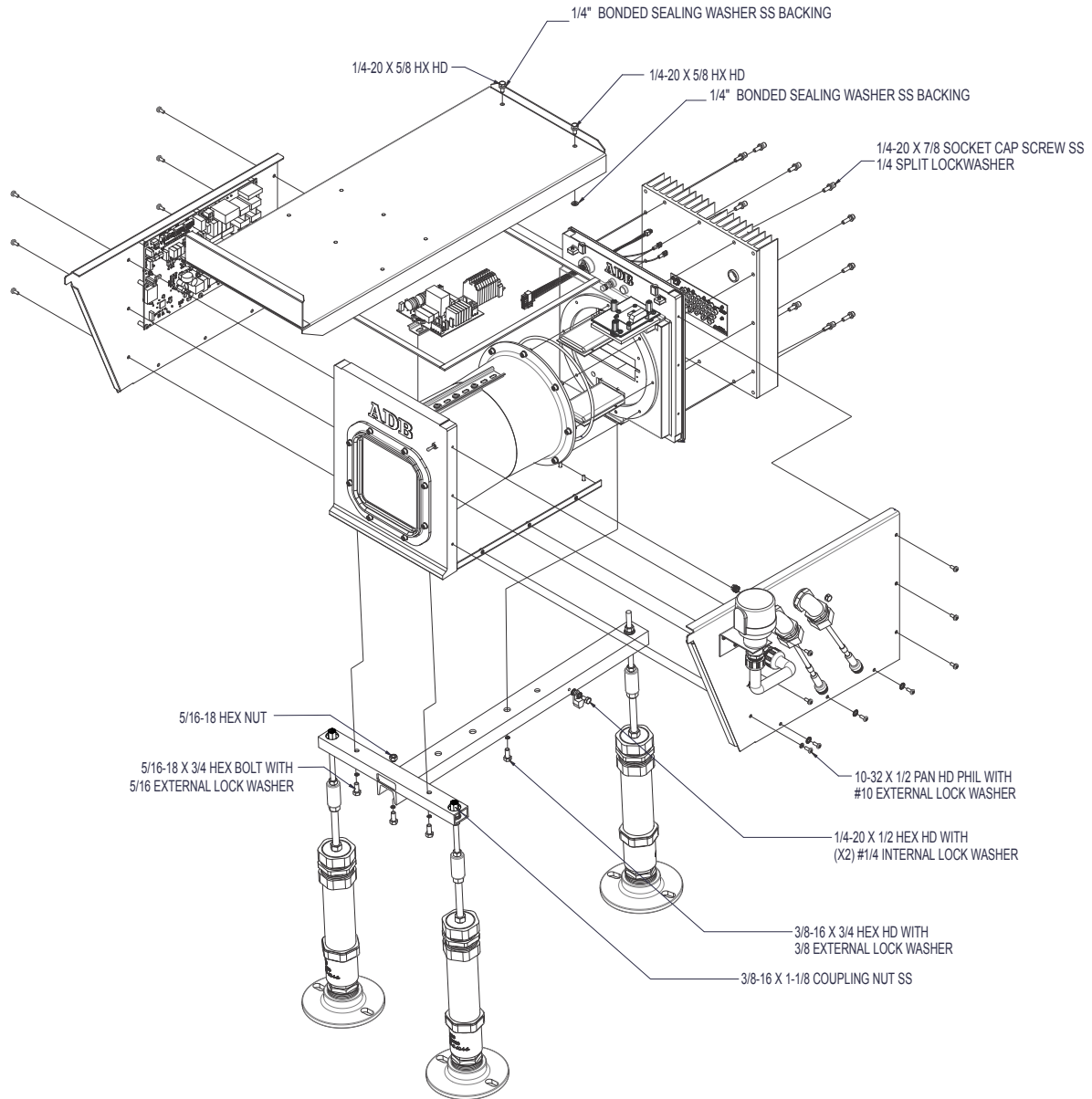


Figure 82: RELIANCE PAPI Side View Assembly

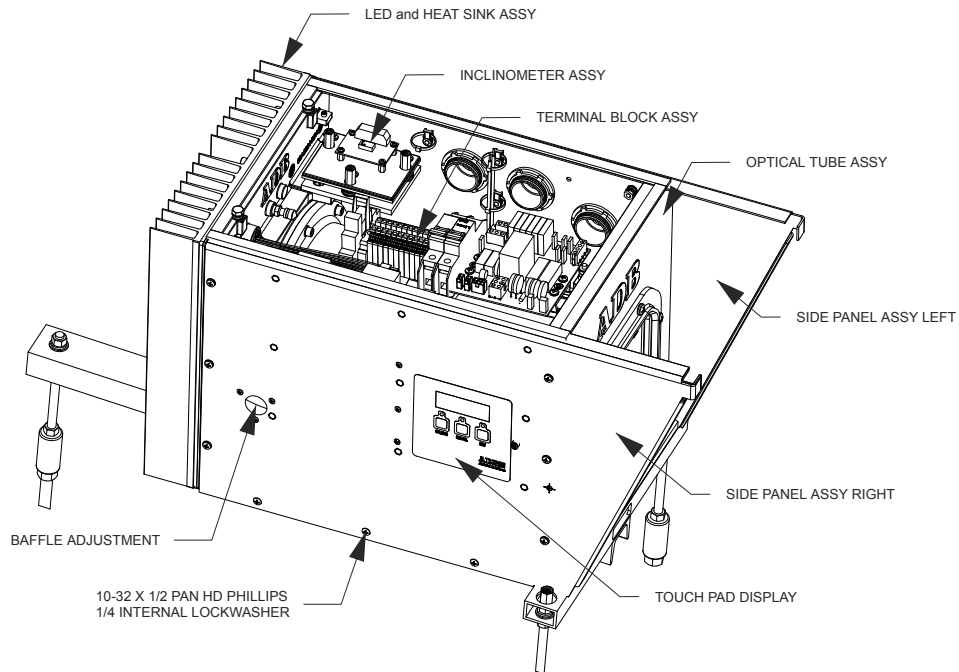
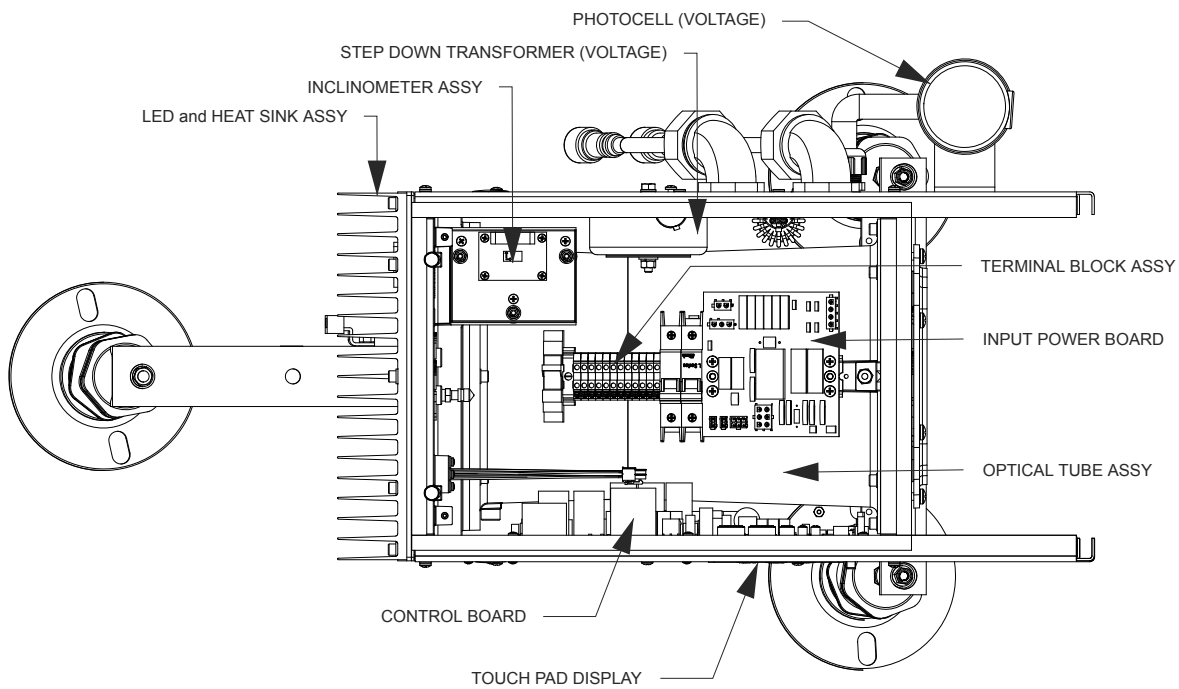


Figure 83: RELIANCE PAPI Assembly Top View



Appendix A: SUPPORT

Our experienced engineers are available for support and service at all times, 24 hour/7 days a week. They are part of a dynamic organization making sure the entire ADB SAFEGATE is committed to minimal disturbance for airport operations.

ADB SAFEGATE Support

Technical Support – Global

Customers in Europe, the Middle East, Africa or Asia Pacific are more than welcome to our portal for technical support. Trained in all areas of system issues, troubleshooting, quality control and technical assistance, our highly experienced Technical support specialists are available 24 hours a day, seven days a week to provide assistance over the phone. In the Americas, we also offer live technical support.

Live Technical Support – Americas

If at any time you have a question or concern about your product, contact ADB SAFEGATE's US-based technical support specialists, available 24 hours a day, seven days a week, to assist you via phone.

ADB SAFEGATE Americas Technical Service & Support (US & Canada) :+1-800-545-4157

ADB SAFEGATE Americas Technical Service & Support (Canada): +1-905-631-1597

ADB SAFEGATE Americas Technical Service & Support (International): +1-614-861-1304

We can also be reached via email during regular business hours:

Airfield and Gate: techservice.us@adbsafegate.com

Gate: gateservice.us@adbsafegate.com

We look forward to working with you!

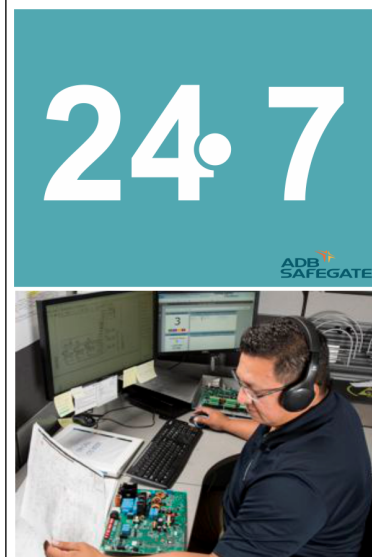
Before You Call

When you have an airfield lighting or system control system problem, prior to calling, please ensure the following:

- Review the product's manual and troubleshooting guide.
- Be located with the product ready to troubleshoot.
- Have all necessary information available: airport code/company name, customer id number, contact phone number/email address, product/part number.
- Have a *True RMS* meter available and any other necessary tools.

When calling about an issue with Safedock A-VDGS, we can serve you better if you collect the following information before you call:

- Relevant information regarding the issue you are calling about, such as gate number, flight number, aircraft type and time of the event.
- What, if any, actions have been taken to resolve the issue prior to the call.
- If available, provide a CCTV recording of the incident to aid in aligning the information from the Safedock log file.



Note

For more information, see www.adbsafegate.com, contact ADB SAFEGATE Support via email at support@adbsafegate.com or

Europe: +32 2 722 17 11

Americas: +1 614 861 1304. Press 3 for technical service or press 4 for sales support.

China: +86 (10) 8476 0106

Middle East and Africa: +971 4 452 7575

A.1 ADB SAFEGATE Website

The ADB SAFEGATE website, www.adbsafegate.com, offers information regarding our airport solutions, products, company, news, links, downloads, references, contacts and more.

A.2 Recycling

A.2.1 Local Authority Recycling

The disposal of ADB SAFEGATE products is to be made at an applicable collection point for the recycling of electrical and electronic equipment. The correct disposal of equipment prevents any potential negative consequences for the environment and human health, which could otherwise be caused by inappropriate waste handling. The recycling of materials helps to conserve natural resources. For more detailed information about recycling of products, contact your local authority city office.

A.2.2 ADB SAFEGATE Recycling

ADB SAFEGATE is fully committed to environmentally-conscious manufacturing with strict monitoring of our own processes as well as supplier components and sub-contractor operations. ADB SAFEGATE offers a recycling program for our products to all customers worldwide, whether or not the products were sold within the EU.

ADB SAFEGATE products and/or specific electrical and electronic component parts which are fully removed/separated from any customer equipment and returned will be accepted for our recycling program.

All items returned must be clearly labeled as follows:

- For *ROHS/WEEE* Recycling
- Sender contact information (Name, Business Address, Phone number).
- Main Unit Serial Number.

ADB SAFEGATE will continue to monitor and update according for any future requirements for *EU directives* as and when *EU member states* implement new *regulations* and or *amendments*. It is our aim to maintain our *compliance plan* and assist our customers.

Company Addresses

ADB SAFEGATE, Belgium	ADB SAFEGATE BV Leuvensesteenweg 585, B-1930 Zaventem Belgium
Contact: Tel.: +32 2 722 17 11 Fax: +32 2 722 17 64	Email: marketing@adbsafegate.com Internet: www.adbsafegate.com
ADB SAFEGATE, Americas	ADB SAFEGATE Americas LLC 700 science Blvd, Columbus OH 43230, USA
Contact: Tel.: +1 (614) 861 1304 Fax: +1 (614) 864 2069	Email: sales.us@adbsafegate.com Internet: www.adbsafegate.com
ADB SAFEGATE, Sweden	ADB SAFEGATE Sweden AB Djurhagegatan 19 SE-213 76 Malmö Sweden
Contact: Tel.: +46 (0)40 699 17 00 Fax: +46 (0)40 699 17 30	Email: marketing@adbsafegate.com Internet: www.adbsafegate.com
ADB SAFEGATE, China	ADB SAFEGATE Airfield Technologies Ltd. China Unit 603, D Block, CAMIC International Convention Center, No 3, Hua Jia Di East road, ChaoYang district, Beijing 100102 P.R. China
Contact: Tel.: +86 (10) 8476 0106 Fax: +86 (10) 8476 0090	Email: china@safegate.com Internet: www.adbsafegate.com
ADB SAFEGATE, Germany	ADB SAFEGATE Germany GmbH Konrad-Zuse-Ring 6, D-68163 Mannheim Germany
Contact: Tel.: +49 (621) 87 55 76-0 Fax: +49 (621) 87 55 76-55	Email: marketing@adbsafegate.com Internet: www.adbsafegate.com



Powering Your Airport Performance from Approach to Departure

adbsafegate.com

Copyright © ADB SAFEGATE, all rights reserved

